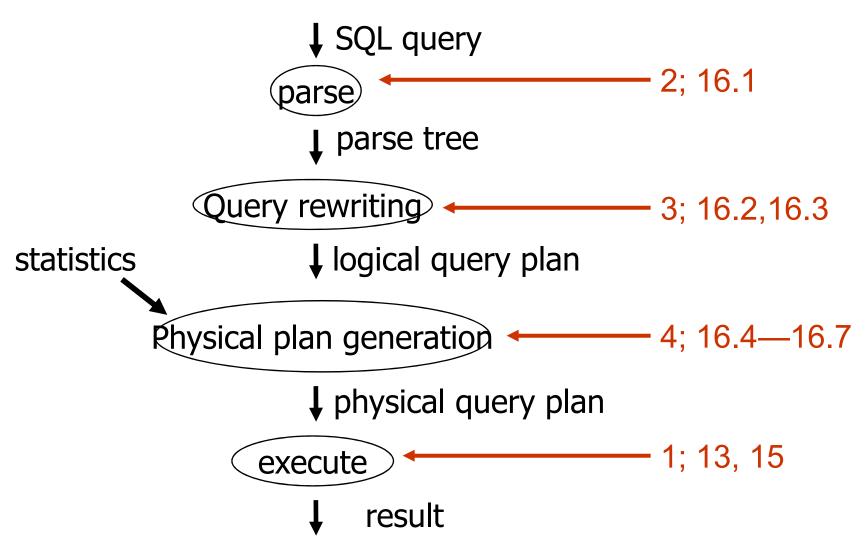
#### CPS216: Advanced Database Systems

## Notes 07:Query Execution (Sort and Join operators)

Shivnath Babu

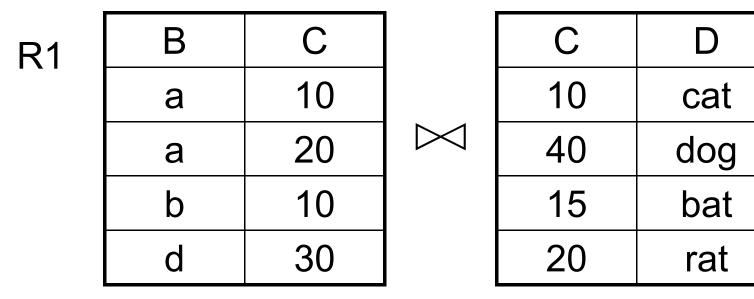
#### Query Processing - In class order



#### Roadmap

- A simple operator: Nested Loop Join
- Preliminaries
  - Cost model
  - Clustering
  - Operator classes
- Operator implementation (with examples from joins)
  - Scan-based
  - Sort-based
  - Using existing indexes
  - Hash-based
- Buffer Management
- Parallel Processing

#### Nested Loop Join (NLJ)



R2

NLJ (conceptually)
 for each r ∈ R1 do
 for each s ∈ R2 do
 if r.C = s.C then output r,s pair

#### Nested Loop Join (contd.)

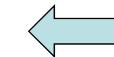
- Tuple-based
- Block-based
- Asymmetric

#### Implementing Operators

- Basic algorithm
  - Scan-based (e.g., NLJ)
  - Sort-based
  - Using existing indexes
  - Hash-based (building an index on the fly)
- Memory management
  - Tradeoff between memory and #IOs
- Parallel processing

#### Roadmap

- A simple operator: Nested Loop Join
- Preliminaries
  - Cost model
  - Clustering
  - Operator classes
- Operator implementation (with examples from joins)
  - Scan-based
  - Sort-based
  - Using existing indexes
  - Hash-based
- Buffer Management
- Parallel Processing



#### **Operator Cost Model**

- Simplest: Count # of disk blocks read and written during operator execution
- Extends to query plans
  - Cost of query plan = Sum of operator costs
- Caution: Ignoring CPU costs

#### <u>Assumptions</u>

- Single-processor-single-disk machine
   Will consider parallelism later
- Ignore cost of writing out result
  - Output size is independent of operator implementation
- Ignore # accesses to index blocks

#### Parameters used in Cost Model

B(R) = # blocks storing R tuples
T(R) = # tuples in R
V(R,A) = # distinct values of attr A in R
M = # memory blocks available

#### Roadmap

- A simple operator: Nested Loop Join
- Preliminaries
  - Cost model
  - Clustering <
  - Operator classes
- Operator implementation (with examples from joins)
  - Scan-based
  - Sort-based
  - Using existing indexes
  - Hash-based
- Buffer Management
- Parallel Processing

