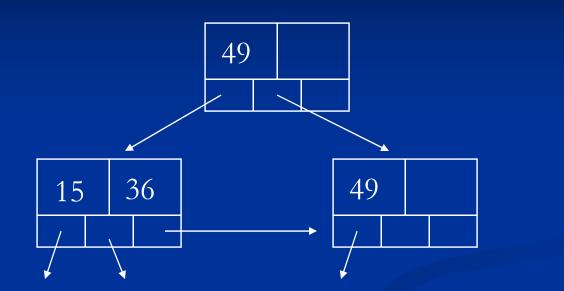
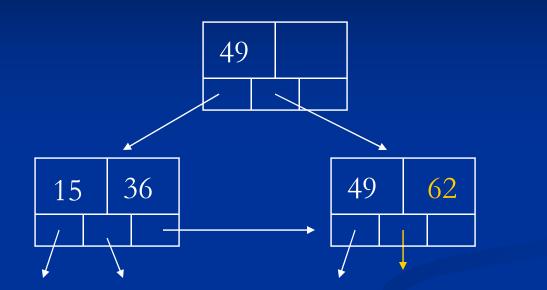
CPS216: Advanced Database Systems

Notes 06: Operators for Data Access (contd.) Shivnath Babu

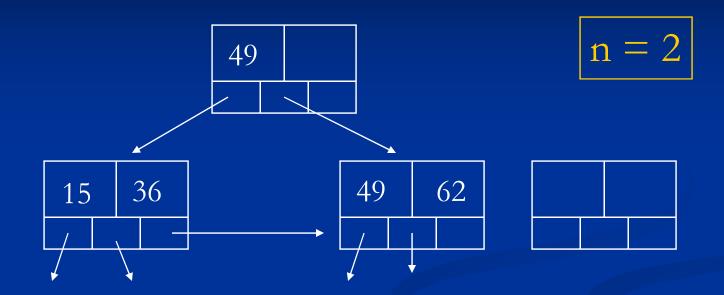


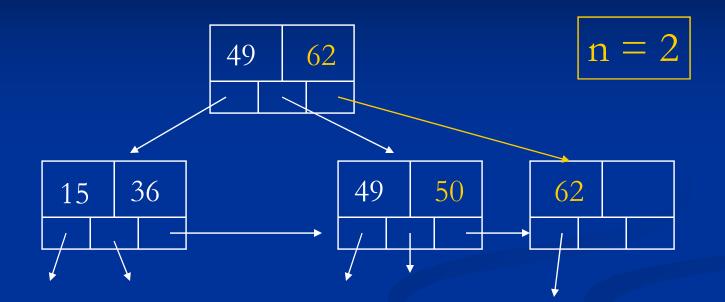
Insert: 62

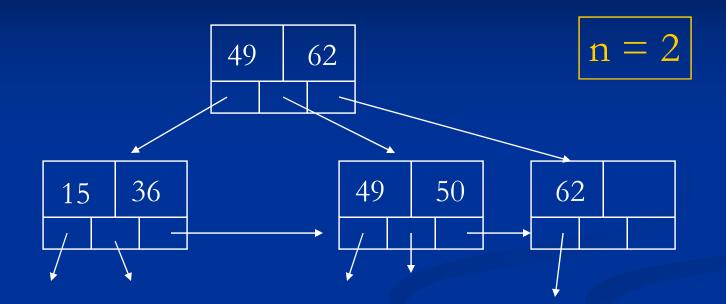
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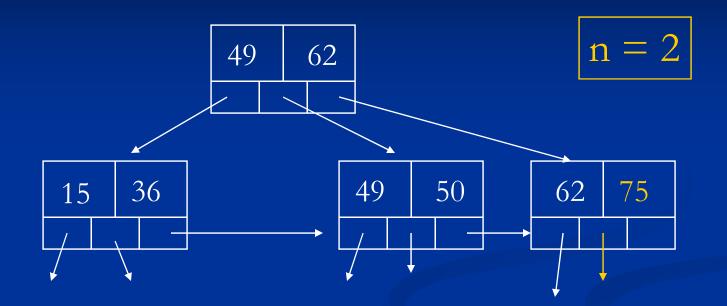


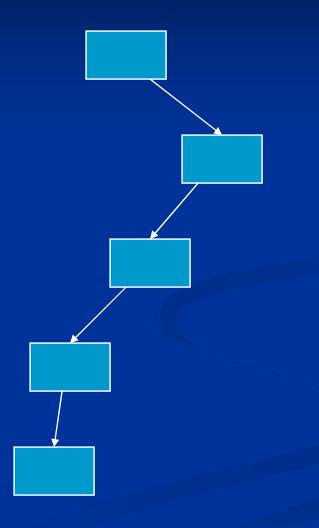
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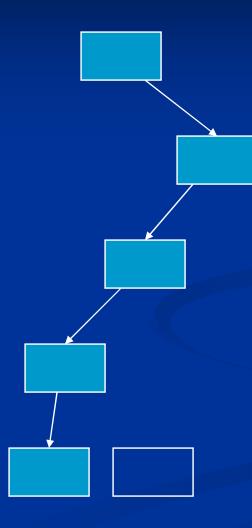


