

Comparing genomes to computer operating systems in terms of the topology and evolution of their regulatory control networks

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The genome has often been called the operating system (OS) for a living organism. A computer OS is described by a regulatory control network termed the call graph, which is analogous to the transcriptional regulatory network in a cell. To apply our firsthand knowledge of the architecture of software systems to understand cellular design principles, we present a comparison between the transcriptional regulatory network of a well-studied bacterium (*Escherichia coli*) and the call graph of a canonical OS (Linux) in terms of topology and evolution. We show that both networks have a fundamentally hierarchical layout, but there is a key difference: The transcriptional regulatory network possesses a few global regulators at the top and many targets at the bottom; conversely, the call graph has many regulators controlling a small set of generic functions. This top-heavy organization leads to highly overlapping functional modules in the call graph, in contrast to the relatively independent modules in the regulatory network. We further develop a way to measure evolutionary rates comparably between the two networks and explain this difference in terms of network evolution. The process of biological evolution via random mutation and subsequent selection tightly constrains the evolution of regulatory network hubs. The call graph, however, exhibits rapid evolution of its highly connected generic components, made possible by designers' continual fine-tuning. These findings stem from the design principles of the two systems: robustness for biological systems and cost effectiveness (reuse) for software systems.

systems biology | adaptive complex systems

Complex systems are characterized by interactions among huge numbers of heterogeneous constituents. In particular, many complex systems are adaptive, meaning the interconnections are shaped progressively by a changing environment. The driving forces of adaptation are common design principles such as the reduction of cost and the enhancement of system robustness (1). Optimal solutions are determined by trade-offs between conflicting principles and therefore vary from system to system. Over the past decade, the study of networks has emerged as an interdisciplinary research field aiming to discover the underlying principles of complex systems and to develop tools or algorithms for analyzing them. By capturing the interconnections between individual components, networks not only serve as backbones to study the emergent properties of complex systems, but they also provide an abstract framework that facilitates the cross-disciplinary comparison of different adaptive complex systems, ranging from biological systems to technological ones (2). Cross-disciplinary comparison between biological systems and commonplace systems such as organization hierarchies (3, 4) and engineering devices should be of particular interest to systems biologists. Despite tremendous advancement in high-throughput experiments and computational algorithms, the study of biological systems in general still suffers from limitations in accuracy and completeness of data. Insights gained from systems in which we have direct access and thorough understanding can leverage our knowledge to biological ones.

Like biological systems, software systems such as a computer operating system (OS) are adaptive systems undergoing evolution. Whereas the evolution of biological systems is subject to natural selection, the evolution of software systems is under the constraints of hardware architecture and customer requirements. Since the pioneering work of Lehman (5), the evolutionary pressure on software has been studied among engineers. Interestingly enough, biological and software systems both execute information processing tasks. Whereas biological information processing is mediated by complex interactions between genes, proteins, and various small molecules, software systems exhibit a comparable level of complexity in the interconnections between functions. Understanding the structure and evolution of their underlying networks sheds light on the design principles of both natural and man-made information processing systems.

The master control plan of a cell is its transcriptional regulatory network. The transcriptional regulatory network coordinates gene expression in response to environmental and intracellular signals, resulting in the execution of cellular processes such as cell divisions and metabolism. Understanding how cellular control processes are orchestrated by transcription factors (TFs) is a fundamental objective of systems biology (6–9), and therefore a great deal of effort has been focused on understanding the structure and evolution of transcriptional regulatory networks. Analogous to the transcriptional regulatory network in a cell, a computer OS consists of thousands of functions organized into a so-called call graph, which is a directed network whose nodes are functions with directed edges leading from a function to each other function it calls. Whereas the genome-wide transcriptional regulatory network and the call graph are static representations of all possible regulatory relationships and calls, both transcription regulation and function activation are dynamic. Different sets of transcription factors and target genes forming so-called functional modules (10) are activated at different times and in response to different environmental conditions. In the same way, complex OSs are organized into modules consisting of functions that are executed for various tasks.

Here we perform a one-to-one comparison between the transcriptional regulatory network of *Escherichia coli* and the call graph of the Linux kernel, which are both canonical systems. *E. coli* is one of the most well-annotated model organisms. The study of its transcriptional regulatory network has a long history (11–15). On the software side, the Linux kernel is the central