#### Notions of clustering

- Clustered file organization
   R1 R2 S1 S2
   R3 R4 S3 S4
- Clustered relation

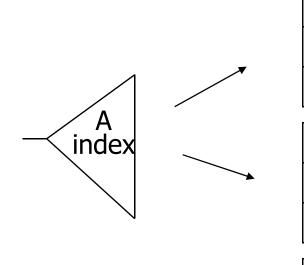
R1 R2 R3 R4

R5 R5 R7 R8

• Clustering index

#### **Clustering Index**

Tuples with a given value of the search key packed in as few blocks as possible



10	
10	
35	
19	
19	
19	
19	
42	

37

#### **Examples**

- T(R) = 10,000
- B(R) = 200
- If R is clustered, then # R tuples per block = 10,000/200 = 50
- Let V(R,A) = 40
- →If I is a clustering index on R.A, then # IOs to access  $\sigma_{R.A = "a"}(R) = 250/50 = 5$
- → If I is a non-clustering index on R.A, then # IOs to access  $\sigma_{R,A = "a"}(R) = 250 (> B(R))$

#### **Operator Classes**

	Tuple-at-a-time	Full-relation
Unary	Select	Sort
Binary		Difference

#### Roadmap

- A simple operator: Nested Loop Join
- Preliminaries
  - Cost model
  - Clustering
  - Operator classes
- Operator implementation (with examples from joins)
  - Scan-based
  - Sort-based
  - Using existing indexes
  - Hash-based
- Buffer Management
- Parallel Processing

#### Implementing Tuple-at-a-time Operators

- One pass algorithm:
  - Scan
  - Process tuples one by one
  - Write output
- Cost = B(R)
  - Remember: Cost = # IOs, and we ignore the cost to write output

#### Implementing a Full-Relation Operator, Ex: Sort

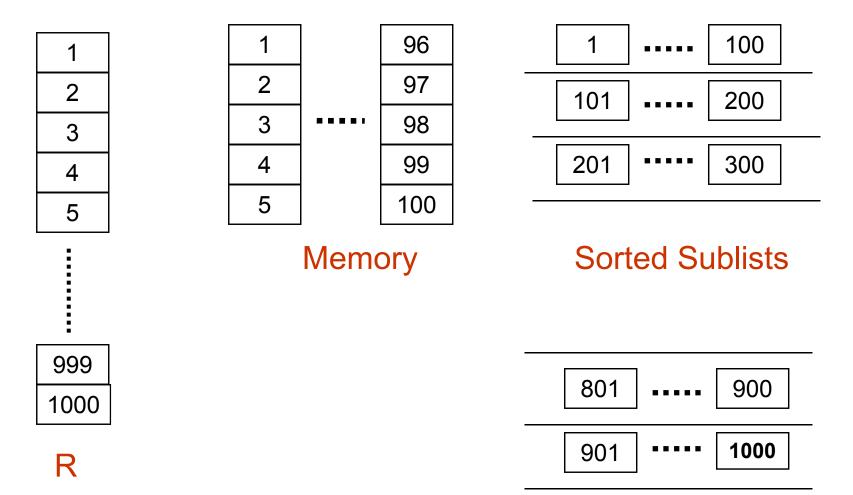
- Suppose T(R) x tupleSize(R) <= M x |B(R)|</li>
- Read R completely into memory
- Sort
- Write output
- Cost = B(R)

#### Implementing a Full-Relation Operator, Ex: Sort

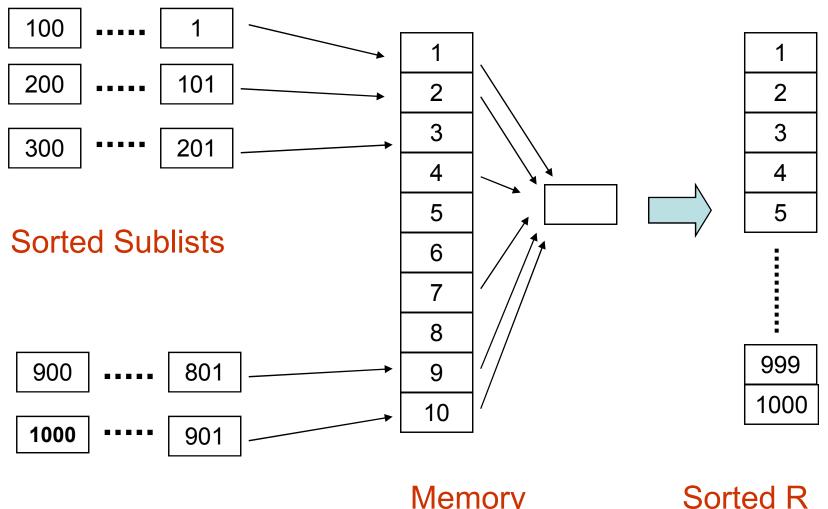
- Suppose R won't fit within M blocks
- Consider a two-pass algorithm for Sort; generalizes to a multi-pass algorithm
- Read R into memory in M-sized chunks
- Sort each chunk in memory and write out to disk as a sorted sublist
- Merge all sorted sublists
- Write output

