

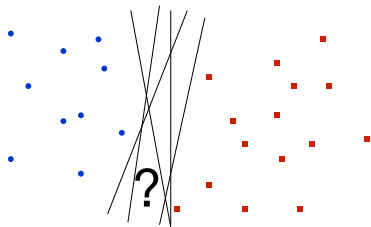
# Linear, Binary SVM Classifiers

COMPSCI 371D — Machine Learning

# Outline

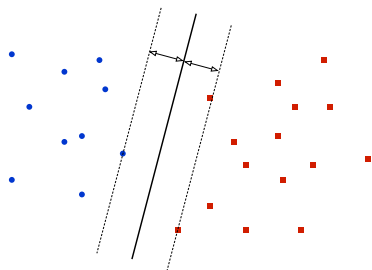
- 1 What Linear, Binary SVM Classifiers Do
- 2 Margin
- 3 Loss and Regularized Risk
- 4 Training an SVM

# The Separable Case



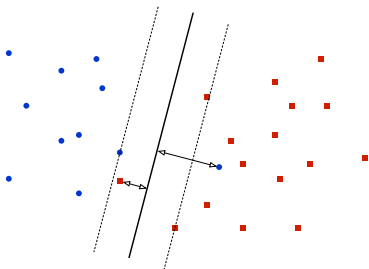
- Where to place the boundary?
- The number of degrees of freedom grows with  $d$

# SVMs Maximize the Smallest *Margin*



- Placing the boundary as far as possible from the nearest samples improves generalization
- Leave as much empty space around the boundary as possible
- Only the points that barely make the margin matter
- These are the *support vectors*
- Initially, we don't know which points will be support vectors

# The General Case: Soft SVMs



- If the data is not linearly separable, there *must* be misclassified samples. These have a negative margin
- Assign a penalty that penalizes a narrow band around the boundary *and* the number of samples that fall into it or on the incorrect side of the boundary
- Give different weights to the two penalties (cross-validation!)
- Find the optimal compromise: minimum risk (total penalty)

# Separating Hyperplane

- $X = \mathbb{R}^d$  and  $Y = \{-1, 1\}$   
(more convenient labels than  $\{0, 1\}$ )
- Hyperplane:  $\mathbf{n}^T \mathbf{x} + c = 0$  with  $\|\mathbf{n}\| = 1$
- Decision rule:  $\hat{y} = h(\mathbf{x}) = \text{sign}(\mathbf{n}^T \mathbf{x} + c)$
- $\mathbf{n}$  points towards the  $\hat{y} = 1$  half-space
- If  $y$  is the true label, decision is correct if
 
$$\begin{cases} \mathbf{n}^T \mathbf{x} + c \geq 0 & \text{if } y = 1 \\ \mathbf{n}^T \mathbf{x} + c \leq 0 & \text{if } y = -1 \end{cases}$$
- More compactly,  
decision is correct if  $y(\mathbf{n}^T \mathbf{x} + c) \geq 0$
- SVMs want this inequality to hold with a *margin*

# Margin

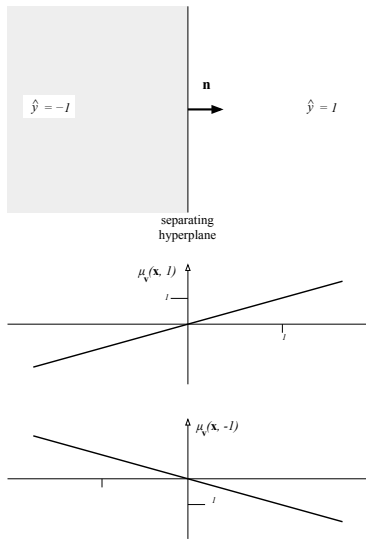
- The margin of  $(\mathbf{x}, y)$  is the signed distance of  $\mathbf{x}$  from the boundary: Positive if  $\mathbf{x}$  is on the correct side of the boundary, negative otherwise

$$\mu_{\mathbf{v}}(\mathbf{x}, y) \stackrel{\text{def}}{=} y(\mathbf{n}^T \mathbf{x} + c)$$

- $\mathbf{v} = (\mathbf{n}, c)$
- Margin of a training set  $T$ :

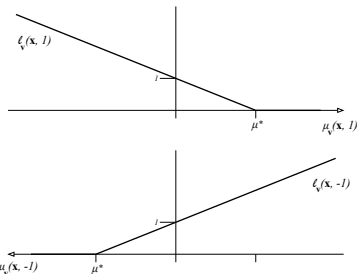
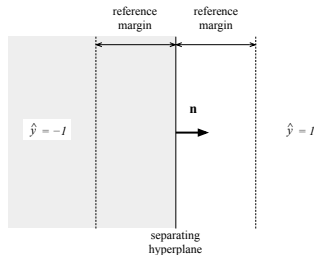
$$\mu_{\mathbf{v}}(T) \stackrel{\text{def}}{=} \min_{(\mathbf{x}, y) \in T} \mu_{\mathbf{v}}(\mathbf{x}, y)$$

