

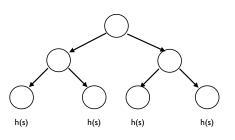
# Informed Search Key thing in search is managing the frontier. Solution So

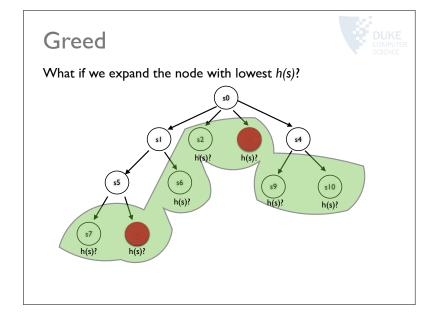
### Heuristics



Key idea: heuristic function.

- h(s) estimates cost-to-go
- · Cost to go from state to solution.
- · Problem specific.





# $A^*$

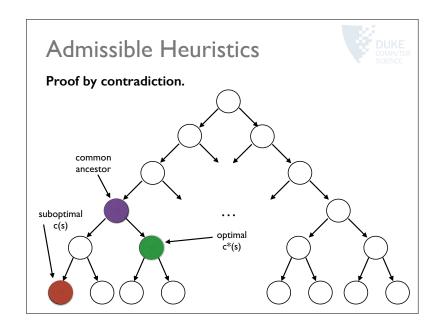


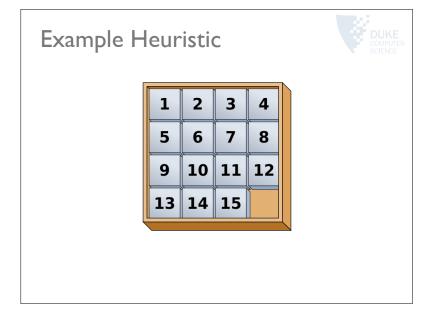
### A\* algorithm:

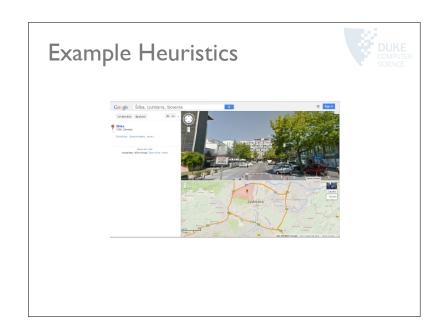
- Also g(s) cost so far (start to s).
- Expand s that minimizes g(s) + h(s)
- Manage frontier as priority queue.
- Admissible heuristic: never overestimates cost.

$$h(s) \le h^*(s)$$

- h(s) = 0 if s is a goal state, so g(s) + h(s) = c(s)
- If h is admissible, A\* is optimal.
- If h(s) is exact, runs in O(bd) time.







## More on Heuristics



Heuristic hI dominates h2 if hI(s) >= h2(s) for all s.

• Is hI or h2 better? (If they're both admissible.)

How might you combine two heuristics?

What is h(s) = k (constant) for all s?

# More on Heuristics



 $A^*$  is optimally efficient: any algorithm using h must expand the nodes  $A^*$  expands.

Why?

# More on Heuristics



### Ideal heuristics:

- Fast to compute.
- · Close to real costs.
- Some programs automatically generate heuristics.