Entity Resolution: Blocking

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Recap: Entity Resolution

Problem of identifying and linking/grouping different manifestations of the same real world object.

Examples of manifestations and objects:

- Different ways of addressing (names, email addresses, FaceBook accounts) the same person in text.
- Web pages with differing descriptions of the same business.
- Different photos of the same object.

• ...



Recap: Fellegi & Sunter Model [FS, Science '69]

• r = (x,y) is record pair, γ is comparison vector, M matches, U nonmatches

• Decision rule
$$R = \frac{P(\gamma \mid r \in M)}{P(\gamma \mid r \in U)}$$

$$R \ge t_l \Rightarrow r \rightarrow \text{Match}$$
 $t_l < R < t_u \Rightarrow r \rightarrow \text{Potential Match}$
 $R \le t_u \Rightarrow r \rightarrow \text{Non - Match}$

• Naïve Bayes Assumption: $P(\gamma \mid r \in M) = \prod_{i} P(\gamma_i \mid r \in M)$



Outline

- Algorithms for Single Entity ER
 - Computing Pairwise Match scores
 - Blocking: Efficiently Identifying of Near-Duplicates
 - Correlation Clustering: Enforcing Transitivity Constraints
- Algorithms for Relational & Multi-Entity ER



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SCALING ENTITY RESOLUTION



Outline

- Definition of Blocking
- Hash-based Blocking
 - Boolean functions over attributes
 - minHash: Locality Sensitive Hashing
- Neighborhood-based Blocking
 - Merge/Purge
 - Canopy Clustering



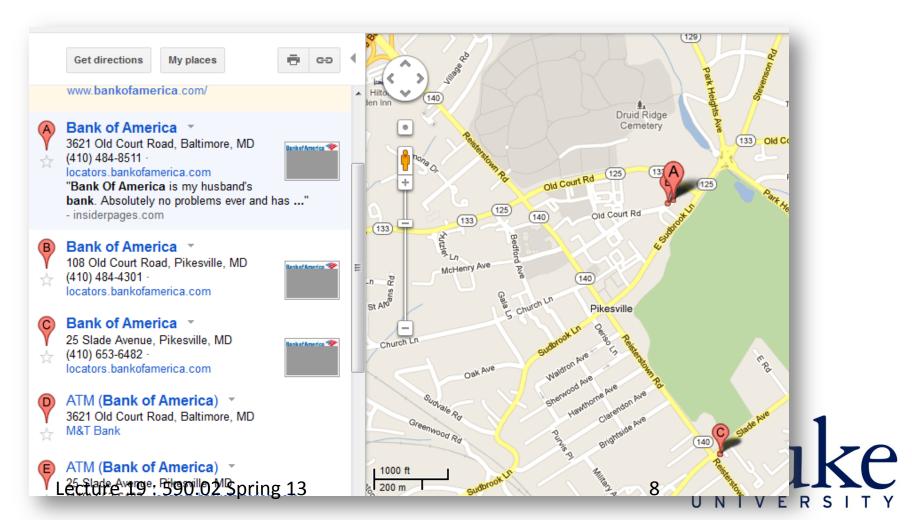
Blocking: Motivation

- Naïve pairwise: $|R|^2$ pairwise comparisons
 - 1000 business listings each from 1,000 different cities across the world
 - 1 trillion comparisons
 - 11.6 days (if each comparison is 1 μs)
- Mentions from different cities are unlikely to be matches
 - Blocking Criterion: City
 - 1 billion comparisons
 - 16 minutes (if each comparison is $1 \mu s$)

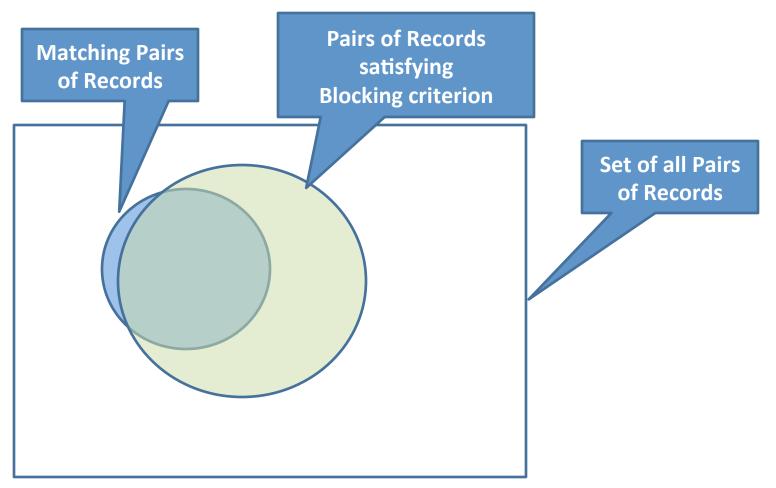


Blocking: Motivation

- Mentions from different cities are unlikely to be matches
 - May miss potential matches