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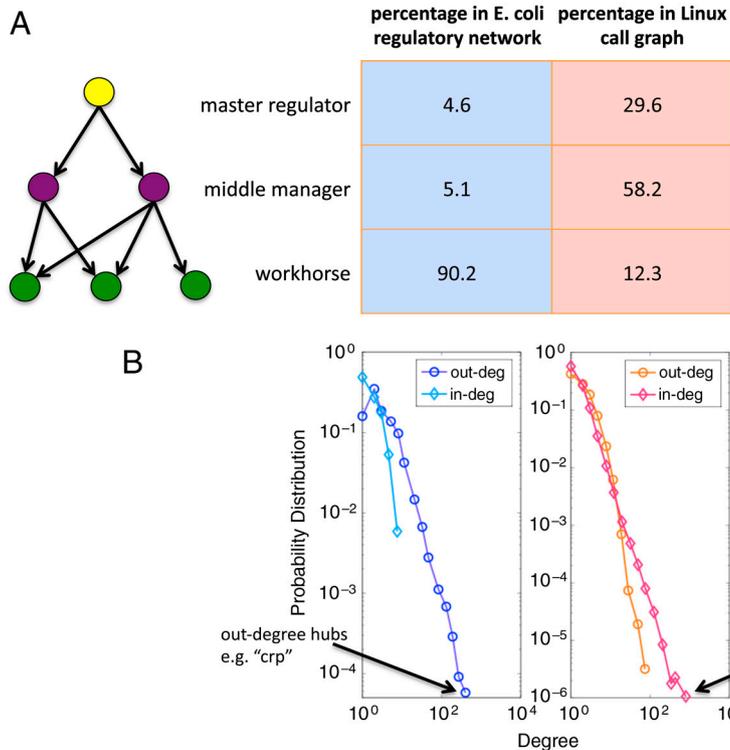


Fig. 2. Comparison of the *E. coli* transcriptional regulatory network and Linux call graph in terms of topology and hierarchical structure. (A) The distribution of the three categories in the *E. coli* transcriptional regulatory network and the Linux call graph. The transcriptional regulatory network (1,378 nodes) follows a conventional hierarchical picture, with a few top regulators and many workhorse proteins. The Linux call graph (12,391 nodes), on the other hand, possesses many regulators; the number of workhorse routines is much lower in proportion. (B) Degree distributions of the *E. coli* transcriptional regulatory network and the Linux call graph. The regulatory network has a broad out-degree distribution but a narrow in-degree distribution. The situation is reversed in the call graph, where we can find in-degree hubs, but the out-degree distribution is rather narrow. An out-degree hub in the *E. coli* regulatory network and an in-degree hub in the Linux call graph are shown.

$r = 0.53, P < 10^{-100}$ for the *E. coli* regulatory network). The most generic function is the well known function “printk,” which is responsible for standard display and thus called by over 90% functional modules. In the *E. coli* regulatory network, one of the most generic nodes is the outer membrane porin “ompF” that controls the diffusion of various metabolites. It is reused by 20% of the modules. Generally speaking, nodes in the Linux call graph have on average higher reuse than those in the *E. coli* transcriptional regulatory network (8.4% and 3.5%, respectively, $P < 10^{-12}$ in t test; see Fig. 3B). The difference is topologically attributed to the pyramidal versus top-heavy organization. The narrow base in the Linux call graph leads to a higher average reuse. Indeed, many generic functions are workhorses such as string manipulation function “strlen.”

As shown in Fig. 3B, one of the most striking differences concerning the organization of modules in the transcriptional regulatory network and the call graph is the overlap of modules. In the Linux call graph, two randomly chosen modules overlap by more than 80%. On the other hand, the average overlap in the *E. coli* transcriptional regulatory network is less than 5%. We shall discuss later how such differences in the overlap of modules play a key role in robustness and fragility of the two systems.

Comparison of Network Evolution and Node Persistence. The core components of a system are usually those that survive the evolutionary process. It is instructive to study those “survivors” in both the *E. coli* transcriptional regulatory network and the Linux call graph. In the Linux kernel, we focus on persistent functions, defined as those that exist in every version of software development. Persistent functions in software systems are analogous to persistent genes in biological systems, which are genes that are consistently present in a large number of genomes (22). We identified persistent functions in the Linux kernel on the basis of their appearance in all versions of the Linux source code used in this study and persistent genes in the *E. coli* genome by examining their distribution across a group of over 200 phylogenetically diverse bacterial genomes (see *Materials and Methods* for details). As shown in Fig. 1, most persistent genes in the *E. coli* regulatory network are workhorses: 71 out of 72 compared to 1,243 out of

1,378 for all genes ($P < 10^{-3}$ by permutation test). On the other hand, in the Linux call graph, persistent functions are present at all three levels but are significantly enriched only among the master regulators and middle managers (4,680 out of 5,120 persistent functions are master regulators and middle managers, compared