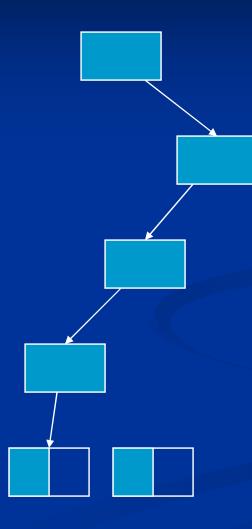


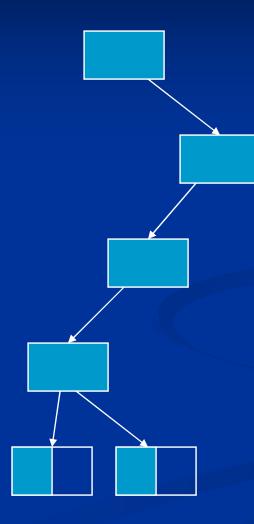


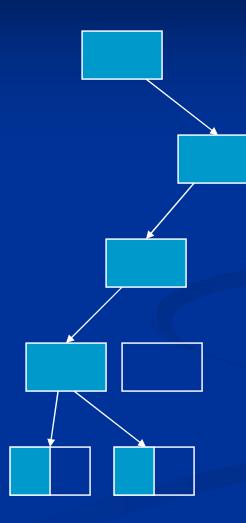




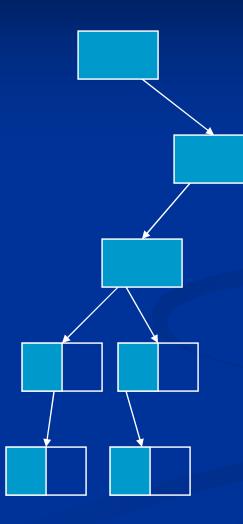


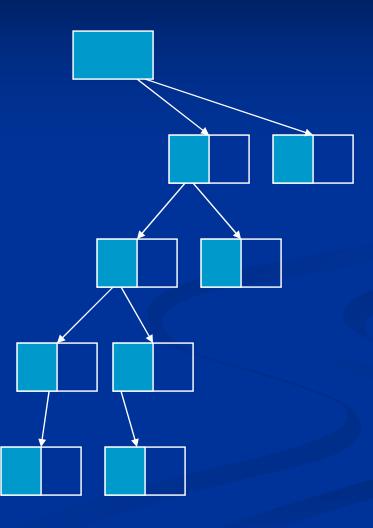


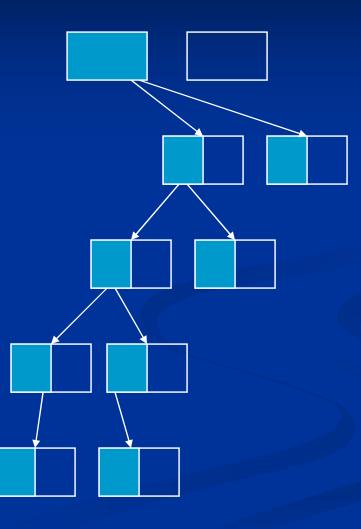


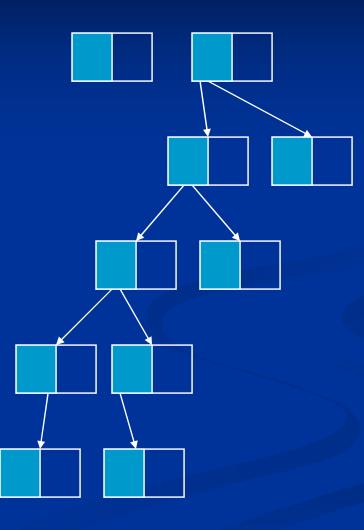


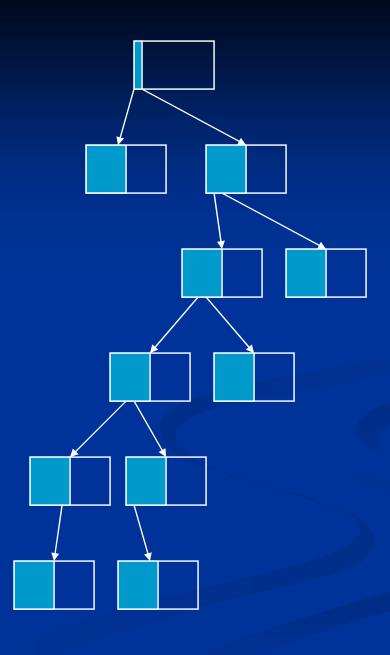










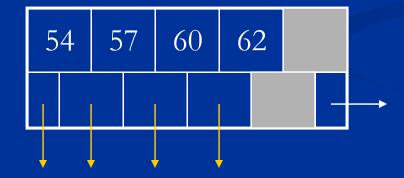


Insertion: Primitives

Inserting into a leaf node
Splitting a leaf node
Splitting an internal node
Splitting root node

