

# CompSci 201, L27: Minimum Spanning Tree (MST) and Disjoint Sets (Continued)

# Logistics, coming up

- Today, Monday, 4/24
  - Project P6: Route (last project) due
- End of Semester Survey
  - Due by LDOC this Wednesday, April 26
  - Required class survey, run by the course staff
- Course Evaluations
  - Due by this Saturday, April 29
  - Run by Duke, anonymous to us

# Final Exam Logistics Reminder

- 3 final sections: F1, F2, F3 corresponding to 3 midterms M1, M2, M3.
  - Exams grade =  $\text{Avg}(\text{Max}(M1, F1), \text{Max}(M2, F2), \text{Max}(M3, F3))$
  - If happy with grades? Don't need to take it.
  - If you missed a midterm? Make sure to take at least that part.
- Monday 5/1, 9 am - noon. You will have 50 minutes to complete each part.
  - 9-9:50 am. F1 (corresponding to M1)
  - 10-10:50 am. F2 (corresponding to M2)
  - 11-11:50 am. F3 (corresponding to M3)

# Final Grade Estimates

- Everything should be live and updated in the sakai gradebook *except*:
  - To add today or tomorrow:
    - P5
  - To add by this weekend
    - P6
    - APT9
    - Last couple weeks WOTOs

# Today's Agenda

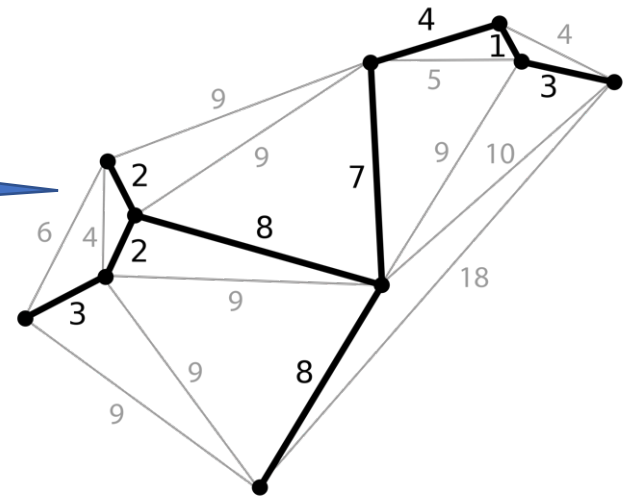
1. Review Minimum Spanning Tree (MST) problem and Kruskal's Algorithm
2. Investigate efficient disjoint sets / union find data structure
3. (time permitting) Solve an MST problem together live

# Minimum Spanning Tree (MST) Problem

- Given  $N$  nodes and  $M$  edges, each with a weight/cost...
- Find a set of edges that connect *all* the nodes with minimum total cost. (will be a tree)

Weighted undirected graph with:

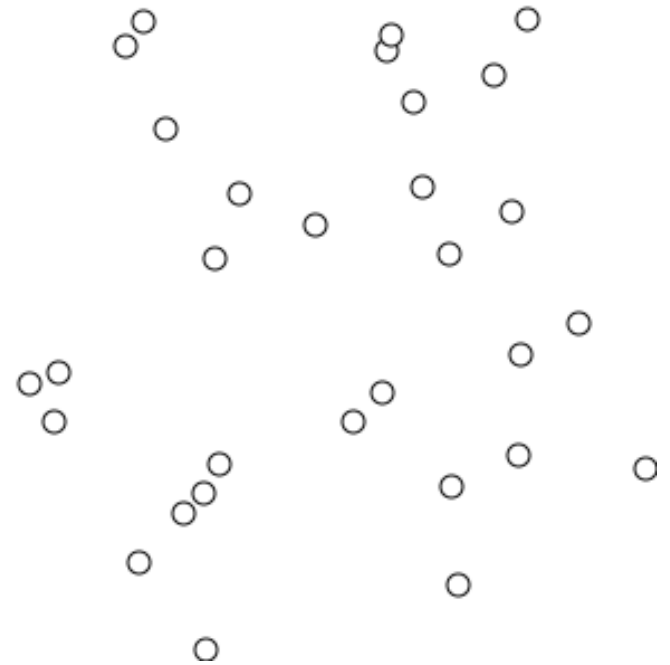
- Edges labeled with weights/costs
- Minimum spanning tree highlighted



# Visualizing Kruskal's Algorithm

In the visualization:

- Edges between all pairs of vertices
- Weights are implicit by distances
- Algorithm greedily grows by cheapest edge that connects disjoint sets/trees.