- Boundary separates  $T$  if  $\mu_{\mathbf{v}}(T) > 0$



# The Hinge Loss

- *Reference margin*  $\mu^* > 0$   
(unknown, to be determined)
- *Hinge loss*  $\ell_v(\mathbf{x}, y)$ :  
$$\frac{1}{\mu^*} \max\{0, \mu^* - \mu_v(\mathbf{x}, y)\}$$
- Training samples with  $\mu_v(\mathbf{x}, y) \geq \mu^*$   
are classified correctly  
with a margin at least  $\mu^*$
- Some loss incurred as soon as  $\mu_v(\mathbf{x}, y) < \mu^*$   
*even if the sample is  
classified correctly*





# The Training Risk

- The training risk for SVMs is not just  $\frac{1}{N} \sum_{n=1}^N \ell_{\mathbf{v}}(\mathbf{x}_n, y_n)$
- A *regularization term* is added to force  $\mu^*$  to be large
- Decision boundary is  $\mathbf{n}^T \mathbf{x} + c = 0$

$$\begin{aligned}\ell_{\mathbf{v}}(\mathbf{x}, y) &= \frac{1}{\mu^*} \max\{0, \mu^* - \mu_{\mathbf{v}}(\mathbf{x}, y)\} \\ &= \frac{1}{\mu^*} \max\{0, \mu^* - y(\mathbf{n}^T \mathbf{x} + c)\} = \max\{0, 1 - y(\mathbf{w}^T \mathbf{x} + b)\} \\ &= \ell_{(\mathbf{w}, b)}(\mathbf{x}, y)\end{aligned}$$

where the decision boundary is  $\mathbf{w}^T \mathbf{x} + b = 0$

with  $\mathbf{w} = \frac{\mathbf{n}}{\mu^*}$ ,  $b = \frac{c}{\mu^*}$  and  $\|\mathbf{w}\| = \frac{1}{\mu^*}$

- Make risk higher when  $\frac{1}{\mu^*}$  is large (small margin):

$$L_T(\mathbf{w}, b) \stackrel{\text{def}}{=} \frac{1}{2} \|\mathbf{w}\|^2 + \frac{C_0}{N} \sum_{n=1}^N \ell_{(\mathbf{w}, b)}(\mathbf{x}_n, y_n)$$

# Regularized Risk

- ERM classifier:

$$(\mathbf{w}^*, b^*) = \text{ERM}_T(\mathbf{w}, b) = \arg \min_{(\mathbf{w}, b)} L_T(\mathbf{w}, b)$$

$$\text{where } L_T(\mathbf{w}, b) \stackrel{\text{def}}{=} \frac{1}{2} \|\mathbf{w}\|^2 + \frac{C_0}{N} \sum_{n=1}^N \ell_{(\mathbf{w}, b)}(\mathbf{x}_n, y_n)$$

- $\ell_{(\mathbf{w}, b)}(\mathbf{x}_n, y_n) \stackrel{\text{def}}{=} \max\{0, 1 - y_n(\mathbf{w}^T \mathbf{x}_n + b)\}$
- $C_0$  determines a trade-off
- Large  $C_0 \Rightarrow \|\mathbf{w}\|$  less important  $\Rightarrow$  smaller margin  $\mu^*$   
 $\Rightarrow$  fewer samples within the margin
- We buy a larger margin at the cost of more samples inside it
- $C_0$  is a hyper-parameter: Cross-validation!

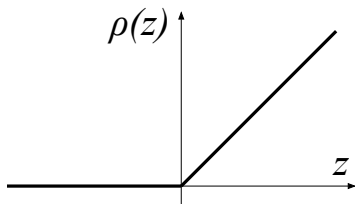
# Training an SVM

- $(\mathbf{w}^*, b^*) = \arg \min_{(\mathbf{w}, b)} L_T(\mathbf{w}, b)$  where  

$$L_T(\mathbf{w}, b) = \frac{1}{2} \|\mathbf{w}\|^2 + \frac{C_0}{N} \sum_{n=1}^N \ell_n \quad \text{and}$$

$$\ell_n = \ell_{(\mathbf{w}, b)}(\nu_n) \stackrel{\text{def}}{=} \max\{0, 1 - \underbrace{y_n(\mathbf{w}^T \mathbf{x}_n + b)}_{\nu_n}\}$$

$$= \max\{0, 1 - \nu_n\} = \rho(1 - \nu_n)$$
- $\rho(z) = \max\{0, z\}$  is the *hinge function*



- A.k.a. Rectified Linear Unit (ReLU) in deep learning



# Sub-Gradient of the Risk

- Mini-batch  $B$  of size  $M$  with  $1 \leq M \leq N$
- $(\mathbf{w}^*, b^*) = \arg \min_{(\mathbf{w}, b)} L_B(\mathbf{w}, b)$  where
 
$$L_B(\mathbf{w}, b) = \frac{1}{2} \|\mathbf{w}\|^2 + \frac{C_0}{M} \sum_{n=1}^M \rho(1 - y_n(\mathbf{w}^T \mathbf{x}_n + b))$$

$$\frac{\partial L_B}{\partial \mathbf{w}} = \mathbf{w} - \frac{C_0}{M} \sum_{n=1}^M \rho'(1 - y_n(\mathbf{w}^T \mathbf{x}_n + b)) y_n \mathbf{x}_n$$

$$\frac{\partial L_B}{\partial b} = -\frac{C_0}{M} \sum_{n=1}^M \rho'(1 - y_n(\mathbf{w}^T \mathbf{x}_n + b)) y_n .$$

- Use (stochastic) gradient descent to find  $\mathbf{w}^*, b^*$
- Recall that the risk is *convex*