

- Graphs and Representations
- Depth First Search
- Breadth First Search

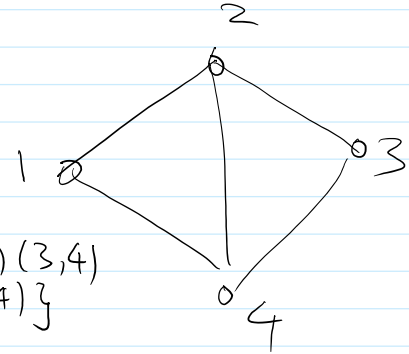
- Graph

- a set of nodes (vertices) connected by edges

- (V, E) $V = \{1, 2, \dots, n\}$

edge (i, j)

$$E = \{(1,2), (2,3), (3,4), (4,1), (2,4)\}$$

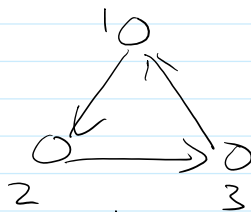


- abstraction

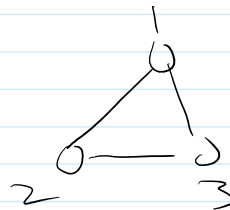
- Examples

1. road network
2. supplies network
3. social network (edges = friends)
4. dependency network (COMPSCI 201 \rightarrow 330)
5. internet (edges = hyperlinks)

- directed and undirected graph



directed



undirected

- graph problems

1. shortest path
2. minimum spanning tree
3. community detection
4. scheduling
5. pagerank

- represent (store) a graph

- adjacency array

$A[1..n, 1..n]$

$A[i, j] = 1$ if (i, j) is an edge

$= 0$ if (i, j) is not an edge.

benefit: simple, quickly know whether $(i,j) \in E$

but: take $\Theta(n^2)$ space

- adjacency list

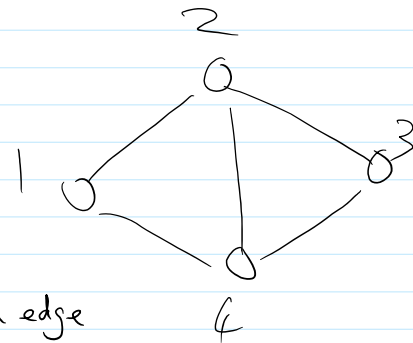
Store a list for every vertex
list i contains set of edges from vertex i

1: [2,4] 2: [1,3,4]

3: [2,4] 4: [1,2,3]

benefit: take $\Theta(m)$ space

But: hard to know whether (i,j) is an edge



- Basic Graph algorithms

- Graph traversal: want to visit all nodes of graph G by

- DFS (Depth First Search) following edges.

DFS

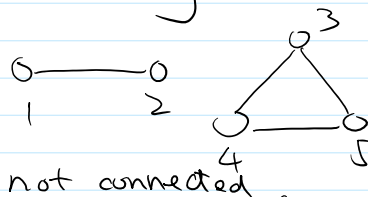
for $i = 1$ to n
if i is not visited
DFS_visit(i)

DFS_visit(i)

mark i as visited
for each edge (i,j)
if j is not visited
DFS_visit(j)

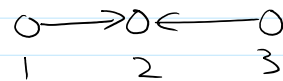
- why do we need this loop?

- Connectivity



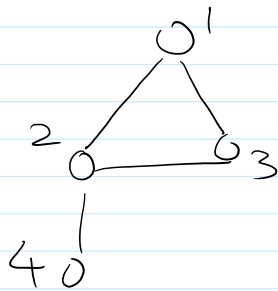
(Undirected Graph is connected if $\forall i,j$, there is a path from i to j)

- directed

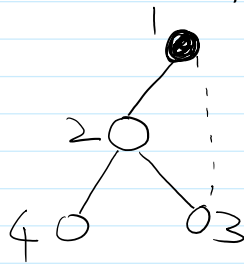


- Depth First Search Tree

- j is a child of i , if DFS_visit(i) called DFS_visit(j)



DFS: $0 \rightarrow 0 \rightarrow 0 \rightarrow 0 \rightarrow 0$
 1 2 3 2 4

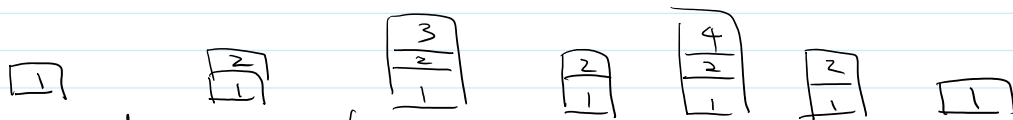


- Pre-order and post-order

Pre-order: order of visits (1, 2, 3, 4)

Post-order: order of DFS_visit(i) returns (3, 4, 2, 1)

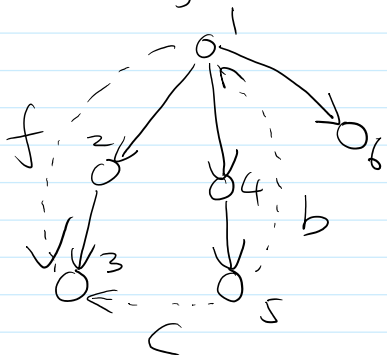
- DFS and stack



Preorder: order of entering the stack

Post-order: order of exiting the stack

- edge types



tree edge

f: forward edge

b: backward edge

c: Cross edge

- BFS (Breadth First Search)

BFS_visit(i)

put i into a queue (mark i as visited)

while queue is not empty

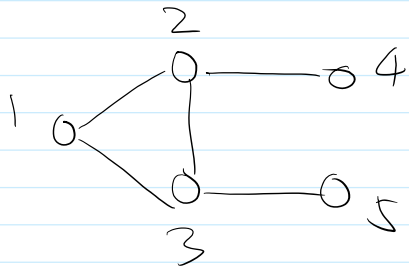
u ← dequeue

for each edge (u, v)

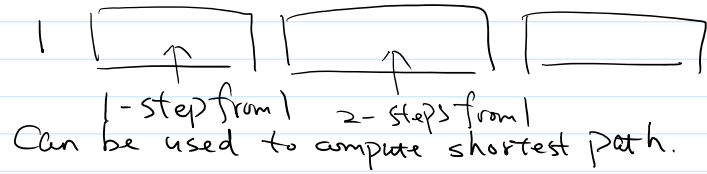
if v is not visited

put v into the queue

mark v as visited.

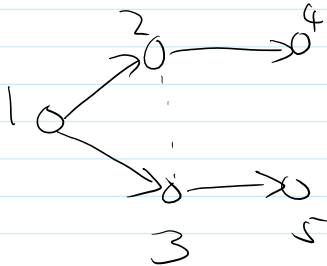


queue 1 2 3 4 5
 BFS order: order of entering the queue



BFS tree

v is a child of u , if v is added to the queue when processing u



(shortest path tree)