Lecture 16 Linear Programming

Tuesday, March 19, 2019 2:18 PM

- Linear Program

- a linear program has n variables X_1, X_2, \dots, X_n (represented as a vector $x \in \mathbb{R}^n$), an objective $f(x) = C^T x = \sum_{i=1}^n C_i x_i$

and a set of linear constraints. (Xi's are variable, Ci's are known)

- goal of the linear program is to maximize/minimize the objective function given the constraints.

variables: X, X_2 objective $2X_1+X_2$ (c=(2,1))max 2x,+xz $\times^{r \geqslant 0}$ \downarrow -> constraints. XHX2 < 1

- Solution to a linear program

- feasible solution: a vector x that sotisfies all the constraints.

example:
$$X = (0,0)$$
 $X = (0,1)$ $X = (1,1)$

$$\begin{cases} X_{1} = 0 & \begin{cases} X_{1} = 0 & \\ X_{2} = 1 \end{cases} \\ X_{2} = 1 & \begin{cases} X_{1} = 1 & \\ X_{2} = 1 \end{cases} \end{cases}$$

$$f(X) = 0 \qquad f(X) = 0 \qquad f(X) = 0 \qquad f(X) = 0$$

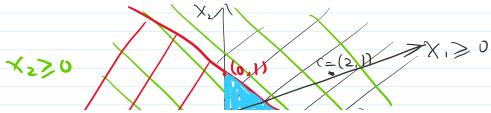
- optimal solution: a feasible solution x that optimizes the objective

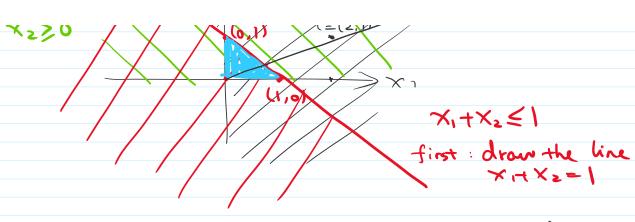
$$x=(1,0)$$
 $f(x)=2x,+x_z=(2)$
ratue of optimal solution is the value $f(x)$

value of optimal solution is the value f(x)
for optimal solution

- germetric interpretation

- constraints = half planes (half spaces in higher dimensions)





- system of linear inequalities (intersection of half planes blue region: feasible region
- objective function (a) direction of gravity

 line connecting from 0 to 0 is the direction
 of gravity
- Caronical form

standard way of writing linear program

Same linear program can be written in many ways.

$$\max_{X_1 \ge 0} \underbrace{X_1 \ge 0}_{X_2 \ge 0}$$

$$\underbrace{X_1 \ge 0}_{X_2 \ge 0}$$

$$\begin{array}{c|c}
 & min-2x_1-x_2 \\
 & x_1 \ge 0 \\
 & x_2 > 0
\end{array}$$

- Canonical form

$$(min) \langle C_1 X \rangle = C^T X = \sum_{i=1}^{N} C_i X_i$$

m inequalities $A \times \ge 0$ \Longrightarrow for every j=1,2,...,m $\stackrel{>}{\underset{i=1}{\sim}} A_{i,i} \times i \ge b_i$ $\stackrel{>}{\underset{>}{\sim}} b_i$ $\stackrel{>}{\underset{>}{\sim}} b_i$ $\stackrel{>}{\underset{>}{\sim}} b_i$ $\stackrel{>}{\underset{>}{\sim}} b_i$ $\stackrel{>}{\underset{>}{\sim}} b_i$

$$\begin{array}{c|c}
 & f_{ov} \ j=1, 2, ..., M \\
 & (A_{x})_{j} = \sum_{i=1}^{s} A_{j,i} \times_{i}
\end{array}$$

for the example
$$LP$$
 $c = (-2, -1)$

for the example
$$\angle P$$
 $c = (-2, -1)$

$$A = (-1, -1) \qquad b = -1$$

$$A \times \ge b \implies -x_1 - x_2 \ge -1$$

- free variable

$$\max_{y \ge 0} x + y$$

$$x + y \le 3$$

$$x \ge -5$$

call x a tree veriable because we have no constraint X > 0

- Using LP to solve graph problems

- Example 1: bipartite motching

O find the variables

in matching: for each edge want to know if it's in the matching.

$$X_{i,j} = \begin{cases} 1 & \text{if } (i,j) \text{ is an edge in motching.} \end{cases}$$

write constraints.

a. every classroom can hold ≤ 1 course for every \hat{J} (classroom) $\left(\sum_{i=1}^{h} X_{i,j}\right) \leq 1$

for every \hat{j} (classroom) $\left(\sum_{i=1}^{N} X_{ij}\right) \leq 1$ b every course needs only I classroom for every i (course) \(\int \times_i \) \(\int \times_i \) C. X;; Should be o or 1 cannot write this constraint, try best approximation. $0 \in X; j \leq 1$ (possible X; j = 0.7) (3) write the objective maximize number of matched edges $\geq \chi_{ij}$ max \(\bar{\bar{\chi}}\) \(\text{ij}\) for hipartite matching option() have X: j variables for all (iii) pairs only place where graph influences the LP is in the 2) only have Xi; variables if (i.i) is an edge. for every i $\sum_{j:(i,j)\in T} X_{i,j} \leq 1$ - fractional solution us. integral solution for LP. variables can be fractions in general. if all variables are integers. coll that un integral solution usually we hope for integral solutions - for the motching LP, possible to prove there exists integral optimal solution