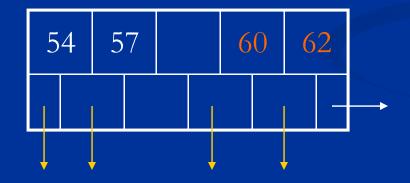
Inserting into a Leaf Node





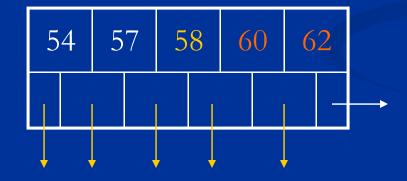
Inserting into a Leaf Node



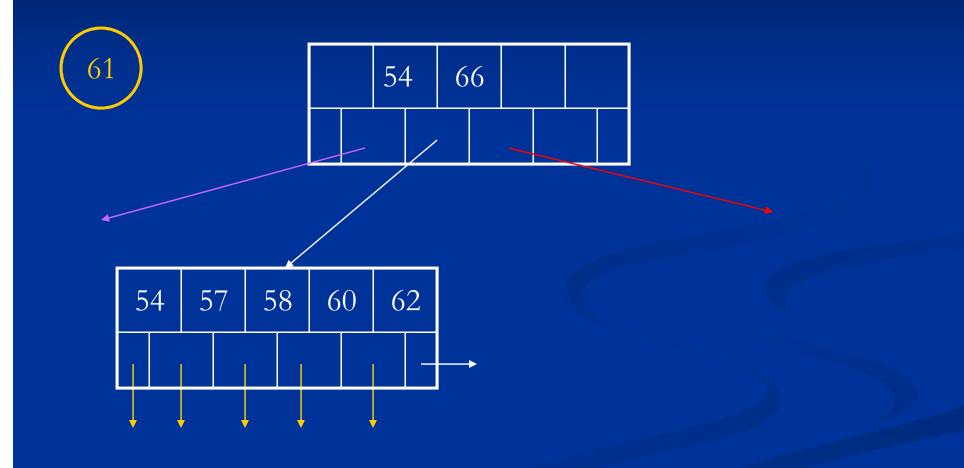


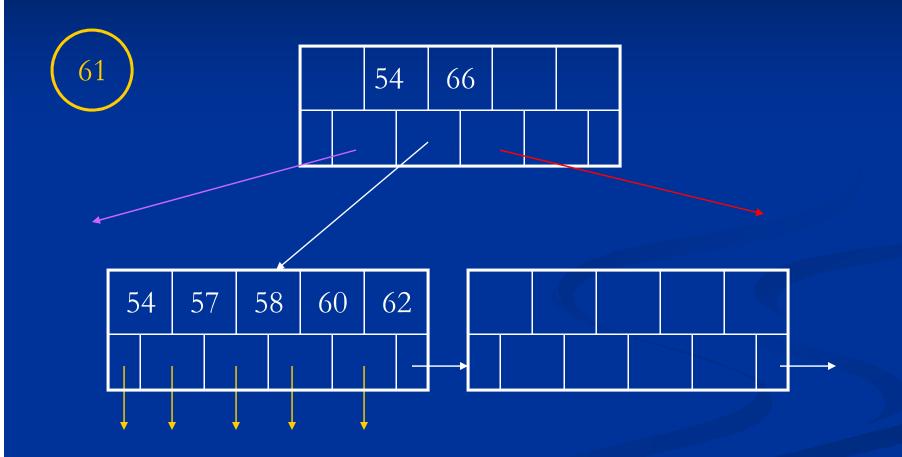
Inserting into a Leaf Node

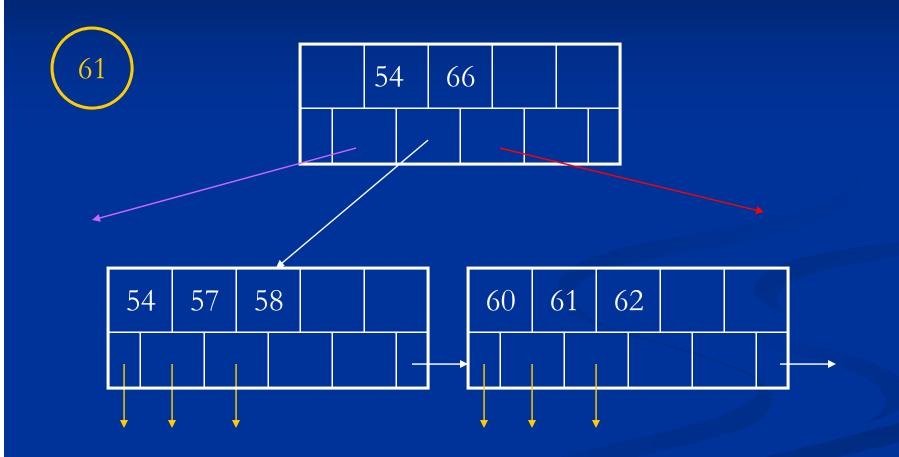


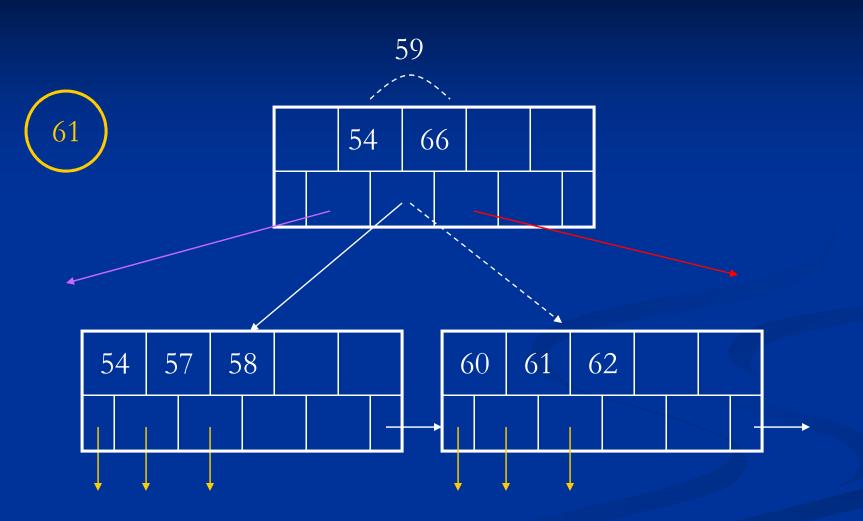


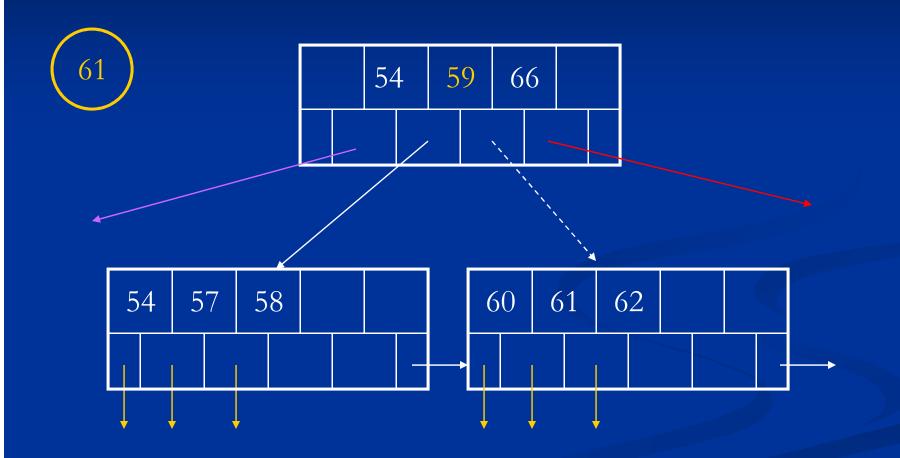
22