By Shiyu Ji - Own work, CC BY-SA 4.0,  
<https://commons.wikimedia.org/w/index.php?curid=54420894>

# Kruskal's Algorithm in *Pseudocode*

Input:  $N$  node,  $M$  edges,  $M$  edge weights

- Let MST to an empty set
- Let  $S$  be a collection of  $N$  **disjoint sets**, one per node
- While  $S$  has more than 1 set:
  - Let  $(u, v)$  be the minimum cost remaining edge
  - **Find** which sets  $u$  and  $v$  are in. If not equal:
    - **Union** the sets
    - Add  $(u, v)$  to MST
- Return MST



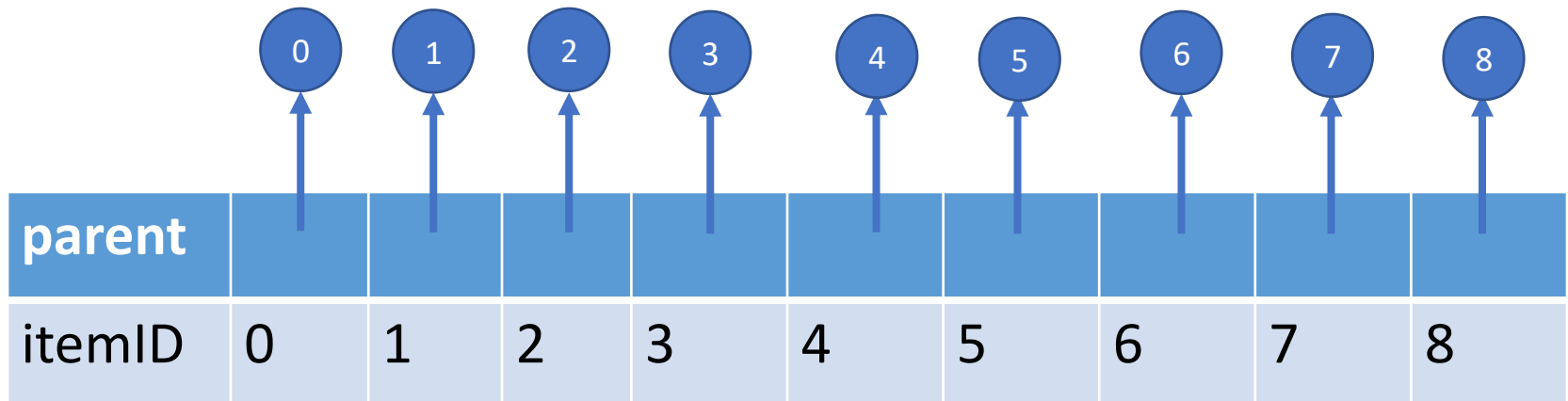
# Disjoint Sets and Union-Find

# Union Find Data Structure

- Aka Disjoint Set Data Structure
- Start with  $N$  distinct (disjoint) sets
  - consider them labeled by integers: 0, 1, ...
- ***Union*** two sets: create set containing both
  - label with one of the numbers
- ***Find*** the label of the set containing a number
  - Initially self, but changes after unions

