

Algorithmic mechanism design

Vincent Conitzer
conitzer@cs.duke.edu

Algorithmic mechanism design

- Mechanisms should be accompanied by an efficient **algorithm** for computing the outcome
- May not be easy
 - E.g., using the Clarke (VCG) mechanism in combinatorial auctions requires solving the winner determination problem optimally
- If the mechanism's outcomes are too hard to compute, we may need a different mechanism
- **Algorithmic mechanism design** [Nisan & Ronen STOC 99] = simultaneous design of mechanism and algorithm for computing its outcomes
 - Given a mechanism, is there an efficient algorithm for computing its outcomes?
 - Given an algorithm for choosing outcomes, can we make it incentive compatible (e.g., using payments)?

Combinatorial auctions: mechanisms that solve the winner determination problem approximately

- Running Clarke mechanism using approximation algorithms for WDP is generally not strategy-proof
- Assume bidders are single-minded (only want a single bundle)
- A greedy strategy-proof mechanism [Lehmann, O'Callaghan, Shoham JACM 03]:

1. Sort bids by
(value/bundle
size)

2. Accept
greedily starting
from top

Worst-case
approximation
ratio = (#items)

✓ {a}, 11	1*(18/2) = 9
✓ {b, c}, 20	
✗ {a, d}, 18	
✗ {a, c}, 16	2*(7/1) = 14
✗ {c}, 7	
✓ {d}, 6	0

3. Winning bid
pays **bundle size**
times
(value/bundle size)
of first bid forced
out by the winning
bid

Can get a better approximation
ratio, $\sqrt{(\#items)}$,
by sorting by value/ $\sqrt{(\text{bundle size})}$

Clarke-type payments with same approximation algorithm do not work

✓ {a}, 11

✓ {b, c}, 20

✗ {a, d}, 18

✗ {a, c}, 16

✗ {c}, 7

✓ {d}, 6

Total value to
bidders other
than the {a}
bidder: 26

✓ {b, c}, 20

✓ {a, d}, 18

✗ {a, c}, 16

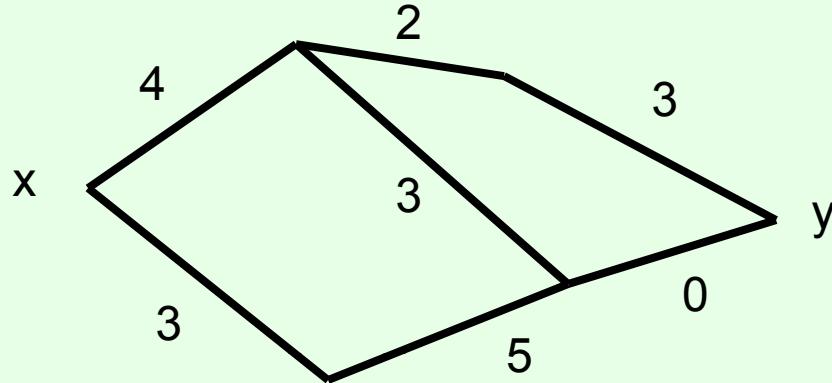
✗ {c}, 7

✗ {d}, 6

Total value: 38

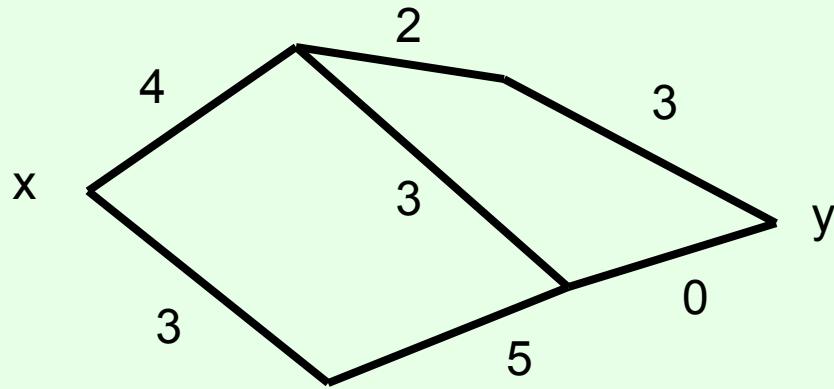
{a} bidder should
pay $38 - 26 = 12$,
more than her
valuation!