#### Two-phase Sort: Phase 1

Suppose B(R) = 1000, R is clustered, and M = 100



#### Two-phase Sort: Phase 2



Memory

#### Analysis of Two-Phase Sort

- Cost = 3xB(R) if R is clustered, = B(R) + 2B(R') otherwise
- Memory requirement M >=  $B(R)^{1/2}$

#### **Duplicate Elimination**

- Suppose B(R) <= M and R is clustered
- Use an in-memory index structure
- Cost = B(R)
- Can we do with less memory?
  - $-B(\delta(R)) \le M$
  - Aggregation is similar to duplicate elimination

#### Duplicate Elimination Based on Sorting

- Sort, then eliminate duplicates
- Cost = Cost of sorting + B(R)
- Can we reduce cost?

- Eliminate duplicates during the merge phase

#### Back to Nested Loop Join (NLJ)

R

В	С		С	D	
а	10		10	cat	
а	20	$\boxtimes$	40	dog	
b	10		15	bat	
d	30		20	rat	

S

 NLJ (conceptually) for each r ∈ R do for each s ∈ S do if r.C = s.C then output r,s pair

#### Analysis of Tuple-based NLJ

- Cost with R as outer =  $T(R) + T(R) \times T(S)$
- Cost with S as outer =  $T(S) + T(R) \times T(S)$
- M >= 2

#### Block-based NLJ

- Suppose R is outer
  - Loop: Get the next M-1 R blocks into memory
    - Join these with each block of S
- B(R) + (B(R)/M-1) x B(S)
- What if S is outer?

 $-B(S) + (B(S)/M-1) \times B(R)$ 

#### Let us work out an NLJ Example

- Relations are <u>not</u> clustered
- T(R1) = 10,000 T(R2) = 5,000
   10 tuples/block for R1; and for R2
   M = 101 blocks

<u>Tuple-based NLJ Cost:</u> for each R1 tuple: [Read tuple + Read R2] Total =10,000 [1+5000]=50,010,000 IOs

### Can we do better when R,S are not clustered?

<u>Use our memory</u>

- (1) Read 100 blocks worth of R1 tuples
- (2) Read all of R2 (1 block at a time) + join
- (3) Repeat until done

# $\frac{\text{Cost:}}{\text{Read chunk:}} \text{ for each R1 chunk:} \\ \text{Read chunk: } 1000 \text{ IOs} \\ \text{Read R2:} \quad 5000 \text{ IOs} \\ \text{Total/chunk = } 6000 \\ \end{array}$

Total =  $\frac{10,000}{1,000}$  x 6000 = 60,000 IOs [Vs. 50,010,000!]

- Can we do better?
  - Reverse join order:  $R2 \bowtie R1$
  - Total =  $\frac{5000}{1000}$  x (1000 + 10,000) =

5 x 11,000 = 55,000 IOs [Vs. 60,000]

#### Example contd. NLJ R2 > R1

• Now suppose relations are clustered

# $\begin{array}{l} \underline{Cost} \\ \mbox{For each R2 chunk:} \\ \mbox{Read chunk: 100 IOs} \\ \mbox{Read R1:} & \underline{1000} IOs \\ \mbox{Total/chunk} = 1,100 \\ \mbox{Total} = 5 \mbox{chunks x 1,100} = 5,500 IOs \\ \mbox{[Vs. 55,000]} \end{array}$

