Raft

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Fundamental Goals

- Safety
 - Nothing bad happens. System runs correctly
 - **Consistency**: All nodes see the same data at the same time
- Liveness
 - Something good eventually happens. System makes progress
 - Availability: Systems remain responsive during failures

Generic Technique: Replicated State Machine (RSM)

- Replicated state machine
 - Model service as a deterministic state machine
 - Same commands \rightarrow same output
 - Run multiple replicas that fail *independently*
 - Redundancy and independency
 - No single point of failure
 - Replicas agree on the seq of ops they run



Model Services as State Machines

Consensus Algorithm

- Consensus algorithm
 - Nodes agree on something in the presence of failures
 - Type 1. Byzantine fault tolerance
 - Proof-of-work (BitCoin), proof-of-stake (Ethereum)
 - Type 2. Crash fault tolerance
 - Paxos, Raft (this lecture)

RSM with Consensus



- Leader-based: A leader node is designated to coordinate consensus process
- Consensus: Ensure consistency across nodes via log replication

Fundamental Trade-Off Between Safety and Liveness

- FLP Impossibility
 - **Theorem**: In an *asynchronous* (unbounded network delay) distributed system with even one *faulty* node, it is impossible to guarantee both safety and liveness in reaching consensus.
 - Proof: Because messages can be delayed indefinitely, a protocol cannot distinguish between a slow node (or network partition) and a failed node.
 - **Implication**: Consensus algorithms must sacrifice liveness under certain failures to maintain safety.



Case 1. Network Partition



Case 2. Node Failure

Fundamental Trade-Off Between Safety and Liveness

- CAP Theorem
 - **Theorem**: In a distributed system that can experience *network partitions*, it is impossible to simultaneously achieve consistency, availability, and partition tolerance.
 - Proof: Serving clients in one partition during network partition: (1) reject ops: sacrifice availability; (2) allow ops: sacrifice consistency.
 - **Implication**: Under network failures, you must choose between consistency (safety) and availability (liveness).



Categorizing Dist Sys By Trade-Offs They Make

Quorum-Based Consensus: Trade Off Availability for Consistency

- Leader must be supported by a majority of the group (a *quorum*)
 - **Consistency**: At most one connected subgroup can serve requests
 - Availability: Once a majority of replicas fail, the remaining replicas should not serve requests due to the indistinguishbility issue.

Raft: Overview



- Quorum-based, leader-based consensus for RSM
- Failure model: message delayed/lost messages, fail-stop

Raft: Problem Decomposition

- Leader election
 - Detect leader crashes and select a new leader
- Log replication
 - Leader appends commands from clients to its log
 - Leader replicate its log to other servers
- Safety properties

Raft: Leader Election

Server Roles and RPCs



Passive (but expects regular heartbeats)

Issues RequestVote RPCs to get elected as leader Nodes vote for the first request received

Issues AppendEntries RPCs:

- Replicate its log
- Heartbeats to maintain leadership

Raft: Leader Election

Terms



- Logical time individually maintained by each node
 - Incremented when a node initiates a new election
 - Synced when receives RPCs with newer terms
- Included in both types of RPCs to sync clock
 - Older term \rightarrow reject requests and reply with an error
 - Newer term \rightarrow advance node's own clock
- Each term has at most one leader
 - Agreement on term is equivalent to agreement on leader
 - Election achieves consensus on leader as well as term

Raft: Leader Election

Safety and Liveness of Election

- Safety: at most one leader per term
 - **Proof**: one vote per node. Two majorities must overlap.



- Liveness: some candidate eventually wins
 - Issue: fixed election timeout leads to *split votes*, where multiple nodes timeout and request votes simultaneously, and none receives a majority
 - **Solution**: nodes use *randomized timeout*, hoping one candidate wins before the next node timeout

Normal Operation



5 Followers reply with a positive acknowledgement 8 Leader notifies followers of <u>committed entries</u> in subsequent AppendEntries RPCs Replicated to any majority

Log Structure (Normal Operation)



Issue: Log Inconsistency Caused by Crashes



Fix: Log Matching Property via Consistency Check

- Log matching property: If log entries on different nodes have same index and term, then they store the same command, and the logs are identical in all preceding entries.
 - \rightarrow If a given entry is committed, all preceding entries are also committed.



Fix: Log Matching Property via Consistency Check

- AppendEntries includes <term, index> of the preceding log entry
- Followers first check if they have the preceding log entry
 - Match: append log entry and send positive ack
 - Mismatch: send negative ack, asking leader to retry replicating the preceding entry
- Ensures log matching property via induction



Issue: Leader Overwriting Committed Entries of Previous Terms



Term 5: who can be the new leader?



#2 overwritten!

Fix: Leader Completeness Property During Election

- Ensure leaders contain all committed logs
- How: RequestVote includes <term, index> of the last log entry, and voters reject candidates whose log is less up-to-date than them.
- Proof: The new leader's log is more up-to-date than a majority of the nodes. The majority that committed the entries in the previous term must *overlap* with the majority that elects the new leader.

Committed Entries

- Why are log entries replicated to a majority of nodes considered stable and safe to apply to state machines?
 - Election rules make sure that new leaders always contain all committed entries, thus committed entries cannot be overwritten during log replication
 - Leaders can fix inconsistency/lagging in followers' logs, making sure a majority of nodes contains all committed entries when replicating a new entry