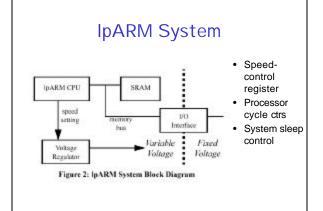
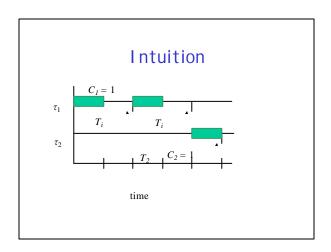


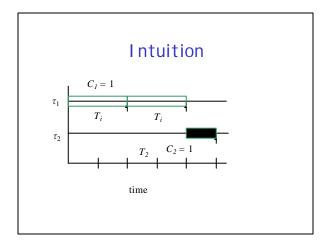
- Simulation study IpARM
- 1.1V to 3.3V 10 MHz to 100 MHz
- Core and cache together consume between 1.8 mW and 220 mW
- Voltage scheduler separate from "temporal" scheduler
- · Use "deadlines"

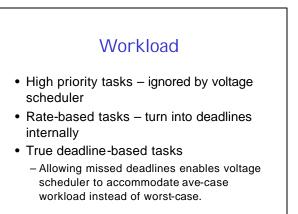


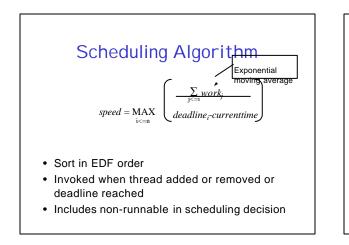
Based on Earliest Deadline First

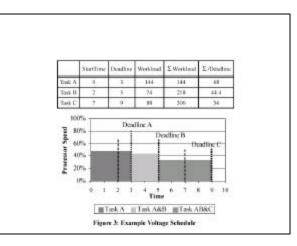
- Dynamic algorithm
- Priorities are assigned to tasks according to the deadlines of their current request
- With EDF there is no idle time prior to an overflow
- For a given set of *m* tasks, EDF is feasible iff $C_1/T_1 + C_2/T_2 + ... + C_m/T_m \le 1$
- If a set of tasks can be scheduled by any algorithm, it can be scheduled by EDF

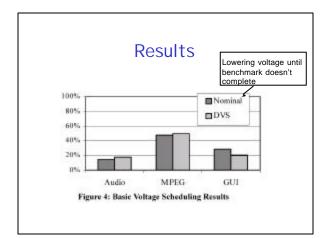


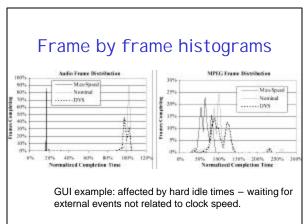


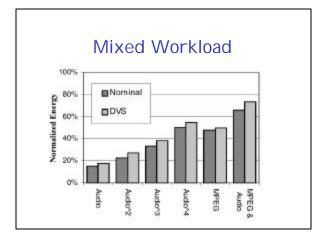












Conclusions

- In all cases, less than 2% of energy going to scheduling thread execution
- Up to 80% reduction in energy
- Application information required

Multiprocessor Affinity Scheduling

- Question: Where (on which node) to run a particular thread during the next time slice?
- Processor's POV: favor processes which have some residual state locally (e.g. cache)
- What is a useful measure of affinity for deciding this?
 - Least intervening time or intervening activity (number of processes here since "my" last time) *
 - Same place as last time "I" ran.
 - Possible negative effect on load-balance.

Affinity Analogies?