#### Joins with Sorting

Sort-Merge Join (conceptually)
(1) if R1 and R2 not sorted, sort them
(2) i ← 1; j ← 1;
While (i ≤ T(R1)) ∧ (j ≤ T(R2)) do
if R1{ i }.C = R2{ j }.C then OutputTuples
else if R1{ i }.C > R2{ j }.C then j ← j+1
else if R1{ i }.C < R2{ j }.C then i ← i+1</li>

```
Procedure Output-Tuples

While (R1{ i }.C = R2{ j }.C) \land (i \leq T(R1)) do

[jj \leftarrow j;

while (R1{ i }.C = R2{ jj }.C) \land (jj \leq T(R2)) do

[output pair R1{ i }, R2{ jj };

jj \leftarrow jj+1 ]

i \leftarrow i+1 ]
```

#### **Example**

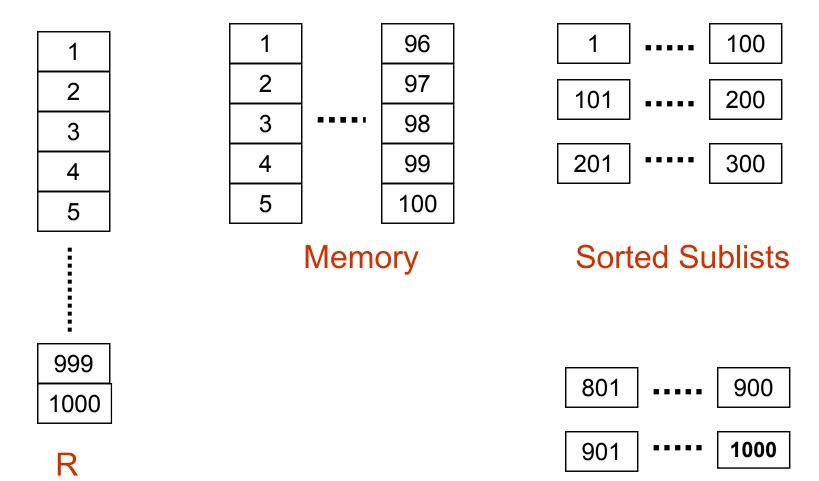
i	R1{i}.C	R2{j}.C	j
1	10	5	1
2	20	20	2
3	20	20	3
4	30	30	4
5	40	30	5
		50	6
		52	7

#### Block-based Sort-Merge Join

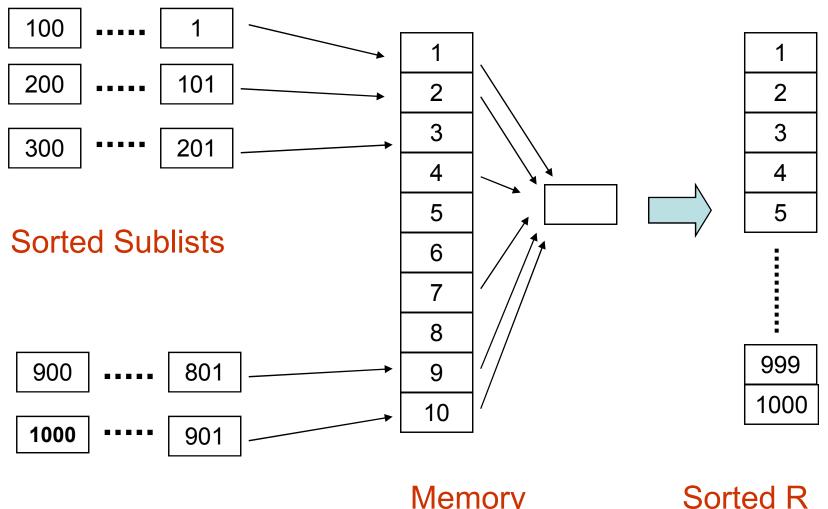
- Block-based sort
- Block-based merge

## Two-phase Sort: Phase 1

Suppose B(R) = 1000 and M = 100

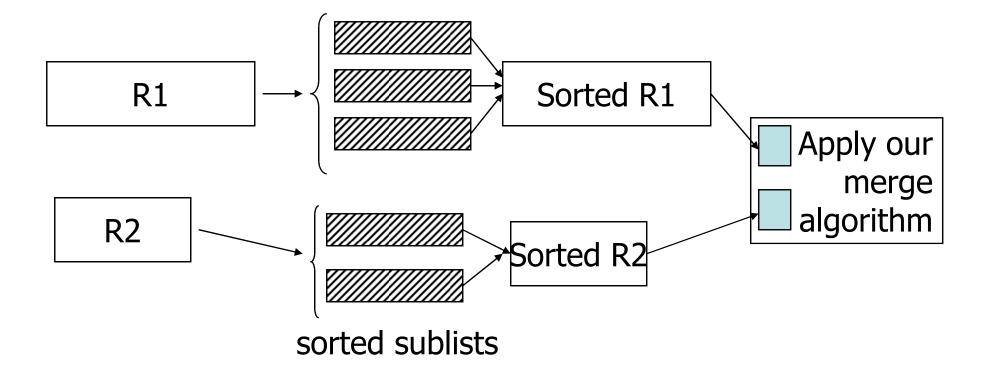


#### Two-phase Sort: Phase 2



Memory

Sort-Merge Join



## Analysis of Sort-Merge Join

- Cost = 5 x (B(R) + B(S))
- Memory requirement: M >= (max(B(R), B(S)))<sup>1/2</sup>