Blocking: Motivation





Input: Set of records *R*

Output: Set of blocks/canopies

$$\{C_1, C_2, ..., C_k\}$$
, where $\forall_i C_i \subset R$ and $\bigcup_i C_i = R$

Intuition:

- Only compare pairs of records that appear within each block / canopy
- Use a simple function (approximate distance) to generate canopies.



$$\{C_1, C_2, ..., C_k\}$$
, where $\forall_i C_i \subset R$ and $\bigcup_i C_i = R$

Metrics:

• Efficiency (or reduction ratio):

number of pairs compared total number of pairs in $R \times R$

$$= \frac{|\{(x,y) \mid \exists i \ C_i, s.t. \ x,y \in C_i\}|}{r(r-1)/2}$$

Recall* (or pairs completeness):

number of true matches compared number of true matches in $R \times R$

*Need to know ground truth in order to compute this metri



Metrics:

- Efficiency (or reduction ratio):
- number of pairs compared total number of pairs in $R \times R$
- Recall* (or pairs completeness):
 - number of true matches compared number of true matches in $R \times R$
- Precision* (or pairs quality):
- number of true matches compared number of matches compared

Max Canopy Size:

 $max_i |C_i|$

*Need to know ground truth in order to compute this metr



Input: Set of records *R*

Output: Set of blocks/canopies

$$\{C_1, C_2, ..., C_k\}$$
, where $\forall_i C_i \subset R$ and $\bigcup_i C_i = R$

Variants:

Disjoint Blocking: Each record appears in one block.

$$\forall_{i,j} C_i \cap C_j = \emptyset$$

 Non-disjoint Blocking: Records can appear in more than one block.

Tradeoff recall for computation.



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Blocking Algorithms 1

- Hash based blocking
 - Each block C_i is associated with a hash key h_i .
 - Record x is hashed to C_i if $hash(x) = h_i$.
 - Each hash function results in disjoint blocks.
 - Easy parallel (MapReduce) implementation.



Hash-based Blocking

- What is a hash function?
 - Deterministic function of attribute values
 - Boolean Functions over attribute values
 [Bilenko et al ICDM'06, Michelson et al AAAI'06,
 Das Sarma et al CIKM '12]
 - minHash (min-wise independent permutations)
 [Broder et al STOC'98]



Blocking Algorithms 1

Hash based blocking

- Each block C_i is associated with a hash key h_i .
- Record x is hashed to C_i if $hash(x) = h_i$.
- Each hash function results in disjoint blocks.
- Easy parallel (MapReduce) implementation.

Non-disjoint variant:

- Each block is associated with a set of K hash keys.
- Each record x is hashed using N hash functions.
- Two records are in the same block if they share K out of N hash keys.
- MapReduce implementation?



Simple Blocking: Inverted Index on a Key

Examples of blocking keys:

- First three characters of last name
- City + State + Zip
- Character or Token n-grams
- Minimum infrequent n-grams



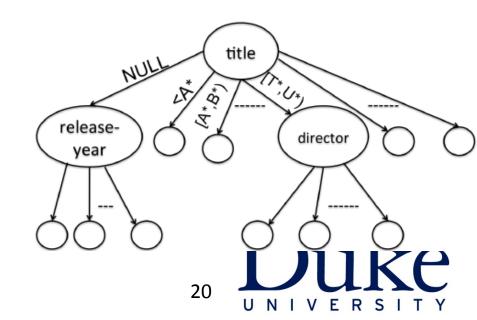
Learning Optimal Blocking Functions

- Using one or more blocking keys may be insufficient
 - 2,376,206 American's shared the surname Smith in the 2000 US
 - NULL values may create large blocks.
- Solution: Construct blocking functions by combining simple functions



Complex Blocking Functions

- Conjunction of functions
 - {City} AND {last four digits of phone}
- Chain-trees
 If ({City} = NULL or LA) then {last four digits of phone} AND {area code}
 else {last four digits of phone} AND {City}
- BlkTrees



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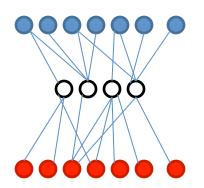
Learning an Optimal function [Bilenko et al ICDM '06]