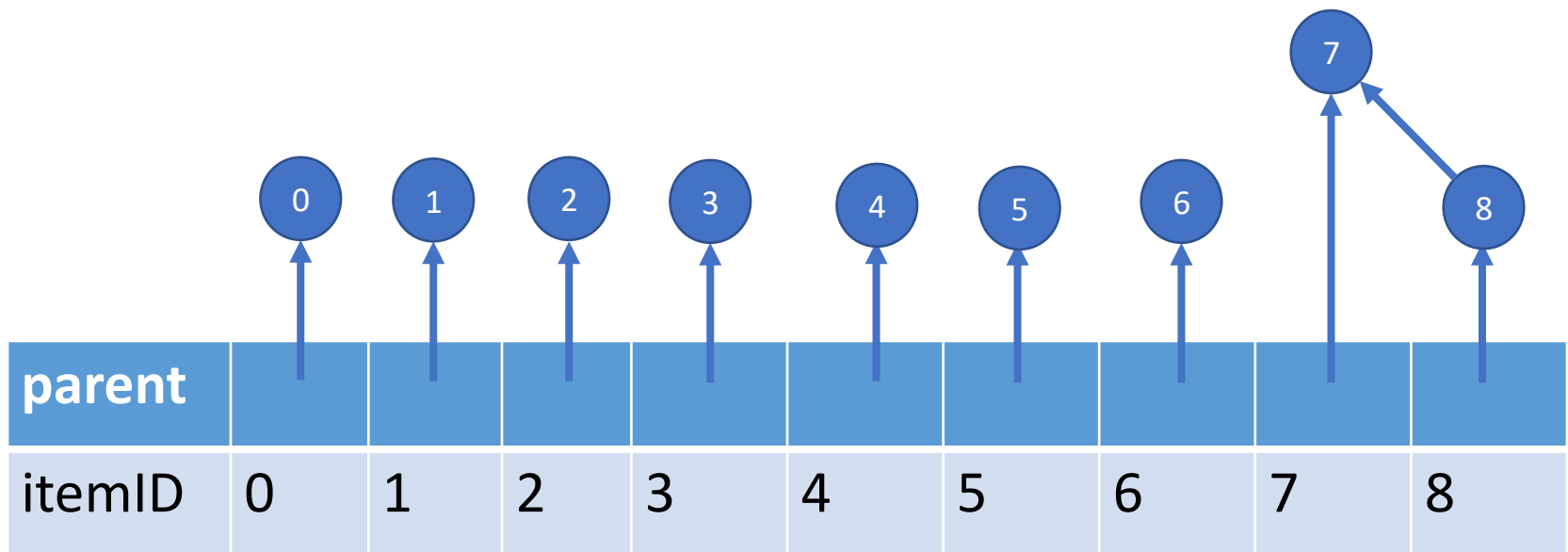
# Disjoint-Set Forest Implementation

- Each set will be represented by a parent “tree”: Instead of child pointers, nodes have a parent “pointer”.
- Everything starts as its own tree: a single node