## Continuing with our Example

R1,R2 clustered, but unordered

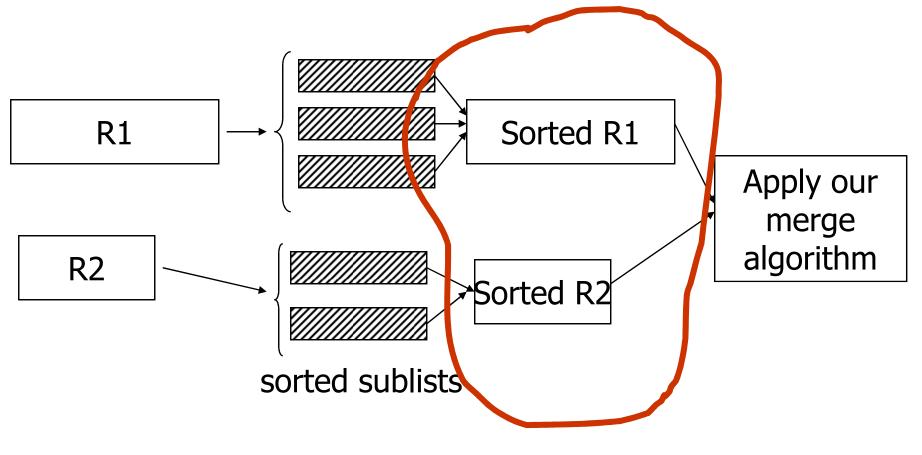
Total cost = sort cost + join cost = 6,000 + 1,500 = 7,500 IOs

<u>But:</u> NLJ cost = 5,500 So merge join does not pay off!

## However ...

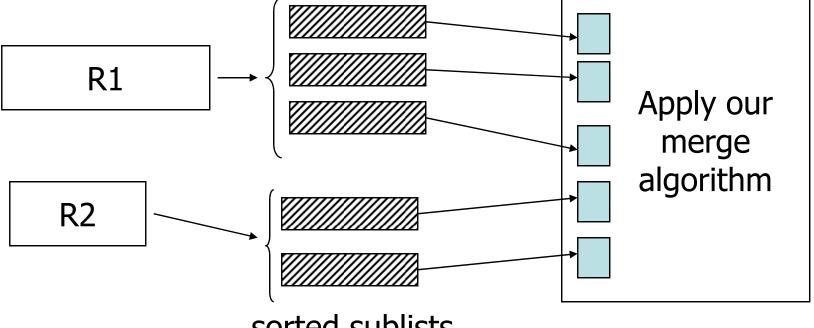
- NLJ cost = B(R) + B(R)B(S)/M-1 = O(B(R)B(S)) [Quadratic]
- Sort-merge join cost = 5 x (B(R) + B(S)) = O(B(R) + B(S)) [Linear]

#### Can we Improve Sort-Merge Join?



Do we need to create the sorted R1, R2?

#### A more "Efficient" Sort-Merge Join



sorted sublists

## Analysis of the "Efficient" Sort-Merge Join

- Cost = 3 x (B(R) + B(S))
   [Vs. 5 x (B(R) + B(S))]
- Memory requirement: M >= (B(R) + B(S))<sup>1/2</sup> [Vs. M >= (max(B(R), B(S)))<sup>1/2</sup>

Another catch with the more "Efficient" version: Higher chances of thrashing!