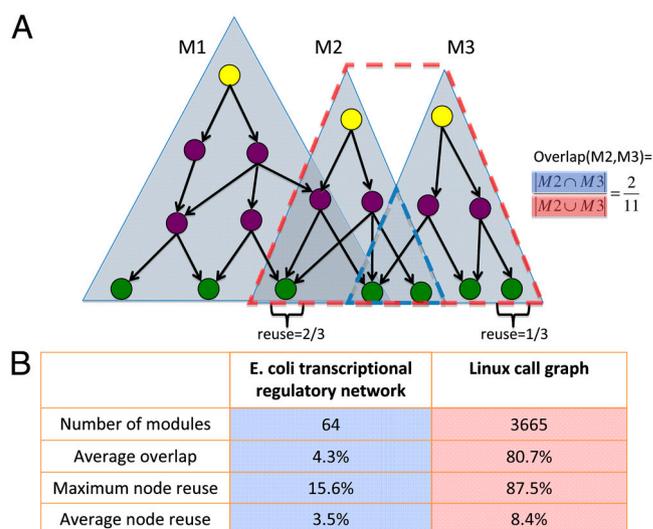


Fig. 3. Modules in the *E. coli* transcriptional regulatory network and Linux call graph. (A) Definition of modules, reuse, and overlap. A module is characterized by a master regulator, with zero in-degree, and all of the nodes regulated directly or indirectly by the master regulator. Here there are three modules (M1, M2, and M3) represented by three triangles. Reuse of a node is defined as the fraction of modules to which the node belongs. This quantity is illustrated with the two labeled nodes. One is shared by M1 and M2 but not M3, and thus the reuse is 2/3. The other belongs to only M3; its reuse is therefore 1/3. The overlap between a pair of modules is defined by the size of their intersection normalized by their union. The overlap of M2 and M3 is thus 2/11. (B) Statistics of modules in the *E. coli* transcriptional regulatory network and the Linux call graph. The average overlap is given by the mean overlap between pairs of randomly chosen modules. Nodes in the call graph are in general more generic; i.e., they are reused by more modules.

are revised more often. In fact, the adaptive functions distinguish themselves by having higher values of reuse (12.6% versus 4.4%, Wilcoxon rank-sum test $P < 10^{-20}$) than the conservative functions.

Discussion

We have presented a comparative analysis between the transcriptional regulatory network of *E. coli* and the call graph of the Linux operating system and explored their similarities and differences in hierarchical structure, modularity of organization, and persistence of nodes. A summary of the comparison can be found in Table 2. The two networks are shaped by different underlying design principles, which are deeply connected to the interplay between the systems and their environments. From a topological standpoint, it is intriguing that two distinct evolutionary processes both lead to the emergence of hierarchy in the control and regulation layouts, probably because hierarchy is a most effective way to transfer information and coordinate processes. Nevertheless, we have observed several intrinsic differences between the two hierarchical networks. To a certain extent, the presence of in-degree hub functions and the top-heavy hierarchy found in the call graph can be readily explained by common programming practices. In general, for the sake of clarity and easy debugging, programmers are encouraged to break down a code into pieces and reuse certain functions; functions that are called by many others, i.e., in-degree hubs, are therefore favored. The reuse of code leads to generic functions, which also accounts for the increase of overlap between modules in the Linux call graph. These programming practices are rooted in considerations of cost effectiveness. From an engineering point of view, the reuse of common nodes between modules is a cost-effective way to construct a complex system. However, such optimized usage of functions comes at the expense of robustness, because breakdown of a generic function causes problems in many modules. More importantly, generic functions lead to potential fragility in the sense that modifying any module may require compensating changes in a generic function. As a result, generic functions have to be updated more often (as reflected by the class of rapidly revising functions in Fig. 4A). The low overlap between modules in biological networks, on the other hand, increases robustness. Modules tend to work more independently by recruiting different sets of workhorses from the broad base of the network hierarchy.

The study of persistent genes in biological networks and persistent functions in call graphs offers insight into the evolution of hierarchies. Persistent genes form the core machinery of life, the so-called paleome (23). They usually are not regulators but work-

horse genes that perform vital tasks. In fact, most persistent genes are enzymes. The enrichment of persistent genes at the bottom of the regulatory hierarchy in *E. coli* is in accordance with the view that orthologous proteins are rather similar in function whereas regulatory changes are the main driving forces of evolution (9). To a certain extent, biological evolution is building from the bottom to the top. In contrast, persistent functions in the Linux call graph are usually not bottom-level workhorses but “controllers.” This difference suggests that not only do software networks possess more regulators than workhorses, the regulators are maintained on purpose and thus the evolution goes from top to bottom.