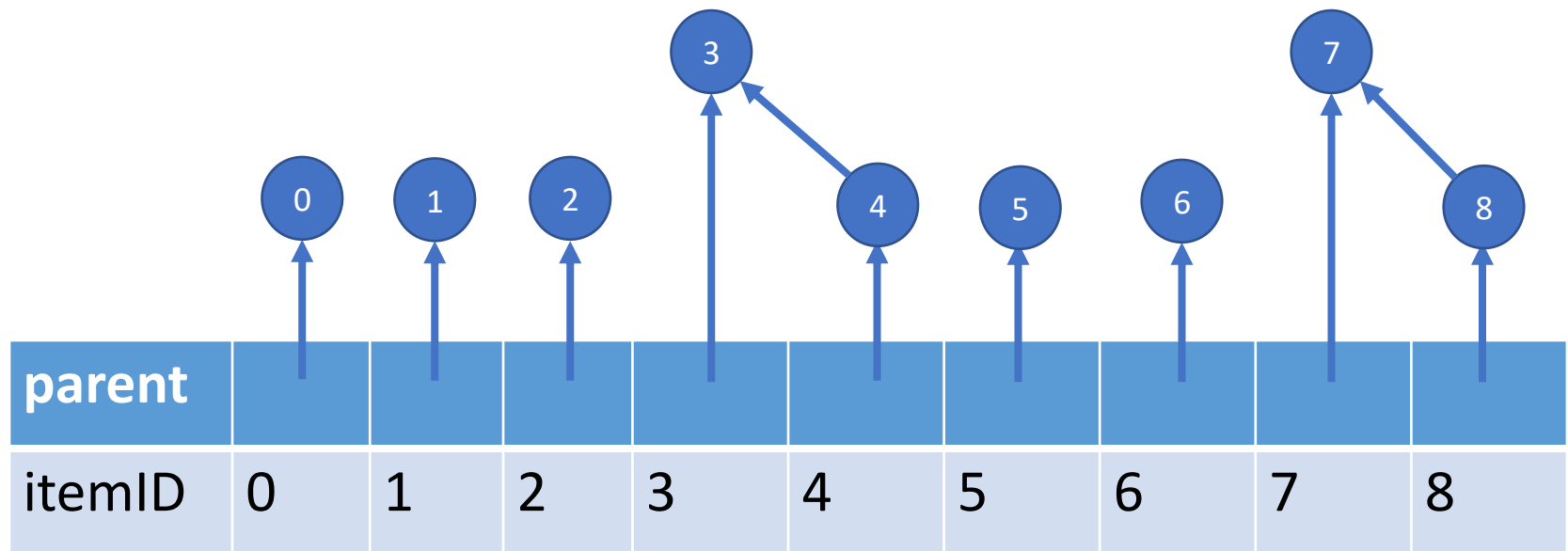
# Disjoint-Set Forest Union

- Union(7,8)
- Just make leaf/root point to parent[7]