#### Cost of "Efficient" Sort-Merge join:

Cost = Read R1 + Write R1 into sublists + Read R2 + Write R2 into sublists + Read R1 and R2 sublists for Join = 2000 + 1000 + 1500 = 4500 [Vs. 7500]

#### Memory requirements in our Example

 $B(R1) = 1000 \text{ blocks}, 1000^{1/2} = 31.62$  $B(R2) = 500 \text{ blocks}, 500^{1/2} = 22.36$  $B(R1) + B(R2) = 1500, 1500^{1/2} = 38.7$ 

M > 32 buffers for simple sort-merge joinM > 39 buffers for efficient sort-merge join

## Joins Using Existing Indexes

Index I С С Β  $\square$ R on S.C 10 10 cat a 20 40 dog а 10 15 bat b 30 20 d rat

S

Indexed NLJ (conceptually)

for each r ∈ R do for each s ∈ S that matches probe(I,r.C) do output r,s pair

#### Continuing with our Running Example

- Assume R1.C index exists; 2 levels
- Assume R2 clustered, unordered
- Assume R1.C index fits in memory

#### Cost: R2 Reads: 500 IOs

for each R2 tuple:

- probe index free
- if match, read R1 tuple

→# R1 Reads depends on:

- # matching tuples
- clustering index or not

#### What is expected # of matching tuples?

(a) say R1.C is key, R2.C is foreign key then expected = 1 tuple

(b) say V(R1,C) = 5000, T(R1) = 10,000 with uniform assumption expect = 10,000/5,000 = 2

#### What is expected # of matching tuples?

(c) Say DOM(R1, C) = 1,000,000
T(R1) = 10,000
with assumption of uniform distribution
in domain

Expected = 
$$10,000$$
 = 1 tuples  
1,000,000 100

Total cost with Index Join with a Non-Clustering Index

(a) Total cost = 500+5000(1) = 5,500

(b) Total cost = 500+5000(2) = 10,500

(c) Total cost = 500+5000(1/100) = 550Will any of these change if we have a clustering index?

#### What if index does not fit in memory?

Example: say R1.C index is 201 blocks

- Keep root + 99 leaf nodes in memory
- Expected cost of each index access is  $E = (0)99 + (1)101 \approx 0.5$   $200 \qquad 200$

- = 500+2500+50 = 3050 IOs
- $= 500+5000[0.5 \times 1 + (1/100) \times 1]$
- For Case (c):
- = 500+12,500 = 13,000 (Case b)
- = 500+5000 [0.5+2]
- = 500+5000 [Probe + Get Records]

<u>Total cost</u> (including Index Probes)

## Block-Based NLJ Vs. Indexed NLJ

- Wrt #joining records
- Wrt index clustering

Join cost Plot graphs for Block NLJ and Indexed NLJ for clustering and non-clustering indexes

Join selectivity

## Sort-Merge Join with Indexes

- Can avoid sorting
- Zig-zag join

# not clustered

NLJ R2 R1 55,000 (best) Merge Join Sort+ Merge Join R1.C Index R2.C Index

clustered

NLJ R2 \R1 Merge join Sort+Merge Join R1.C Index R2.C Index

5500 1500 7500 → 4500 5500, 3050, 550

## Building Indexes on the fly for Joins

- Hash join (conceptual)
  - Hash function h, range  $1 \rightarrow k$
  - Buckets for R1: G1, G2, ... Gk
  - Buckets for R2: H1, H2, ... Hk

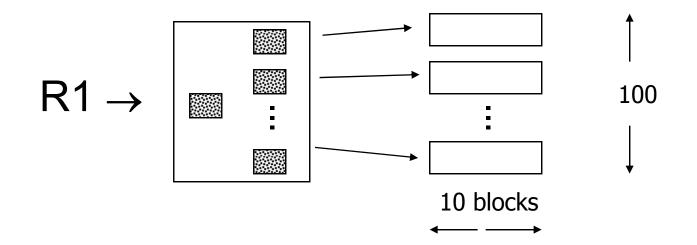
#### <u>Algorithm</u>

- (1) Hash R1 tuples into G1--Gk
- (2) Hash R2 tuples into H1--Hk
- (3) For i = 1 to k do

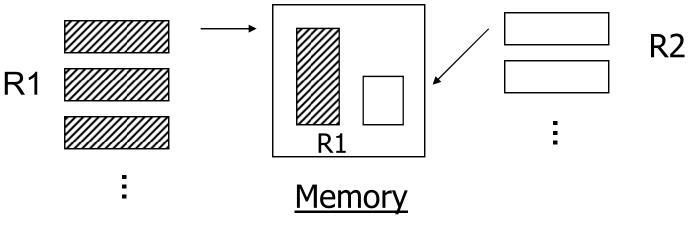
Match tuples in Gi, Hi buckets

#### Example Continued: Hash Join

- R1, R2 contiguous
   → Use 100 buckets
- $\rightarrow$  Read R1, hash, + write buckets