The trade-off between robustness and cost effectiveness biological and software systems is deeply related to the nature of their evolutionary processes. Biological evolution is mediated by random mutations followed by natural selection; a hub protein in a biological network is in general hard to evolve because of the constraints imposed by its many interactions. This constrained evolution is evinced by the negative correlation between node centrality and evolutionary rate in biological networks (24, 25). The random mutation and selection process underlying biological evolution prohibits the frequent targeted changes required for nodes to become generic. The system is then forced to pay for maintaining a large set of specially designed components performing a variety of functions in response to environmental changes. In contrast, engineering systems are fundamentally different. Both in-degree and betweenness centrality (26) are positively correlated with the rate of revision in the Linux call graph (see Fig. 4B for in-degree, Spearman correlation $r = 0.26$, $P < 10^{-82}$ for betweenness). In other words, in software engineering, a system that needs to continually adapt to new conditions is cost effective only by paying the price of constantly fine-tuning its most highly accessed functions.

Reuse is extremely common in designing man-made systems. For biological systems, to what extent they reuse their repertoires and by what means sustain robustness at the same time are questions of much interest. It was recently proposed that the repertoire of enzymes could be viewed as the toolbox of an organism (27). As the genome of an organism grows larger, it can reuse its tools more often and thus require fewer and fewer new tools for novel metabolic tasks. In other words, the number of enzymes grows slower than the number of transcription factors when the size of the genome increases. Previous studies (4) have made the related finding that as one moves towards more complex organisms, the transcriptional regulatory network has an increas-

Table 2. One-to-one comparison between the *E. coli* regulatory network and the Linux call graph

		<i>E. coli</i> transcriptional regulatory network	Linux call graph
Basic properties of systems	Nodes	Genes (TFs & targets)	Functions (subroutines)
	Edges	Transcriptional regulation	Function calls
	External constraints	Natural environment	Hardware architecture, customer requirements
	Origin of evolutionary changes	Random mutation & natural selection	Designers' fine-tuning
Hierarchical organization	Structure	Pyramidal	Top-heavy
	Characteristic hubs	Upper-level TFs with high out-degree	Generic workhorse functions with high in-degree
Organization of modules	Downstream modules as labeled by	Master TFs responsible for sensing environmental signals	High-level starting functions that initiate execution for specific tasks
	Node reuse	Low	High
	Overlap between modules	Low	High
Persistent nodes	Characteristics	Specialized (nongeneric) workhorses	Generic or reusable functions
	Location in hierarchy	Mostly bottom	Mostly top
	Evolutionary rate	Mostly conservative (e.g., dnaA)	Conservative (e.g., strlen) & adaptive (e.g., mempool_alloc)
Design principles	Building of hierarchy	Bottom up	Top down
	Optimal solution favors	Robustness	Cost effectiveness (reuse of components)

ingly top-heavy structure with a relatively narrow base. Thus, it may be that further analysis will demonstrate the increasing resemblance of more complex eukaryotic regulatory networks to the structure of the Linux call graph.

Materials and Methods

Network Information. Data on the *E. coli* transcriptional regulatory network were obtained from RegulonDB (15). The largest connected component of the network consists of 1,378 genes with 2,967 interactions. Linux source code was downloaded from the Linux Kernel Archives (<http://www.kernel.org>). To address the evolution of the kernel, 24 stable versions were used, from 2.6.4 to 2.6.27, spanning from March, 2004 to October, 2008. In general, the release of a new version, say, from 2.5 to 2.6, is accompanied by major changes. We worked on the 24 releases restricted in version 2.6 and focused on the gradual evolution exhibited in these releases. For some of these releases, an additional patch was required in order to compile (*SI Text*). The source codes were compiled on a MacBook with a 2 GHz Intel Core 2 Duo processor and 2 GB of memory by using the compiler GCC 3.4.6, and call graphs were extracted from the compiled code by using the tool CodeViz (release 1.0.11) by Gorman (<http://www.csn.ul.ie/~mel/projects/codeviz/>) (see *SI Text*). The network analysis presented in this study was performed on the most recent version of the Linux kernel downloaded (v. 2.6.27), in which there are 12,391 functions related by 33,553 calls. The network can be downloaded from <http://networks.gersteinlab.org/callgraph>.

Persistent Genes. The persistence index and the list of 212 persistent genes in *E. coli* K12 were obtained from ref. 22. Among them, 72 can be mapped to the largest component of the transcription regulatory network. We quantify conservation by the ratio of nonsynonymous to synonymous substitution rates (dN/dS) (28). The two rates were estimated by aligning *E. coli* K12 proteins with their orthologs from *Salmonella typhimurium* LT2. The list of orthologs was downloaded from the ATGC database (29). Alignment was done by using the tool PAL2NAL (30), and dN/dS values were estimated by the PAML package (31).

Persistent Functions. A function is defined as persistent if it appears in all the compiled call graphs (v. 2.6.4 to v. 2.6.27). The list of persistent functions can be found at <http://networks.gersteinlab.org/callgraph>. In this definition, we do not take into account the precise changes in the code of the function. The frequency of revision for a particular function was estimated by parsing the patch files (see *SI Text*). A function is regarded as revised if there is any change in its code.

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