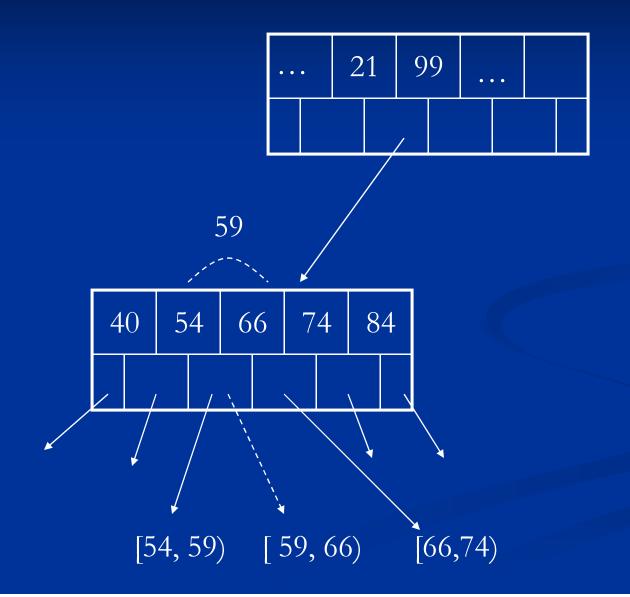




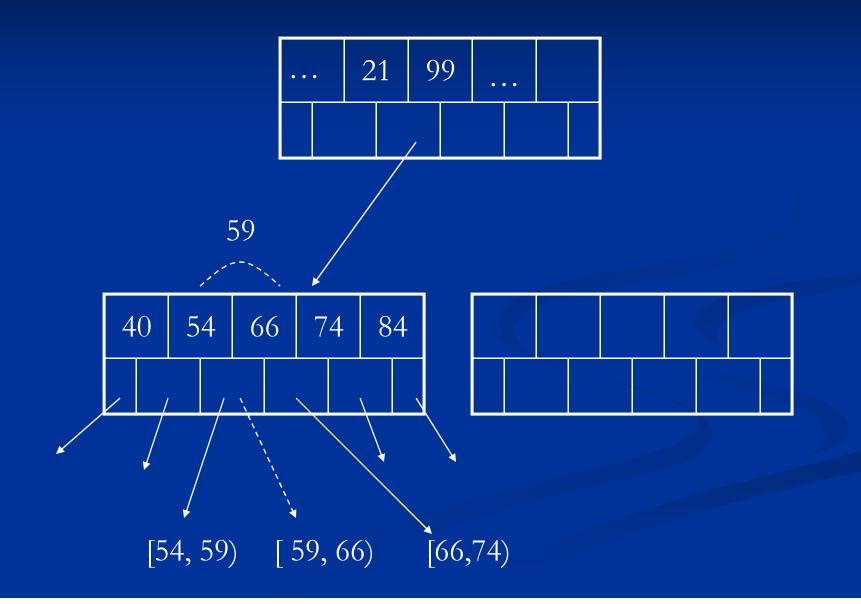


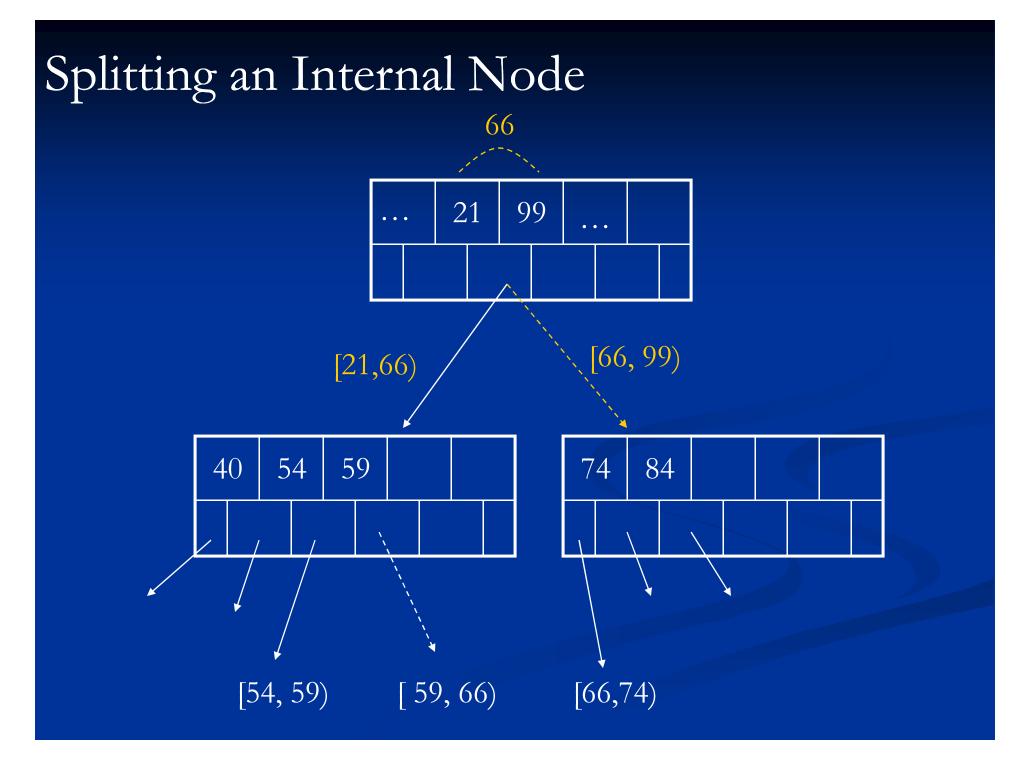


Splitting an Internal Node

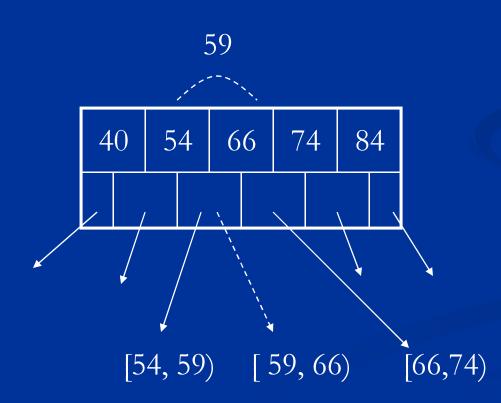


Splitting an Internal Node

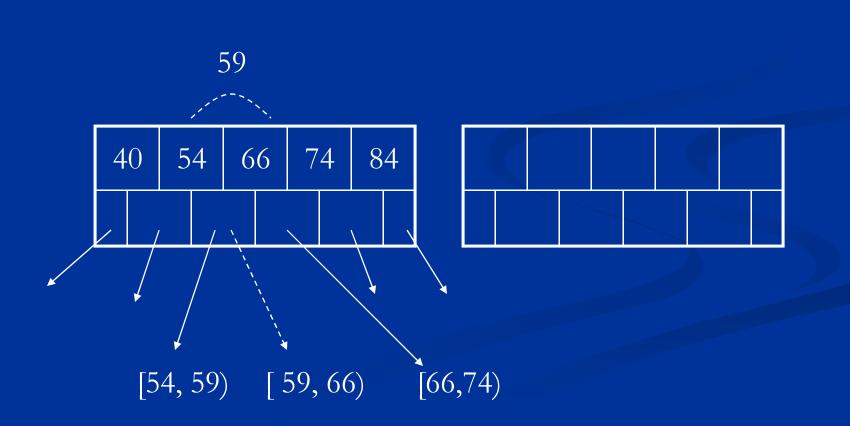




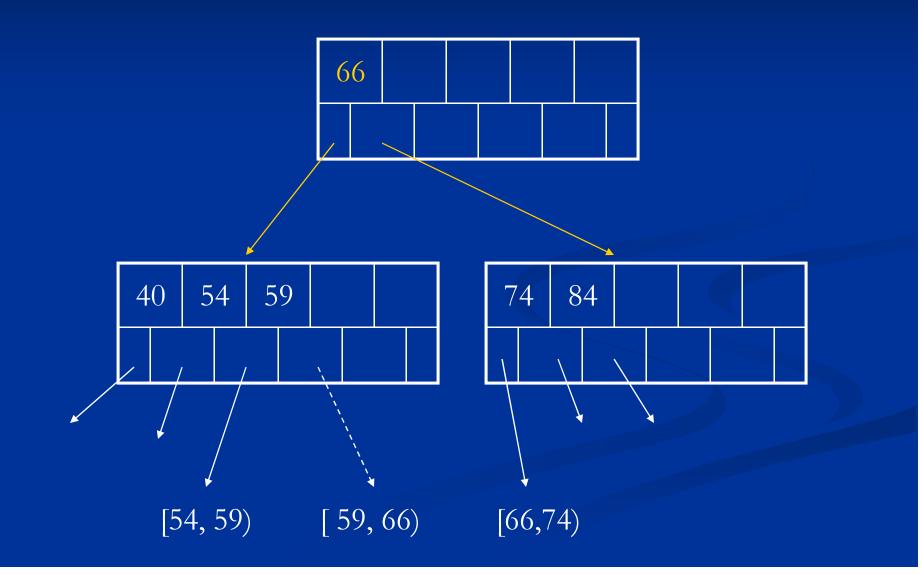
Splitting the Root



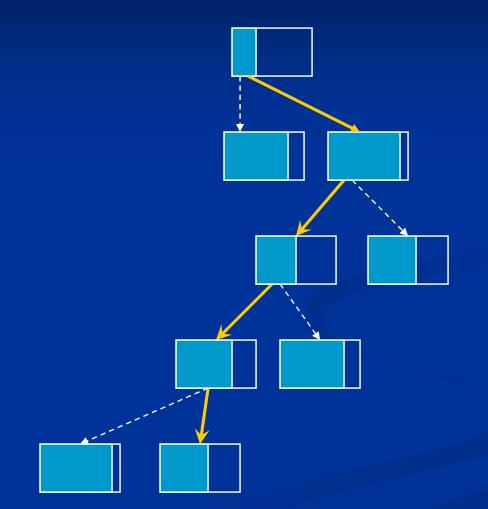
Splitting the Root