- -> Same for R2
- -> Read one R1 bucket; build memory hash table [R1 is called the build relation of the hash join]
- -> Read corresponding R2 bucket + hash probe [R2 is called the probe relation of the hash join]



Then repeat for all buckets

## <u>Cost:</u> "Bucketize:" Read R1 + write Read R2 + write Join: Read R1, R2

#### Total cost = $3 \times [1000+500] = 4500$

#### Minimum Memory Requirements

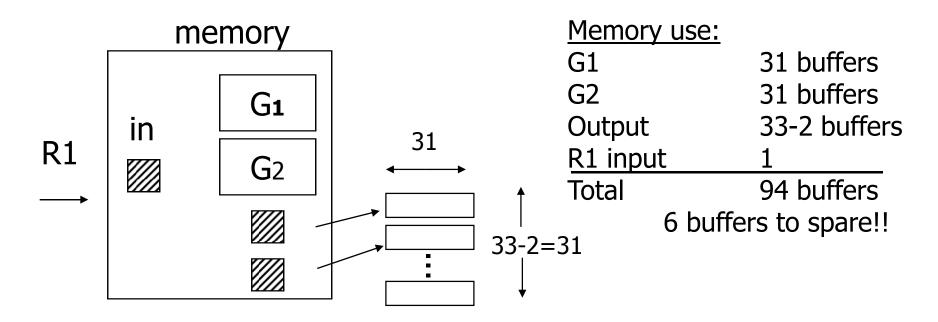
#### Size of R1 bucket = (x/k) k = number of buckets (k = M-1) x = number of R1 blocks

So... 
$$(x/k) \le k \Rightarrow k \ge \sqrt{x} \Rightarrow M > \sqrt{x}$$

Actually, M >  $\sqrt{\min(B(R),B(S))}$ [Vs. M >  $\sqrt{B(R)+B(S)}$  for Sort-Merge Join]

#### Trick: keep some buckets in memory

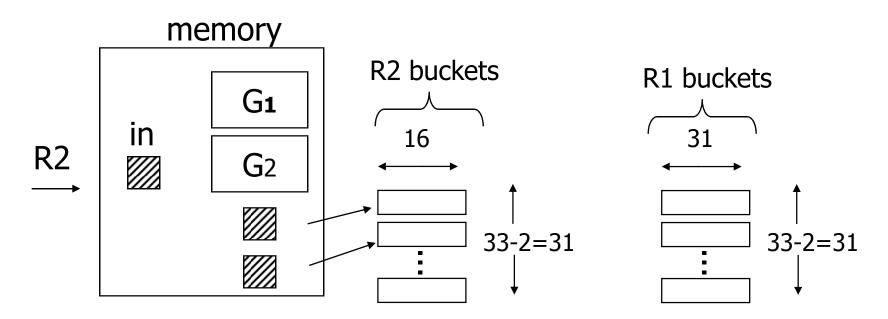
## E.g., k'=33 R1 buckets = 31 blocks keep 2 in memory



called Hybrid Hash-Join

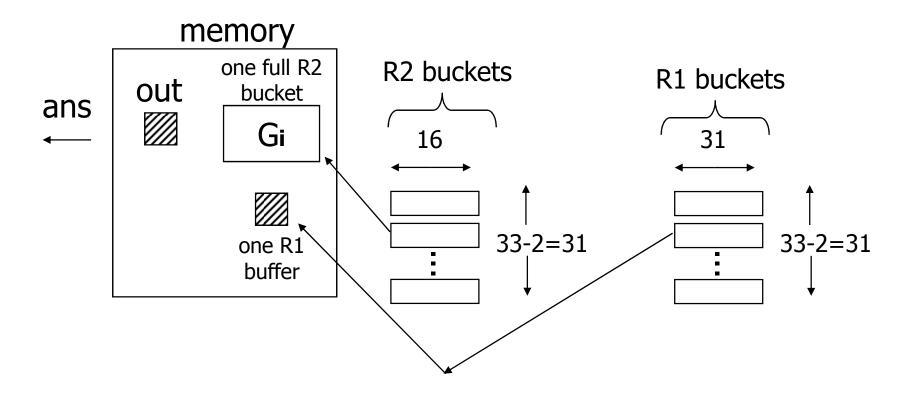
#### Next: Bucketize R2

- R2 buckets =500/33= 16 blocks
- Two of the R2 buckets joined immediately with G1,G2



#### Finally: Join remaining buckets

- for each bucket pair:
  - read one of the buckets into memory
  - join with second bucket

