

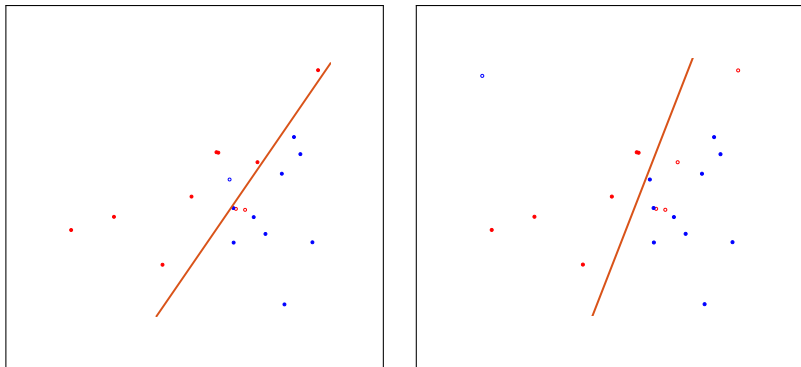
Linear, Binary SVM Classifiers

COMPSCI 371D — Machine Learning

Outline

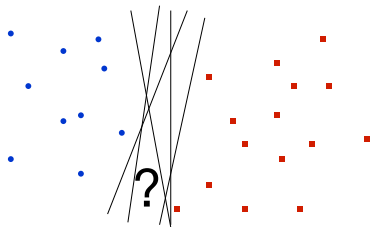
- 1 What Linear, Binary SVM Classifiers Do
- 2 Margin
- 3 Loss and Regularized Risk
- 4 Training an SVM

An Issue with the Logistic Regression Classifier



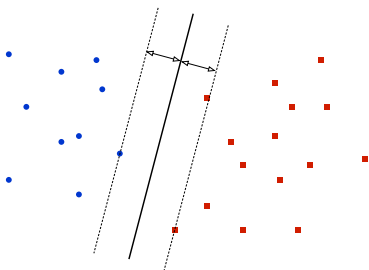
- LRC boundary depends on all the points
- The landscape near the boundary should matter most

The Separable Case



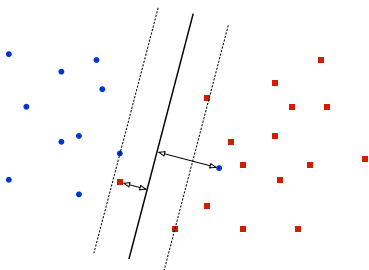
- Where to place the boundary?
- The number of degrees of freedom grows with d

SVMs Maximize the Smallest *Margin*



- Placing the boundary as far as possible from the nearest samples improves generalization
- Leave as much empty space around the boundary as possible
- Only the points that barely make the margin matter
- These are the *support vectors*
- Initially, we don't know which points will be support vectors

The General Case: Soft SVMs



- If the data is not linearly separable, there *must* be misclassified samples. These have a negative margin
- Assign a penalty that penalizes a narrow band around the boundary *and* the number of samples that fall into it or on the incorrect side of the boundary
- Give different weights to the two penalties (cross-validation!)
- Find the optimal compromise: minimum risk (total penalty)

Separating Hyperplane

- $X = \mathbb{R}^d$ and $Y = \{-1, 1\}$
(more convenient labels than $\{0, 1\}$)
- Hyperplane: $\mathbf{n}^T \mathbf{x} + c = 0$ with $\|\mathbf{n}\| = 1$
- Decision rule: $\hat{y} = h(\mathbf{x}) = \text{sign}(\mathbf{n}^T \mathbf{x} + c)$
- $\mathbf{n}$ points towards the $\hat{y} = 1$ half-space
- If y is the true label, decision is correct if
$$\begin{cases} \mathbf{n}^T \mathbf{x} + c \geq 0 & \text{if } y = 1 \\ \mathbf{n}^T \mathbf{x} + c \leq 0 & \text{if } y = -1 \end{cases}$$
- More compactly,
decision is correct if $y(\mathbf{n}^T \mathbf{x} + c) \geq 0$
- SVMs want this inequality to hold with a *margin*