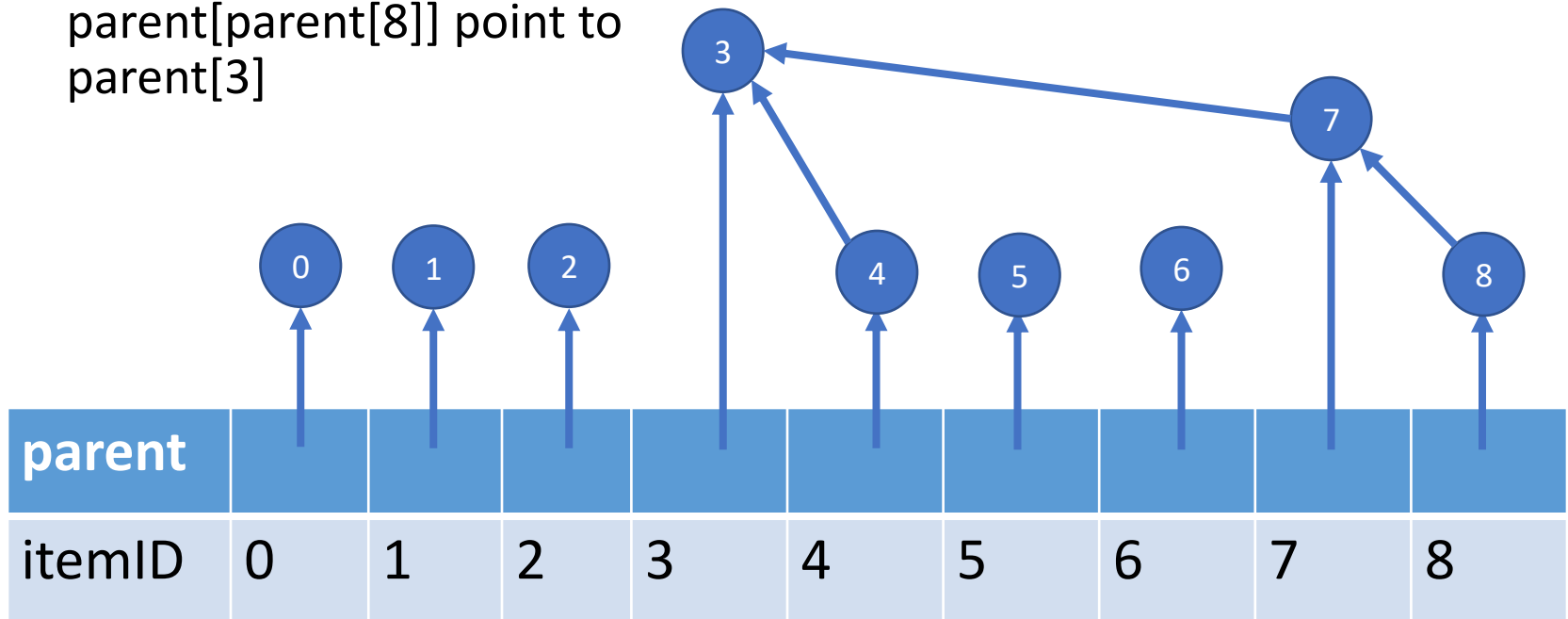
# Disjoint-Set Forest Union

- **Union(3,4)**
- Just make `parent[4]` point to `parent[3]`



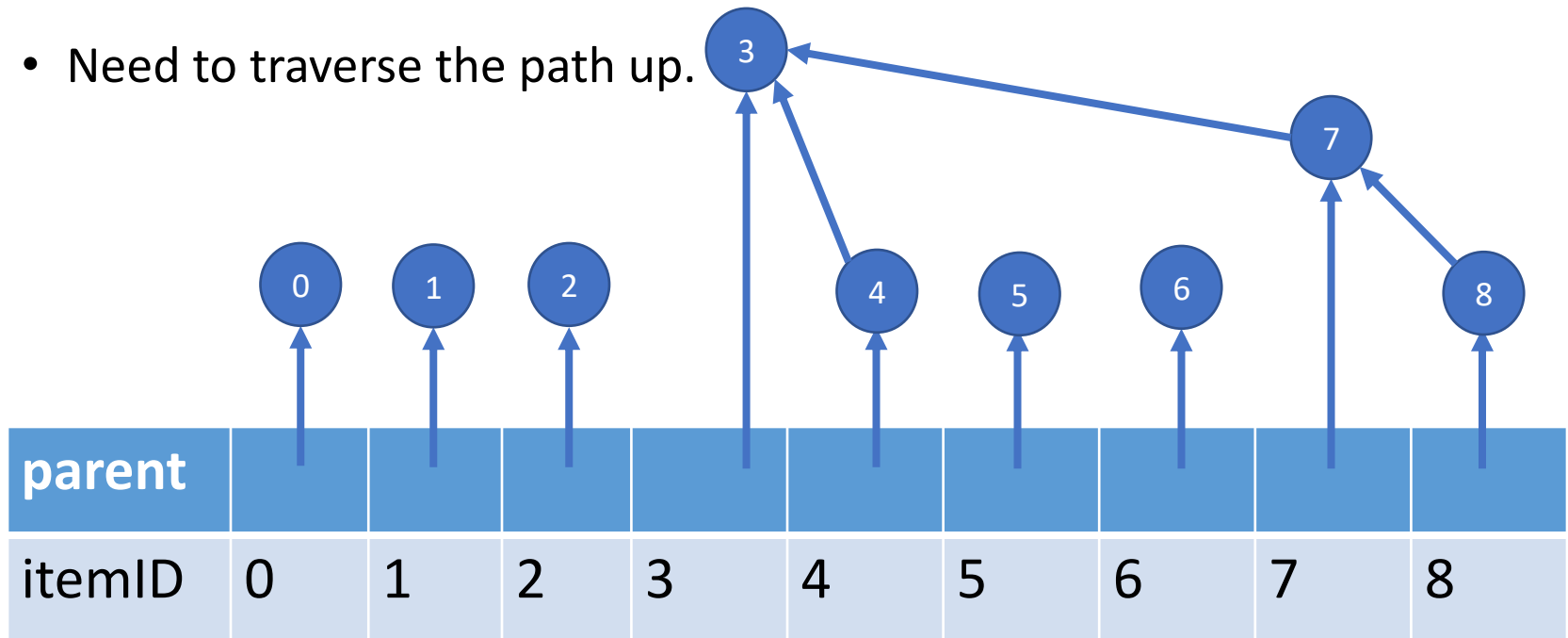
# Disjoint-Set Forest Union

- Union(3,8)
- Multi-level, make  $\text{parent}[\text{parent}[8]]$  point to  $\text{parent}[3]$