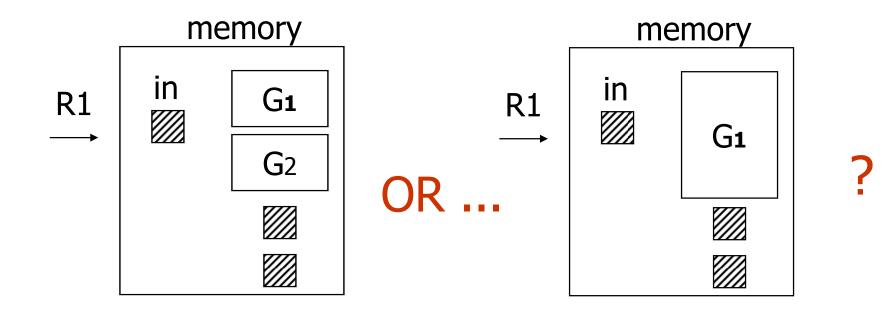


#### <u>Cost</u>

- Bucketize R1 = 1000+31×31=1961
- To bucketize R2, only write 31 buckets: so, cost = 500+31×16=996
- To compare join (2 buckets already done) read 31×31+31×16=1457

<u>Total cost</u> = 1961+996+1457 = 4414

#### How many Buckets in Memory?



See textbook for an interesting answer ...

## Another hash join trick:

- Only write into buckets <val,ptr> pairs
- When we get a match in join phase, must fetch tuples

- To illustrate cost computation, assume:
  - 100 <val,ptr> pairs/block
  - expected number of result tuples is 100
- Build hash table for R2 in memory 5000 tuples  $\rightarrow$  5000/100 = 50 blocks
- Read R1 and match
- Read ~ 100 R2 tuples

<u>Total cost</u> =	Read R2:	500
	Read R1:	1000
	Get tuples:	100
	-	1600

## So far:

clustered

NLJ Merge join Sort+merge joint R1.C index R2.C index Build R.C index Build S.C index Hash join with trick, R1 first with trick, R2 first Hash join, pointers

1600

## Hash-based Vs. Sort-based Joins

- Some similarities (see textbook), some dissimilarities
- Non-equi joins
- Memory requirement
- Sort order may be useful later

#### <u>Summary</u>

- NLJ ok for "small" relations (relative to memory size)
- For equi-join, where relations not sorted and no indexes exist, <u>Hybrid Hash Join</u> usually best

## Summary (contd.)

- Sort-Merge Join good for non-equi-join (e.g., R1.C > R2.C)
- If relations already sorted, use
   Merge Join
- If index exists, it <u>could</u> be useful
  - Depends on expected result size and index clustering
- Join techniques apply to Union, Intersection, Difference

## **Buffer Management**

- DBMS Buffer Manager Buffer Manager Block read/write
- May control memory directly (i.e., does not allocate from virtual memory controlled by OS)

## **Buffer Replacement Policies**

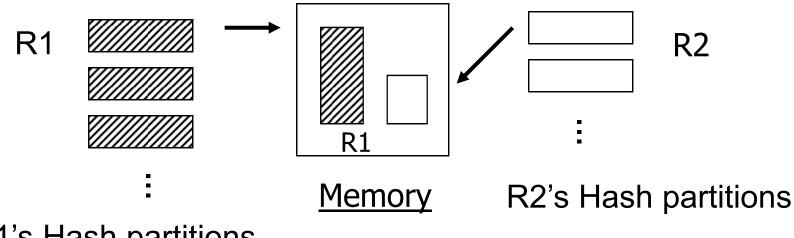
- Least Recently Used (LRU)
- Second-chance
- Most Recently Used (MRU)
- FIFO

## Interaction between Operators and Buffer Management

- Memory (our M parameter) may change while an operator is running
- Some operators can take advantage of specific buffer replacement policies
  - -E.g., Rocking for Block-based NLJ

#### Join Strategies for Parallel Processors

- May cover later if time permits
- We will see one example: Hash Join



R1's Hash partitions

## **Textbook Material**

All of Chapter 15 except 15.8
 – 15.8 covers multi-pass sort and hash

## Roadmap

- A simple operator: Nested Loop Join
- Preliminaries
  - Cost model
  - Clustering
  - Operator classes
- Operator implementation (with examples from joins)
  - Scan-based
  - Sort-based
  - Using existing indexes
  - Hash-based
- Buffer Management
- Parallel Processing