Margin

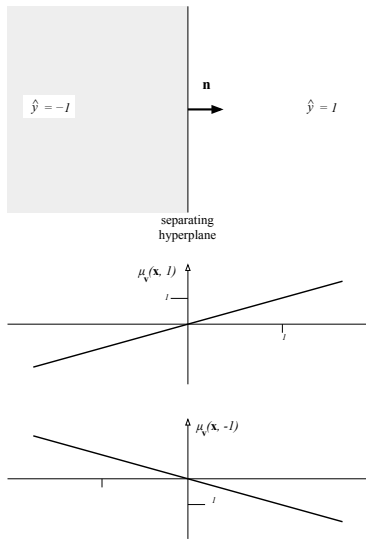
- The margin of $(\mathbf{x}, y)$ is the signed distance of $\mathbf{x}$ from the boundary: Positive if $\mathbf{x}$ is on the correct side of the boundary, negative otherwise

$$\mu_{\mathbf{v}}(\mathbf{x}, y) \stackrel{\text{def}}{=} y(\mathbf{n}^T \mathbf{x} + c)$$

- $\mathbf{v} = (\mathbf{n}, c)$
- Margin of a training set T :

$$\mu_{\mathbf{v}}(T) \stackrel{\text{def}}{=} \min_{(\mathbf{x}, y) \in T} \mu_{\mathbf{v}}(\mathbf{x}, y)$$

- Boundary separates T if $\mu_{\mathbf{v}}(T) > 0$



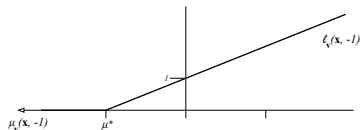
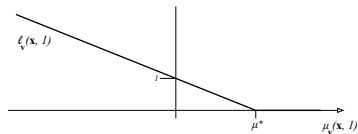
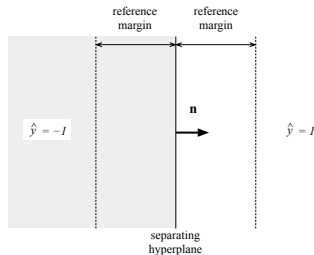
The Hinge Loss

- *Reference margin* $\mu^* > 0$
(unknown, to be determined)
- *Hinge loss* $\ell_v(\mathbf{x}, y)$:

$$\frac{1}{\mu^*} \max\{0, \mu^* - \mu_v(\mathbf{x}, y)\}$$
- Training samples with

$$\mu_v(\mathbf{x}, y) \geq \mu^*$$
are classified correctly
with a margin at least μ^*
- Some loss incurred as soon as

$$\mu_v(\mathbf{x}, y) < \mu^*$$
even if the sample is classified correctly



The Training Risk

- The training risk for SVMs is not just $\frac{1}{N} \sum_{n=1}^N \ell_{\mathbf{v}}(\mathbf{x}_n, y_n)$
- A *regularization term* is added to force μ^* to be large
- Decision boundary is $\mathbf{n}^T \mathbf{x} + c = 0$

$$\begin{aligned} \ell_{\mathbf{v}}(\mathbf{x}, y) &= \frac{1}{\mu^*} \max\{0, \mu^* - \mu_{\mathbf{v}}(\mathbf{x}, y)\} \\ &= \frac{1}{\mu^*} \max\{0, \mu^* - y(\mathbf{n}^T \mathbf{x} + c)\} = \max\{0, 1 - y(\mathbf{w}^T \mathbf{x} + b)\} \\ &= \ell_{(\mathbf{w}, b)}(\mathbf{x}, y) \end{aligned}$$

where the decision boundary is $\mathbf{w}^T \mathbf{x} + b = 0$

with $\mathbf{w} = \frac{\mathbf{n}}{\mu^*}$, $b = \frac{c}{\mu^*}$ and $\|\mathbf{w}\| = \frac{1}{\mu^*}$