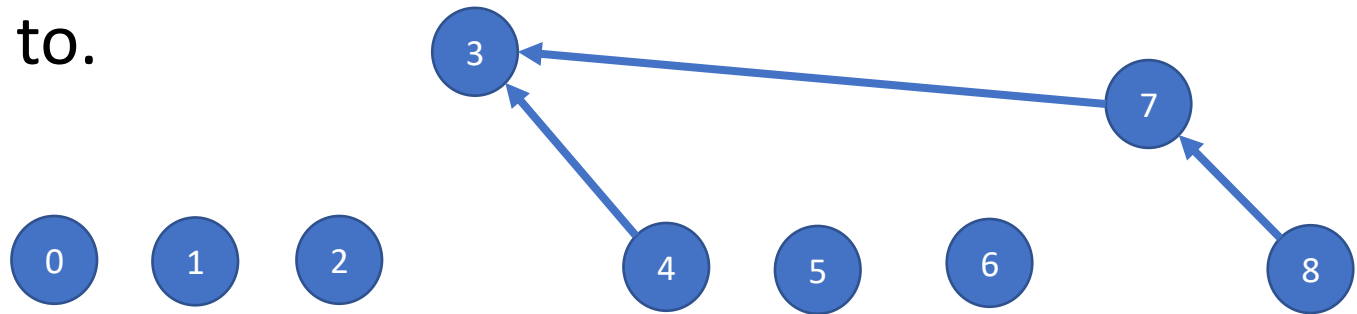
# Disjoint-Set Forest Find

- Find(8)
- Return last ancestor of 8.
- Need to traverse the path up.



# Disjoint-Set Forest Array Representation

- The “nodes” and “pointers” are just conceptual – can represent with a simple array, like binary heap.
- Parent array just stores what the itemID node points to.



parent	0	1	2	3	3	5	6	3	7
itemID	0	1	2	3	4	5	6	7	8

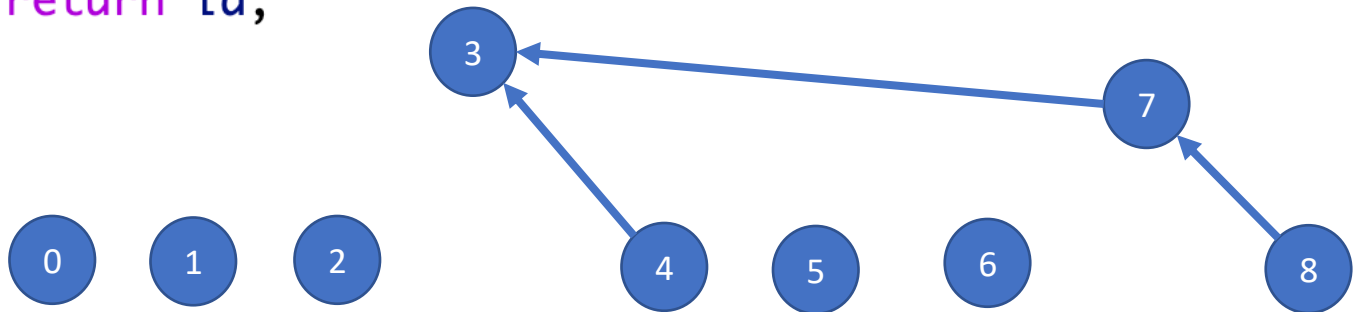


# Disjoint-Set Forest Find

```
18 public int find(int id) {  
19     while (id != parent[id]) {  
20         id = parent[id];  
21     }  
22     return id;  
23 }
```

“last ancestor” is just  
when  $\text{parent}[i] = i$

Else go to next  
“node up”