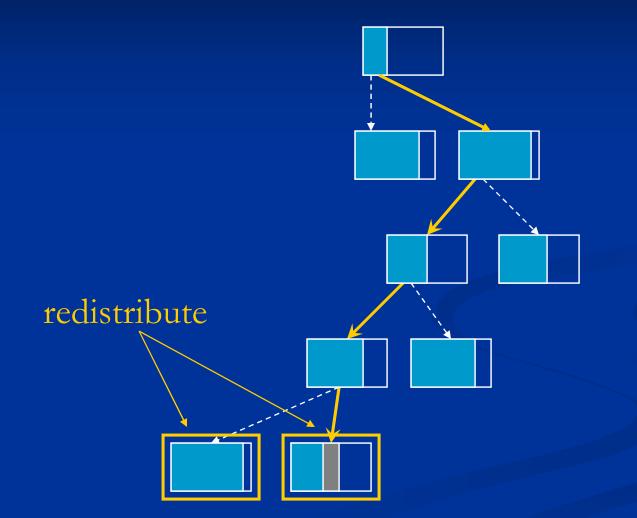
Splitting the Root



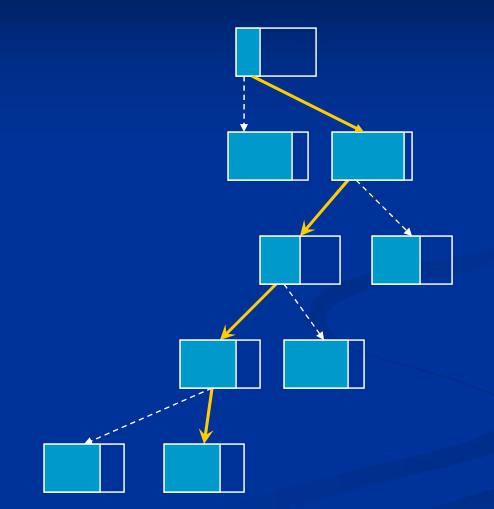
Deletion

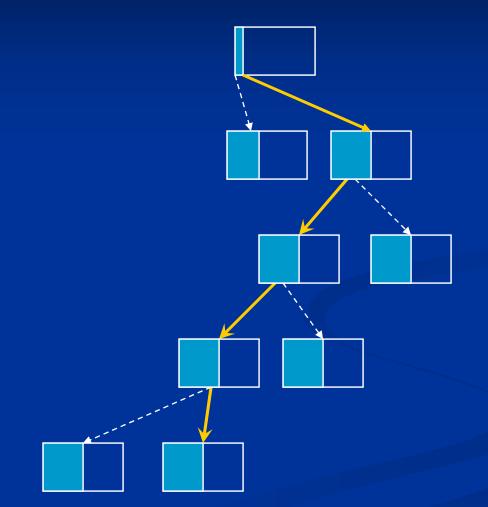


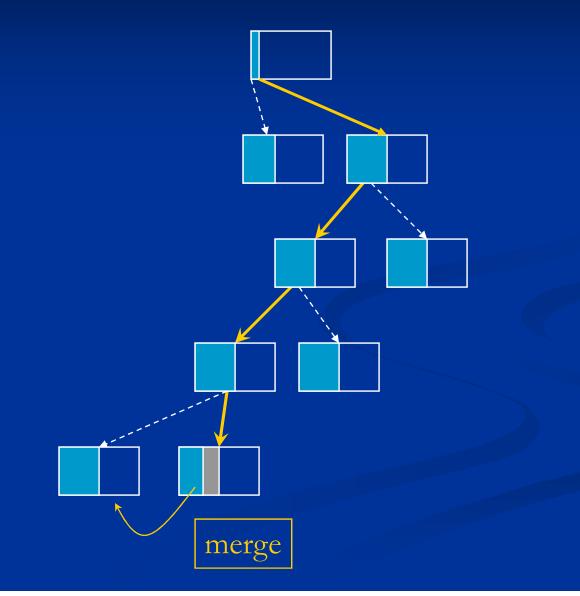
Deletion

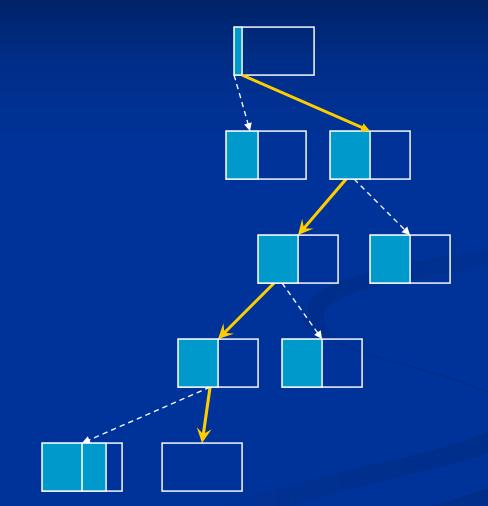


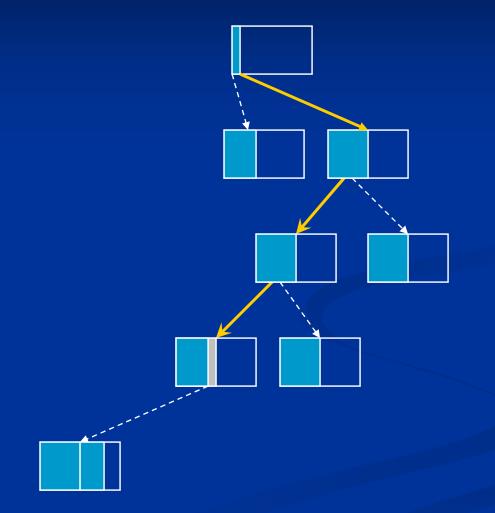
Deletion

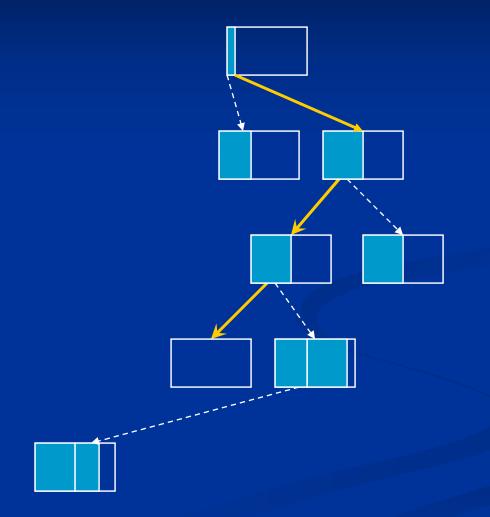


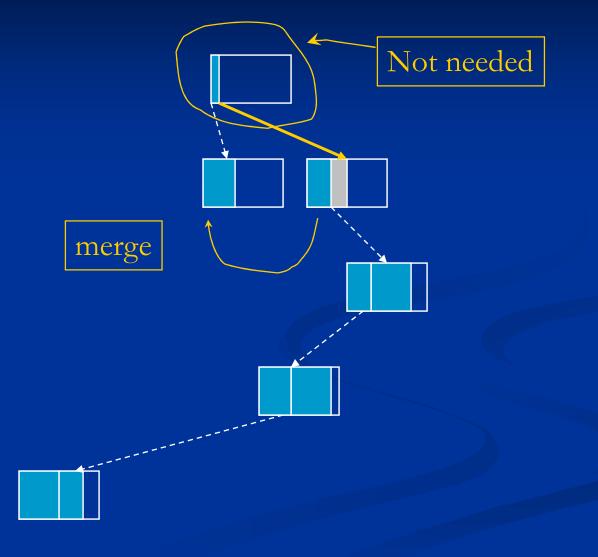


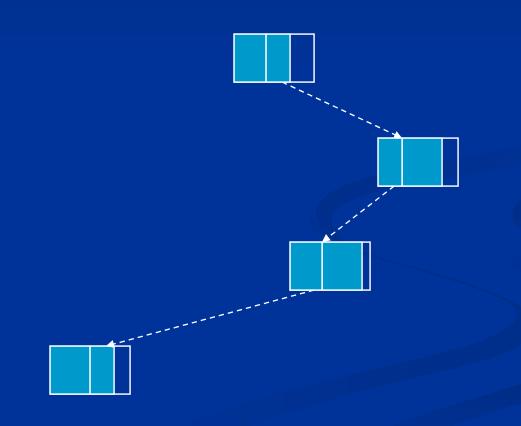