- Make risk higher when $\frac{1}{\mu^*}$ is large (small margin):

$$L_T(\mathbf{w}, b) \stackrel{\text{def}}{=} \frac{1}{2} \|\mathbf{w}\|^2 + \frac{C_0}{N} \sum_{n=1}^N \ell_{(\mathbf{w}, b)}(\mathbf{x}_n, y_n)$$

Regularized Risk

- ERM classifier:

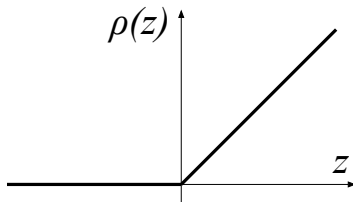
$$(\mathbf{w}^*, b^*) = \text{ERM}_T(\mathbf{w}, b) = \arg \min_{(\mathbf{w}, b)} L_T(\mathbf{w}, b)$$

$$\text{where } L_T(\mathbf{w}, b) \stackrel{\text{def}}{=} \frac{1}{2} \|\mathbf{w}\|^2 + \frac{C_0}{N} \sum_{n=1}^N \ell_{(\mathbf{w}, b)}(\mathbf{x}_n, y_n)$$

- $\ell_{(\mathbf{w}, b)}(\mathbf{x}_n, y_n) \stackrel{\text{def}}{=} \max\{0, 1 - y_n(\mathbf{w}^T \mathbf{x}_n + b)\}$
- C_0 determines a trade-off
- C_0 is a hyper-parameter: Cross-validation!
- Large $C_0 \Rightarrow \|\mathbf{w}\|$ less important $\Rightarrow$ smaller margin μ^*
 $\Rightarrow$ fewer samples within the margin
- We buy a larger margin at the cost of more samples inside it

Training an SVM

- $(\mathbf{w}^*, b^*) = \arg \min_{(\mathbf{w}, b)} L_T(\mathbf{w}, b)$ where
 $L_T(\mathbf{w}, b) = \frac{1}{2} \|\mathbf{w}\|^2 + \frac{C_0}{N} \sum_{n=1}^N \ell_n$ and
 $\ell_n = \ell_{(\mathbf{w}, b)}(\nu_n) \stackrel{\text{def}}{=} \max\{0, 1 - \underbrace{y_n(\mathbf{w}^T \mathbf{x}_n + b)}_{\nu_n}\}$
 $= \max\{0, 1 - \nu_n\} = \rho(\overbrace{1 - \nu_n}^z)$
- $\rho(z) = \max\{0, z\}$ is the *hinge function*



- A.k.a. Rectified Linear Unit (ReLU) in deep learning

Sub-Gradient of the Risk

- SGD: Mini-batch B of size M with $1 \leq M \leq N$
- $(\mathbf{w}^*, b^*) = \arg \min_{(\mathbf{w}, b)} L_B(\mathbf{w}, b)$ where

$$L_B(\mathbf{w}, b) = \frac{1}{2} \|\mathbf{w}\|^2 + \frac{C_0}{M} \sum_{n=1}^M \rho(1 - y_n(\mathbf{w}^T \mathbf{x}_n + b))$$

$$\frac{\partial L_B}{\partial \mathbf{w}} = \mathbf{w} - \frac{C_0}{M} \sum_{n=1}^M \rho'(1 - y_n(\mathbf{w}^T \mathbf{x}_n + b)) y_n \mathbf{x}_n$$

$$\frac{\partial L_B}{\partial b} = -\frac{C_0}{M} \sum_{n=1}^M \rho'(1 - y_n(\mathbf{w}^T \mathbf{x}_n + b)) y_n .$$

- Use (stochastic) gradient descent to find $\mathbf{w}^*, b^*$
- Recall that the risk is *convex*