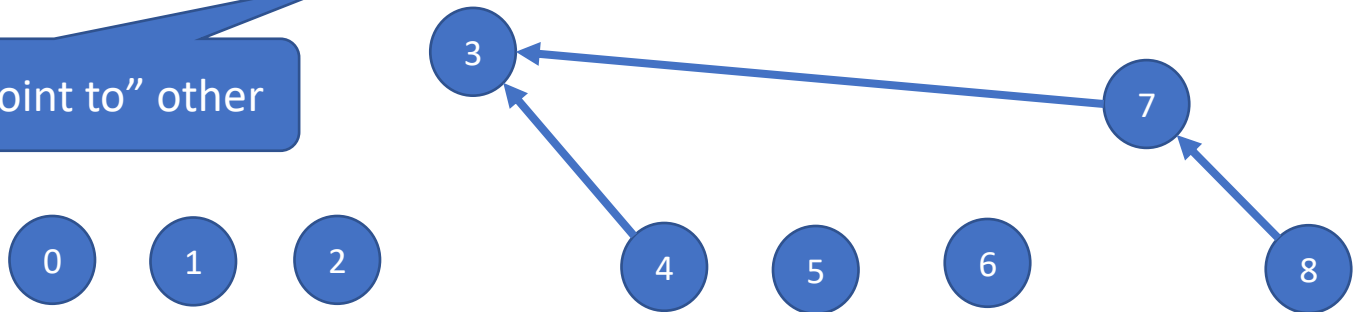
parent	0	1	2	3	3	5	6	3	7
itemID	0	1	2	3	4	5	6	7	8

# Disjoint-Set Forest Union Revisited

```
25 public void union(int set1, int set2) {  
26     int root1 = find(set1);  
27     int root2 = find(set2);  
28     parent[root2] = root1;
```

“last ancestors” from initial  
set1 and initial set2  
“nodes”

Make one “point to” other



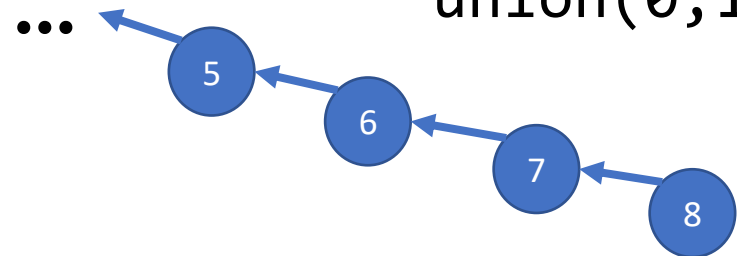
parent	0	1	2	3	3	5	6	3	7
itemID	0	1	2	3	4	5	6	7	8

# Worst-Case Runtime Complexity?

```
25 public void union(int set1, int set2) {  
26     int root1 = find(set1);  
27     int root2 = find(set2);  
28     parent[root2] = root1;
```

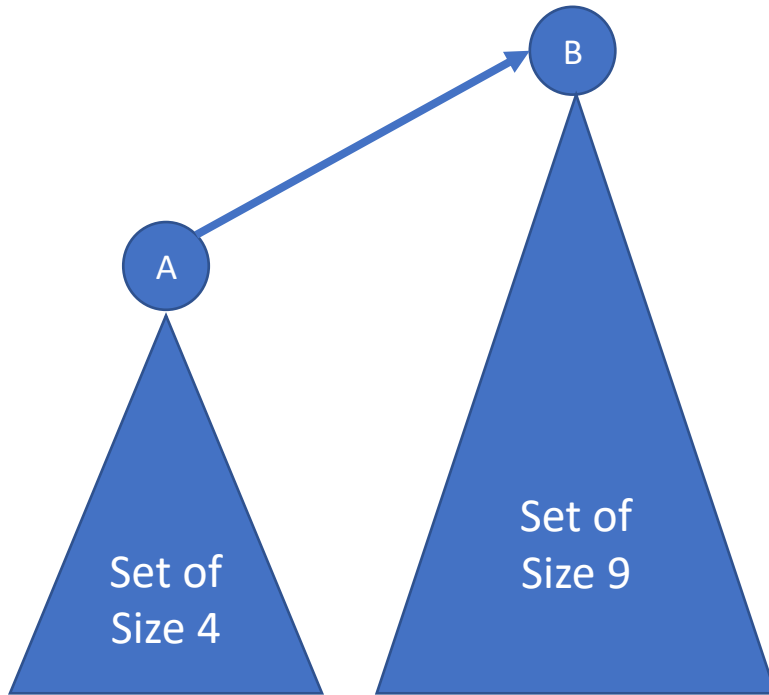
What if we...  
union(7,8)  
union(6,7)  
union(5,6)  
...  
union(0,1)

Now find(8) would have  
linear runtime complexity!!



parent	0	0	1	2	3	4	5	6	7
itemID	0	1	2	3	4	5	6	7	8

# Optimization 1: Union by Size



Be careful in how you union. Always make the “root” for the set with *fewer* elements point to the “root” for the set with *more* elements.