A shortest path/combinatorial reverse auction problem [Nisan & Ronen STOC 99]

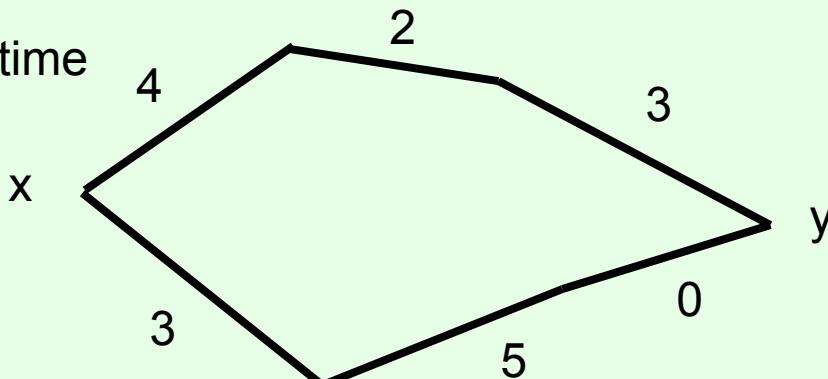


- Someone wants to buy edges that constitute a path from x to y
- Each edge e has a separate owner, and that owner submits (bids) a cost c_e for it
- Goal:
 - buy the shortest path (= path with minimum total weight),
 - pay every edge according to Clarke mechanism
 - no incentive to misreport costs
- That is, an edge e on the shortest path is paid
(cost of shortest path without e) - (cost of shortest path with e) + c_e

Computing Clarke payments

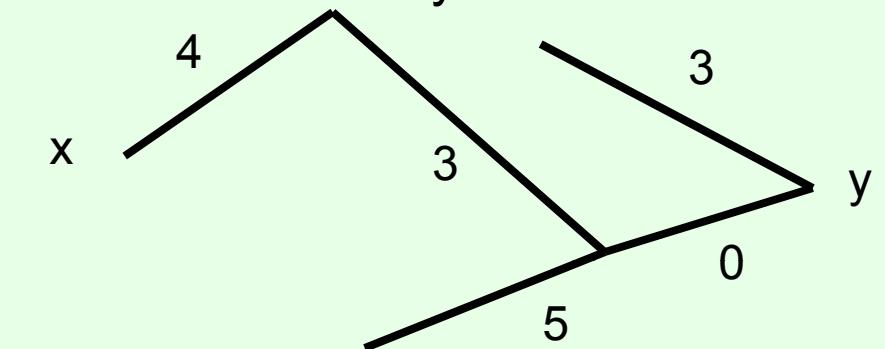
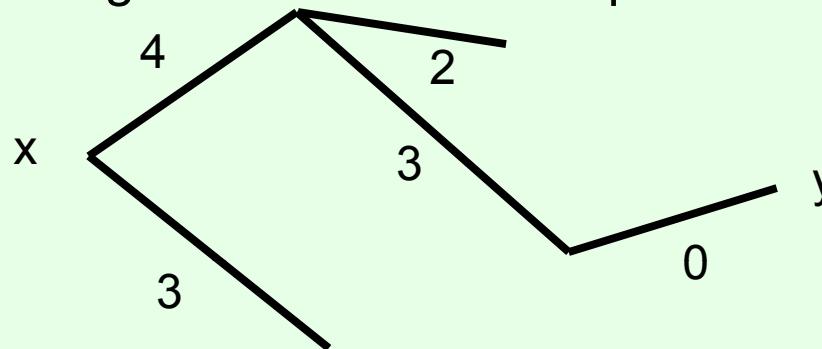


- One strategy:
 - Compute shortest path (e.g., using Dijkstra's algorithm)
 - For each edge on the shortest path, remove that edge, solve the problem again
 - $O(nm + n^2 \log n)$ total time
- Is there a more efficient algorithm?

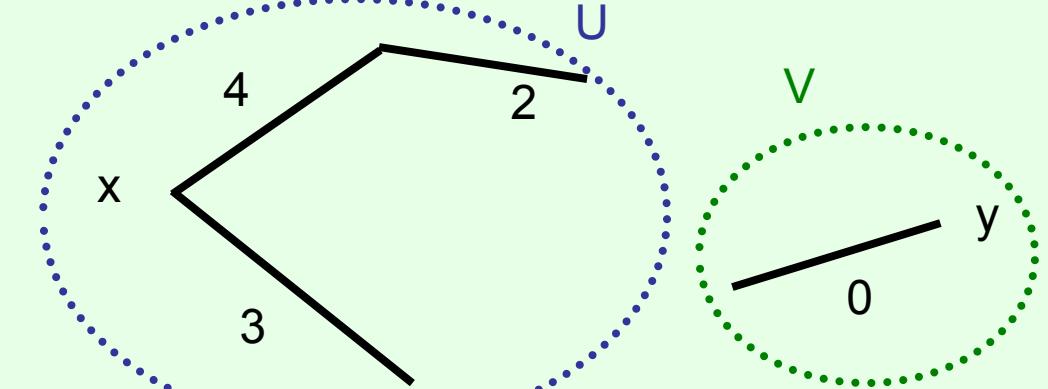


Hershberger-Suri [FOCS 01] algorithm

- Compute the shortest path **trees** from x and from y
 - using Dijkstra
 - gives us the shortest path from any vertex to x and to y



- Remove the edge e whose payment we wish to compute from the first (x) tree
 - Cuts the graph into U and V



- Over all edges (u, v) across components (excluding e), minimize $d(x, u) + c(u, v) + d(v, y)$
 - Using data structures, can be done for all edges in $O(n \log n + m)$