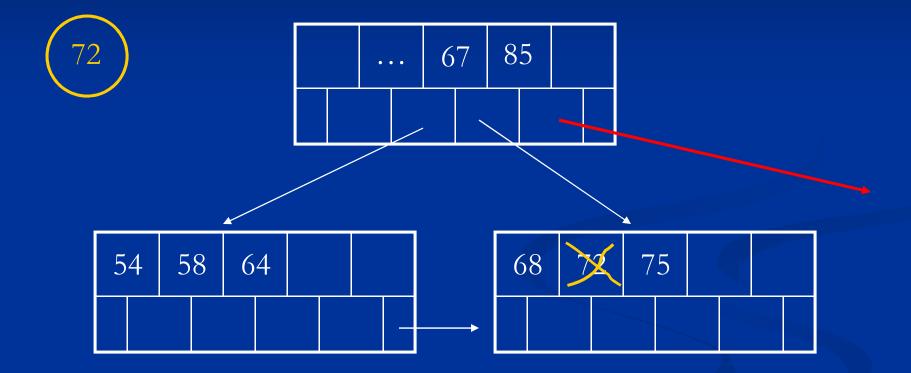


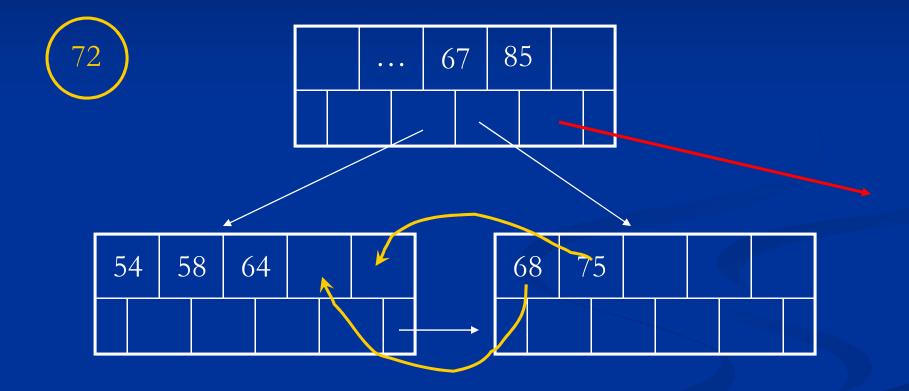


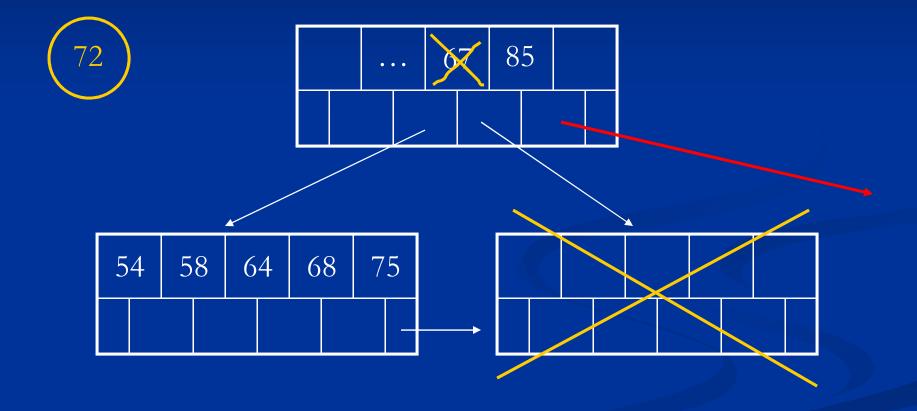


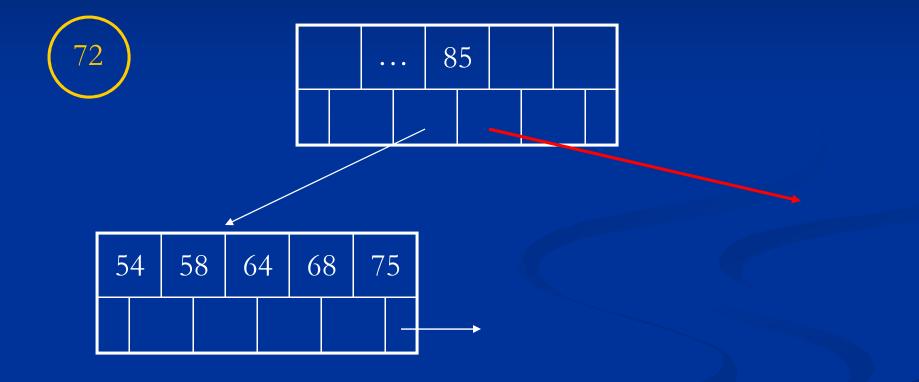
Deletion: Primitives

- Delete key from a leaf
 Redistribute keys between sibling leaves
 Merge a leaf into its sibling
 Redistribute keys between two sibling internal nodes
- ➡ Merge an internal node into its sibling