Sufficient for worst case logarithmic efficiency.

# Optimization 1: Union by Size

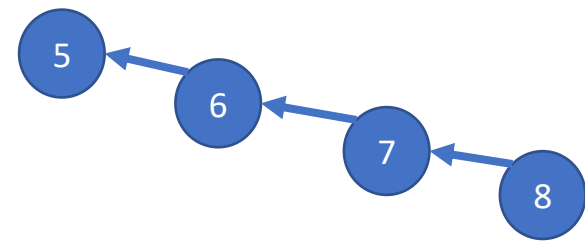
```
37 public void union(int set1, int set2) {
38     int root1 = find(set1);
39     int root2 = find(set2);
40     if (root1 == root2) { return; }
41     if (setSizes[root1] < setSizes[root2]) {
42         parent[root1] = root2;
43         setSizes[root2] += setSizes[root1];
44     }
45     else {
46         parent[root2] = root1;
47         setSizes[root1] += setSizes[root2];
48     }
49     size--;
50 }
```

If already in same set, nothing to do.

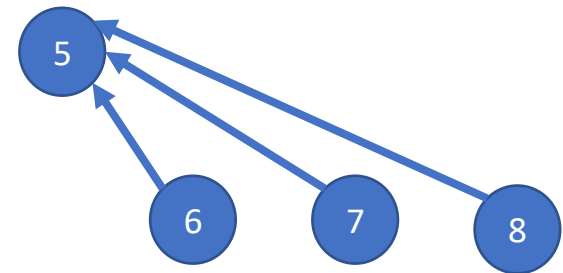
Make the smaller set "point to" the bigger set.

# Lazy Path Compression

- **Lazy path compression:**  
When ever you traverse a path in `find`, connect all the pointers to the top.
- Sufficient for **amortized logarithmic** runtime complexity for union/find operations.



`find(5)`



# Disjoint Set Forest Path Compression

```
8 public int find(int id) {  
9     int idCopy = id;  
10    while (id != parent[id]) {  
11        id = parent[id];  
12    }  
13    int root = id;  
14    id = idCopy;  
15    while(id != parent[id]) {  
16        parent[idCopy] = root;  
17        id = parent[id];  
18        idCopy = id;  
19    }  
20    return id;  
21 }
```

Get the “last ancestor” as before

Traverse path again, assigning everything to the “last ancestor”

# Optimized Runtime Complexity

- Optimizations considered separately:
  - Union by size: Worst case logarithmic
  - Path compression: Amortized logarithmic
- Considered together...?
  - Worst case logarithmic, and *amortized inverse Ackermann function*  $a(n)$ .
  - $a(n) < 5$  for  $n < 2^{2^{2^{2^{16}}}}} = 2^{2^{65536}}$
  - Practically constant for any  $n$  you can write down



# Remember Kruskal's Algorithm

## Runtime?

Input:  $N$  node,  $M$  edges,  $M$  edge weights

- Let MST to an empty set
- Let  $S$  be a collection of  $N$  **disjoint sets** one per node
- While  $S$  has more than 1 set:
  - Let  $(u, v)$  be the minimum cost remaining edge
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    - **Union** the sets
    - Add  $(u, v)$  to MST
- Return MST

Looping over (worst case) all  $M$  edges

Remove from binary heap,  $O(\log(M))$

$O(M(\log(M)+C))$  because  $C < \log(M)$  for our optimized union find

# Solving Example MST Problem

[leetcode.com/problems/min-cost-to-connect-all-points](https://leetcode.com/problems/min-cost-to-connect-all-points)

Live Coding