- Find k blocking functions that eliminate the most non-matches, while retaining almost all matches.
 - Need a training set of positive and negative pairs
- Algorithm Idea: Red-Blue Set Cover

Positive Examples

Blocking Keys

Negative Examples



Pick k Blocking keys such that

- (a) At most ε blue nodes are not covered
- (b) Number of red nodes covered is minimized



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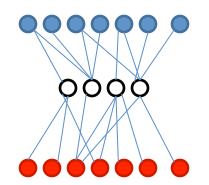
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Algorithm Idea: Red-Blue Set Cover

Positive Examples

Blocking Keys

Negative Examples



Pick k Blocking keys such that

- (a) At most ε blue nodes are not covered
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- Greedy Algorithm:
 - Construct "good" conjunctions of blocking keys $\{p_1, p_2, ...\}$.
 - Pick k conjunctions $\{p_{i1}, p_{i2}, ..., p_{ik}\}$, such that the following is minimized

number of new blue nodes covered by p_{i_j}

number of red nodes covered by p_{i_i}



minHash (Minwise Independent Permutations)

- Let F_x be a set of features for mention x
 - (functions of) attribute values
 - character ngrams
 - optimal blocking functions ...
- Let π be a random permutation of features in F_{x}
 - E.g., order imposed by a random hash function
- minHash(x) = minimum element in F_x according to π



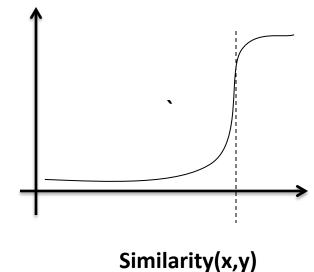
Why minHash works?

Surprising property: For a random permutation π ,

$$P(minHash(x) = minhash(y)) = \frac{F_x \cap F_y}{F_x \cup F_y}$$

How to build a blocking scheme such that only pairs with Jacquard similarity > s fall in the same block (with high prob)?

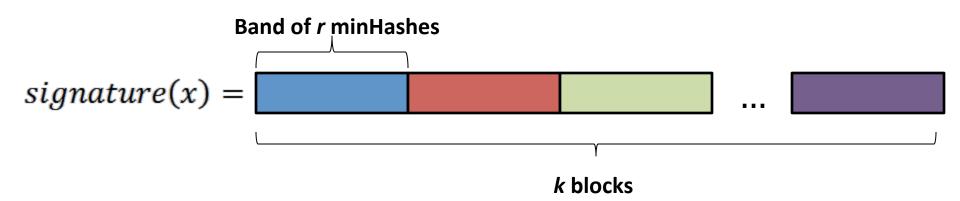
Probability that (x,y) mentions are blocked together



Duke

Blocking using minHashes

• Compute minHashes using r * k permutations (hash functions)



Signature's that match on 1 out of k bands, go to the same block.



minHash Analysis

False Negatives: (missing matches)

P(pair x,y not in the same block with Jacquard sim = s) = $(1 - s^r)^k$

should be very low for high similarity pairs

False Positives: (blocking non-matches)

P(pair x,y in the same block with Jacquard sim = s) = $k \times s^r$

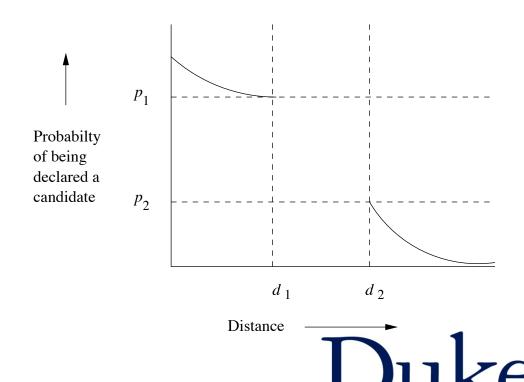
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r	_	J,	ĸ	_	Z	U

10 ⁻⁸
0.00035
0.025
0.2
0.52
0.81
0.95
0.994
0.9998

Locality Sensitive Hashing Functions

Let d1 and d2 be two distances. A family of functions **F** is said to be (d1, d2, p1, p2)-sensitive if for all f in **F**,

- If d(x,y) < d1,
 then P[f(x) = f(y)] > p1
- If d(x,y) > d2,
 then P[f(x) = f(y)] < p2



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Locality sensitive family for Jaccard distance

 minHash is one example of locality sensitive family that can strongly distinguish pairs that are close from pairs that are far.

 The family of minHash functions is a (d1, d2, 1-d1, 1-d2)-sensitive family for any d1, d2.