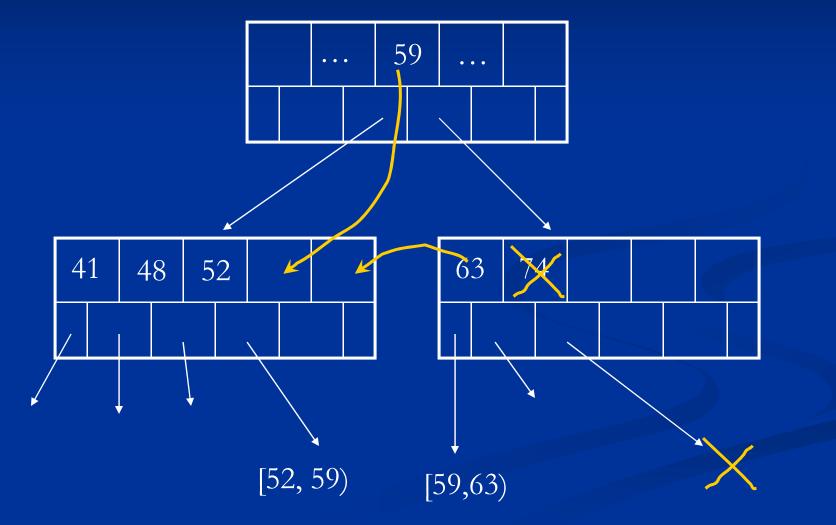




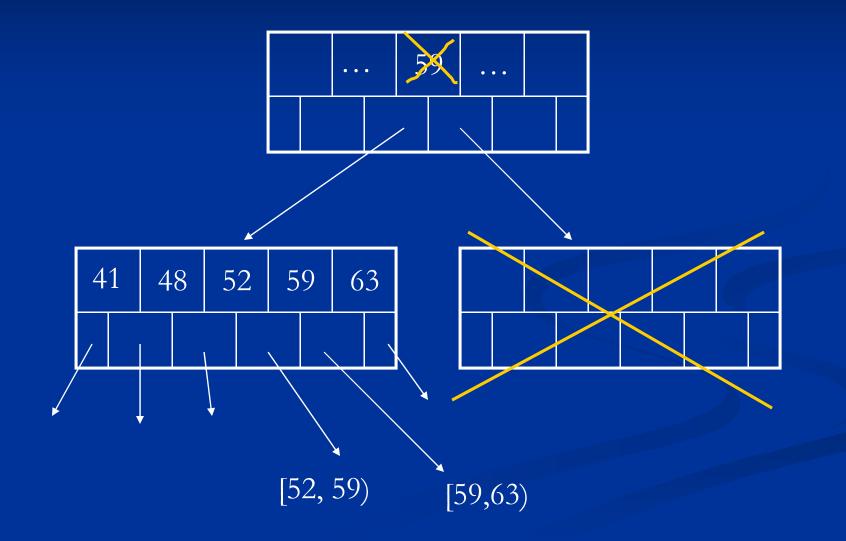




Merge Internal Node into Sibling



Merge Internal Node into Sibling



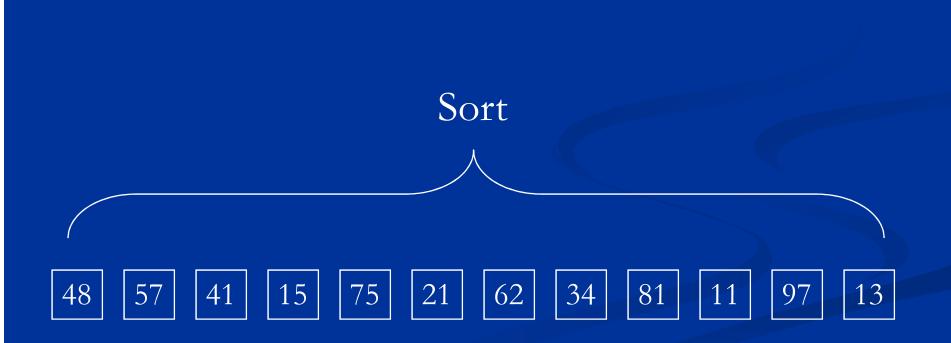
50

B-Tree Roadmap

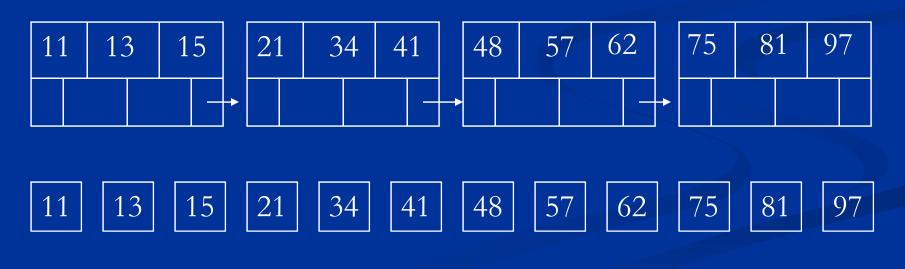
B-Tree ■ Recap ■ Insertion (recap) Deletion Construction Efficiency B-Tree variants Hash-based Indexes



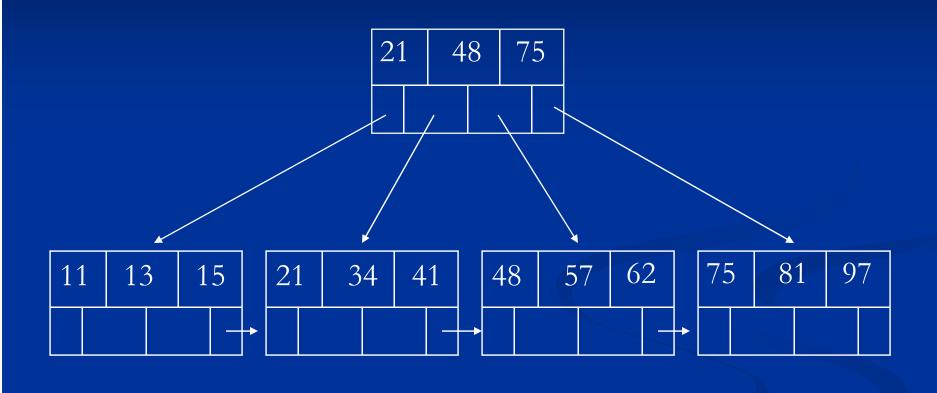
How does insertion-based construction perform?



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Scan



Scan

Why is sort-based construction better than insertion-based one?

Cost of B-Tree Operations

Height of B-Tree: H
Assume no duplicates
Question: what is the random I/O cost of:

Insertion:
Deletion:
Equality search:
Range Search:

Height of B-Tree

Number of keys: NB-Tree parameter: n

Height $\approx \log_n N = \frac{\log N}{\log n}$

In practice: 2-3 levels

Question: How do you pick parameter n?

