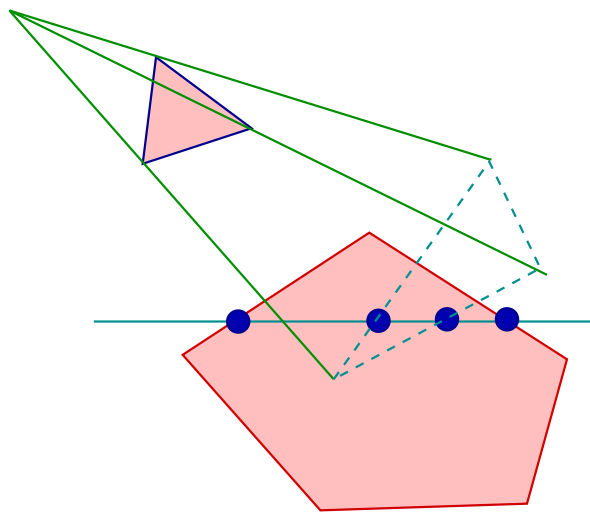


Shadow Generation

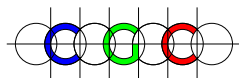
$$I_\lambda = k_a I_{a\lambda} O_{a\lambda} + \sum_{i=1}^k S_i f_{att} I_{L_i\lambda} [k_d O_{d\lambda} (\mathbf{N} \cdot \mathbf{L}_i) + k_s (\mathbf{R} \cdot \mathbf{V})^n]$$

$$S_i = \begin{cases} 0 & \text{if light } i \text{ is blocked,} \\ 1 & \text{if light } i \text{ is not blocked.} \end{cases}$$



Scan-line method

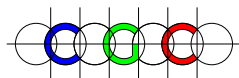
- ★ Use light source as the center of projection.
- ★ Project the edges of polygons that cast shadows on the polygons intersecting the scan line.
- ★ Whenever the scan line visits one of the projected points, change the intensity.



Shadow Generation

Two-Pass Object Precision Algorithm:

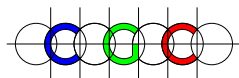
- ★ Find the portion of each polygon visible from the light source.
- ★ Decompose each polygon into subpolygons, each being either completely lit or completely under dark.
- ★ Render each polygon as follows:
 - If the polygon is in dark, set intensity to the ambient light
$$I_{\lambda} = k_a I_{a\lambda} O_{a\lambda}.$$
 - If the polygon is lit, then use ambient, diffuse, and specular reflection.
- ★ Repeat the first two steps for each light source.



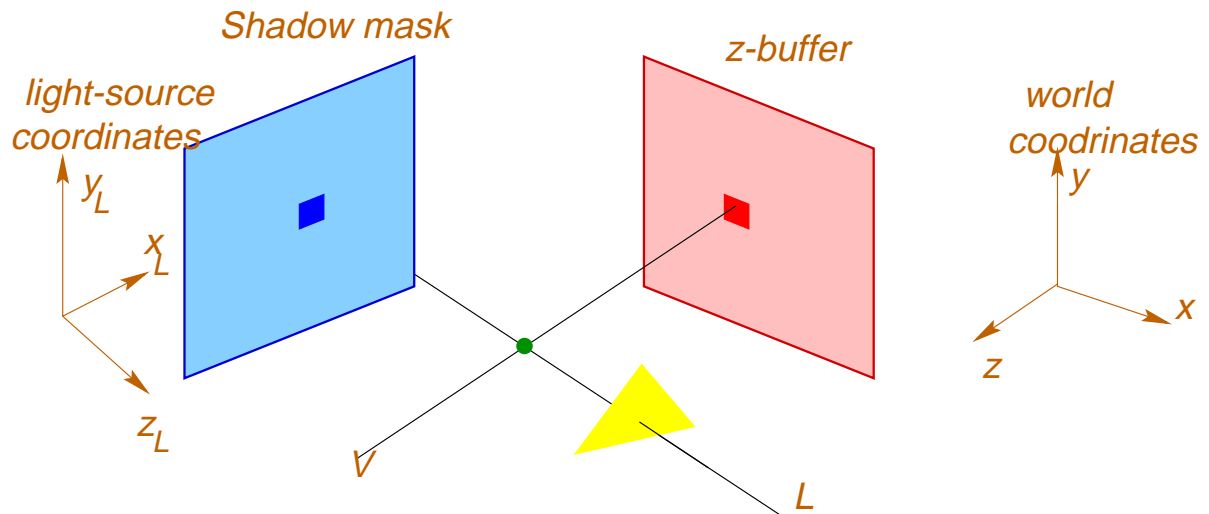
Shadow Generation

Two-Pass Z-Buffer Algorithm:

- ★ Two passes
 - W.r.t light source
 - W.r.t. view point
- ★ Compute depth information w.r.t. the light source.
light buffer (LB) or *shadow mask*
- ★ Compute the value of the frame buffer at each pixel π w.r.t. the viewpoint as follows:
 - Suppose the point p in the world coordinate is drawn at pixel π .
 - Determine if p is under shadow.
 - If under shadow, use ambient light.
Otherwise compute the lighting information at π .
- ★ For multiple light sources, maintain a shadow mask for each light source.



Shadow Generation



- ★ Compute the pixel (a, b) in the shadow mask corresponding to point p .
- ★ Compute the distance c of p from the light source.
- ★ Compare c with $z_L = LB[a, b]$.
- ★ If $z_L < c$, p is under shadow; otherwise p is lit.

