







## Wisdom

Do s

- Reserve using alerts for when you don't know what is going on
- Only use if you forked the thread
- Impose an ordering on lock acquisition
- Write down invariants that should be true when locks aren't being held
- Worry about correctness first before performance

Don't s

- Call into a different abstraction level while holding a lock
- Move the "last" signal beyond scope of Lock
- Acquire lock, fork, and let child release lock
- Expect priority inheritance since few implementations
- Pack data and expect fine grain locking to work



## Practice: Klingon Problem

The Klingons are attacking. The Federation vessels can escape through the wormhole, but sensors indicate that the wormhole is unstable. The ships' captains plan to create a subspace distortion to prevent the wormhole from closing on them while they are in it. To do this, they will enter the wormhole three at a time while emitting a tachyon pulse through their main deflector dishes. Each ship must lower its shields before initiating its tachyon pulse, and once a ship starts emitting tachyons it can have no contact with the other ships.

Implement a synchronization scheme to allow the Federation to retreat through the wormhole in an orderly fashion. Your scheme should have the property that no ship lowers its shields until just before it enters the wormhole, no ship enters the wormhole until two others are ready to go in with it, and all ships in each group of three enter the wormhole before any of the ships in the next group.

## Practice: Fine grain locking Multiple threads inserting and deleting in a linked list

## Practice: Bridge Problem

Synchronize traffic over a narrow light-duty bridge on a public highway. Traffic may only cross the bridge in one direction at a time, and if there are ever more than 3 vehicles on the bridge at one time, it will collapse under their weight. Each car is to be represented by one thread, which executes the procedure OneVehicle in order to cross the bridge:

OneVehicle(int direc) //direc is either 0 or 1; //giving the direction in which the car is to cross

{ ArriveBridge(direc); CrossBridge(direc); ExitBridge(direc);

}