Ignore inserts and deletes
 Optimize for equality searches
 Assume no duplicates

Roadmap

B-Tree
B-Tree variants
Sparse Index
Duplicate Keys
Hash-based Indexes

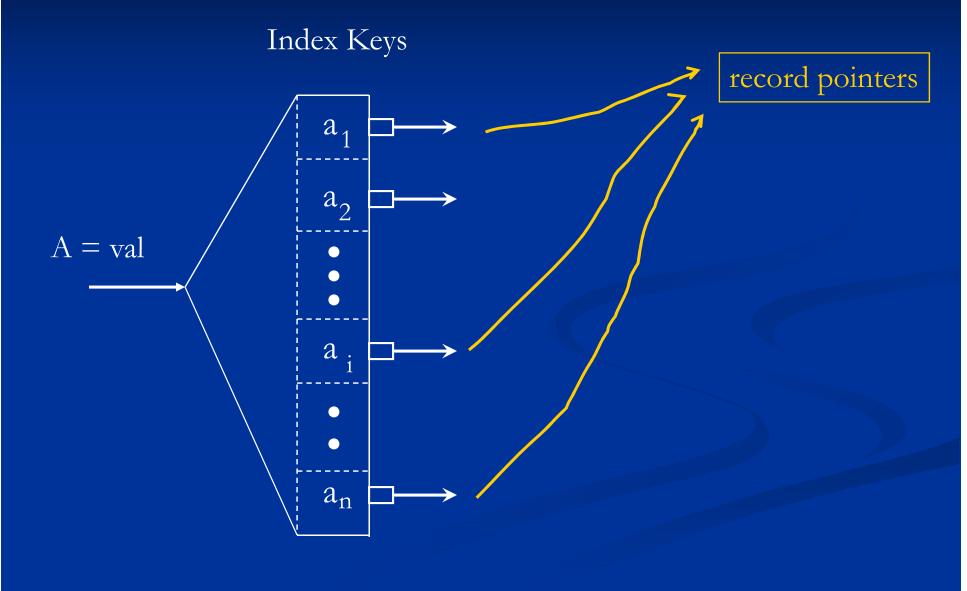
Roadmap

B-Tree
B-Tree variants
Hash-based Indexes
Static Hash Table
Extensible Hash Table
Linear Hash Table

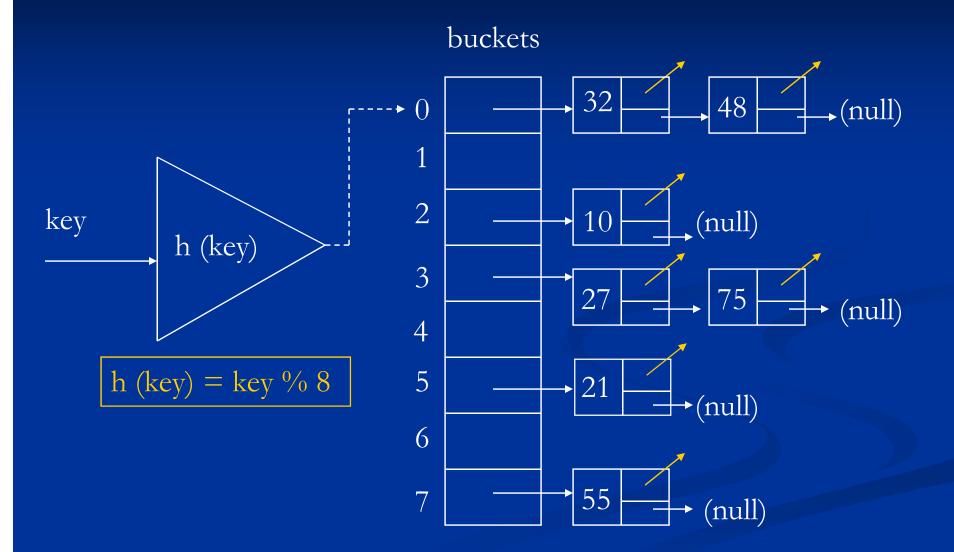
Hash-Based Indexes

Adaptations of main memory hash tables
Support equality searches
No range searches

Indexing Problem (recap)



Main Memory Hash Table



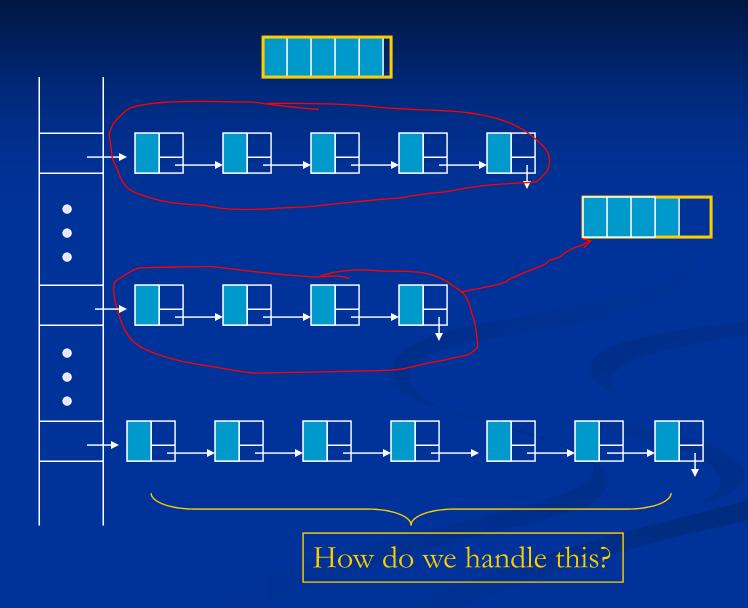
Adapting to disk

1 Hash Bucket = 1 Block

All keys that hash to bucket stored in the block

- Intuition: keys in a bucket usually accessed together
- No need for linked lists of keys ...

Adapting to Disk

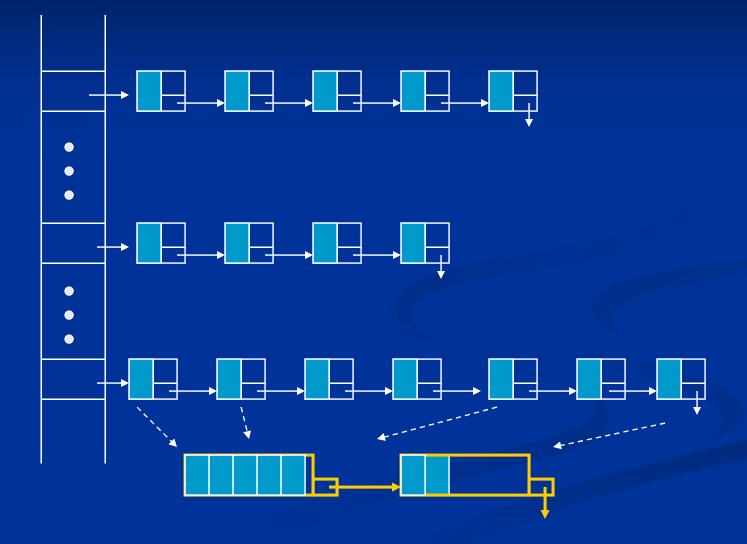


Adapting to disk

\blacksquare 1 Hash Bucket = 1 Block

- All keys that hash to bucket stored in the block
- Intuition: keys in a bucket usually accessed together
- No need for linked lists of keys ...
- In the second second

Adapting to Disk



Adapting to disk

Bucket Id → Disk Address mapping
 Contiguous blocks
 Store mapping in main memory
 Too large?
 Dynamic → Linear and Extensible hash tables

Beware of claims that assume 1 I/O for hash tables and 3 I/Os for B-Tree!!