A make-span/reverse auction problem

[Nisan & Ronen STOC 99]

- There are m jobs that need to be scheduled on (say) 2 machines
- Each machine is owned by a separate agent
- c_{ij} is the time that machine i would take on job j
 - also the cost that machine i has for doing j
 - private information
- The objective is to minimize the **make-span**
 - = highest total cost for an agent, = completion time of last job
- One possibility: just use Clarke mechanism
 - Award job j to the machine that can do it faster (minimize total work),
 - Pay that machine the cost of the other machine for j
- Gives a 2-approximation to the make-span
 - **Theorem:** No deterministic mechanism does better

A bad instance for the Clarke mechanism

- Two jobs
- Machine 1: $c_{11} = 1, c_{12} = 1$
- Machine 2: $c_{21} = 1+\varepsilon, c_{22} = 1+\varepsilon$
- Clarke mechanism will give both jobs to 1
- Make-span: 2
- Can get $1+\varepsilon$ by giving one job to each (ignoring mechanism design considerations)

Weighted Groves mechanisms

- Recall a Groves mechanism
 - chooses an allocation o that maximizes the sum of reported utilities,
 - pays agent i : $\sum_{j \neq i} u_j(\theta_j', o) + h(\theta_{-i}')$ for some function h
- A **weighted Groves mechanism**
 - has a weight w_i for each agent,
 - chooses an allocation o that maximizes $\sum w_i u_i(\theta_i', o)$,
 - pays agent i : $(1/w_i) \sum_{j \neq i} w_j u_j(\theta_j', o) + h(\theta_{-i}')$ for some function h
- Weighted Groves mechanisms are strategy-proof
[Roberts 1979]

A biased mechanism based on a weighted Groves mechanism

[Nisan & Ronen STOC 99]

- For each job j , **bias** the mechanism towards accepting one of the two agents i
 - For some $b > 1$, award job j to i if and only if $c_{ij} < bc_{(-i)j}$
 - If so, i gets payment $bc_{(-i)j}$
 - Otherwise, $-i$ gets payment c_{ij}/b
- Weighted Groves mechanism, so strategy-proof
- A randomized mechanism:
 - set $b = 4/3$,
 - for each job independently, randomly choose the agent to which the mechanism is biased
- Gives a $7/4$ approximation

Characterizing allocation rules that can be made incentive compatible

- We saw that we may be interested in choosing allocations that **do not maximize social welfare** (sum of utilities)
 - Different objectives (e.g., make-span)
 - Social welfare maximizing allocation may be computationally too hard to find
- Some (not all) allocation rules can be made incentive compatible with the right payment rule
- What are **necessary and sufficient** conditions on an allocation rule for this to be possible?

Weak monotonicity

[Bikhchandani et al. *Econometrica* 06]

- Consider the case of a single type reporting agent
 - Equivalently, fix the types of the other players
- $o(\theta)$ is the allocation chosen when the agent reports θ
- $u(\theta, o)$ is the agent's utility for allocation o given true type θ
- Rule $o(\cdot)$ is said to be **weakly monotone** if the following condition holds for every θ, θ' :
$$u(\theta, o(\theta)) - u(\theta, o(\theta')) \geq u(\theta', o(\theta)) - u(\theta', o(\theta'))$$
- In words: if there are no payments, then
 - the utility **loss** from misreporting θ' when the true type is θ
 - is at least as great as
 - the utility **gain** from misreporting θ when the true type is θ'

Necessity of weak monotonicity

- Suppose an allocation rule $o(\cdot)$, together with a payment rule $\pi(\cdot)$, incentivizes the agent to tell the truth
- Then, for any θ, θ' , the following must hold:
 - $u(\theta, o(\theta)) + \pi(\theta) - u(\theta, o(\theta')) - \pi(\theta') \geq 0$
 - $u(\theta', o(\theta')) + \pi(\theta') - u(\theta', o(\theta)) - \pi(\theta) \geq 0$
- Adding these two together gives
 - $u(\theta, o(\theta)) - u(\theta, o(\theta')) + u(\theta', o(\theta')) - u(\theta', o(\theta)) \geq 0$
- Equivalently
 - $u(\theta, o(\theta)) - u(\theta, o(\theta')) \geq u(\theta', o(\theta)) - u(\theta', o(\theta'))$
- But this is the weak monotonicity condition!

Sufficiency of weak monotonicity

- Suppose the agent has a partial order \geq over the allocations
- Here $o \geq o'$ indicates that the agent prefers o to o' for **every** type that she may have
 - E.g., in o , she is allocated a superset of what she is allocated in o' , and free disposal holds
- The set of types is said to be **rich** if every utility function consistent with \geq corresponds to some type
- **Theorem.** If preferences are rich, weak monotonicity is sufficient for incentive compatibility
 - I.e., for any weakly monotone allocation rule, a payment function making this rule incentive compatible exists
- With more restricted type spaces, weak monotonicity is not always sufficient