Amplifying a Locality-sensitive family

AND construction:

- Construct a new family F' consisting of r members of F
- f in F' = {f1, f2, ..., fr}
- f(x) = f(y) iff for all i, fi(x) = fi(y)
- If F is (d1, d2, p1, p2)-sensitive, then F' is (d1, d2, p1^r, p2^r)-sensitive

OR construction:

- Construct a new family F' consisting of b members of F
- f in F' = {f1, f2, ..., fb}
- f(x) = f(y) iff there exists i, fi(x) = fi(y)
- If F is (d1, d2, p1, p2)-sensitive,
 then F' is (d1, d2, 1-(1-p1)^b, 1-(1-p2)^b)-sensitive



Example

- Suppose F is (0.2, 0.6, 0.8, 0.4)-sensitive.
- We use AND-construction with r= 4 to create F1
- We use OR-construction with b=4 to create F2
- F2 is $(0.2, 0.6, 1-(1-0.8^4)^4, 1-(1-0.4^4)^4)$ = (0.2, 0.6, 0.875, 0.0985)-sensitive



LSH for Hamming distance

- Given two vectors x, y
- Hamming distance h(x,y) = number of positions where x and y are different

minHash: (d1, d2, 1-d1/d, 1-d2/d)-sensitive



LSH for Cosine Distance

Cosine Distance: angle between two vectors

- Locality sensitive function F:
 Pick a random vector vf.
 f(x) = f(y) is x.vf and y.vf have the same sign.
- **F** is (d1, d2, (180-d1)/180, d2/180)-sensitive
- Another method:
 Generate v in {-1, +1}^d (d is the dimensionality of x)
 f(x) = f(y) is x.vf and y.vf have the same sign.



Summary of Hash-based Blocking

- Complex boolean functions can be built to optimize recall using a training set of matches and non-matches
- Locality sensitive hashing functions can strongly distinguish pairs that are close from pairs that are far.
- AND and OR construction help amplify the distinguishing capability of locality sensitive functions.



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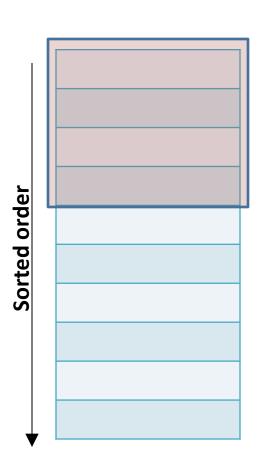
Blocking Algorithms 2

- Pairwise Similarity/Neighborhood based blocking
 - Nearby nodes according to a similarity metric are clustered together
 - Results in non-disjoint canopies.
- Techniques
 - Sorted Neighborhood Approach [Hernandez et al SIGMOD'95]
 - Canopy Clustering [McCallum et al KDD'00]



Sorted Neighborhood [Hernandez et al SIGMOD'95]

- Compute a **Key** for each record.
- Sort the records based on the key.
- Merge: Check whether a record matches with (w-1) previous records.
 - Implementation?
- Perform multiple passes with different keys



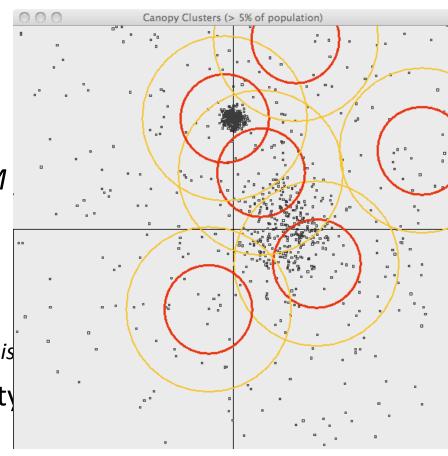


Canopy Clustering [McCallum et al KDD'00]

Input: Mentions M, d(x,y), a distance metric, thresholds $T_1 > T_2$

Algorithm:

- Pick a random element x from M
- 2. Create new canopy C_x using mentions y s.t. $d(x,y) < T_1$
- 3. Delete all mentions y from Ms.t. $d(x,y) < T_2$ (from consideration in this
- 4. Return to Step 1 if *M* is not empty





Summary of Blocking

- $O(|R|^2)$ pairwise computations can be prohibitive.
 - Blocking eliminates comparisons on a large fraction of non-matches.
- Hash-based Blocking:
 - Construct (one or more) hash keys from features
 - Records not matching on any key are not compared.
- Neighbohood based Blocking:
 - Form overlapping canopies of records based on similarity.
 - Only compare records within a cluster.

