## Lecture 5: Dynamic Programming II

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# 1 Designing a DP for Longest Increasing Subsequence (LIS)

Given a sequence of numbers, we want to find a strictly increasing *subsequence* of it that is also the longest. The numbers in the subsequence may not be consecutive in the original sequence. For example, given sequence  $a[\ ] = \{4,2,5,3,9,7,8,10,6\}$ , its LIS is  $\{2,5,7,8,10\}$  or  $\{2,3,7,8,10\}$ , as they both have length 5.

### 1.1 A Failed Attempt

A natural subproblem is to have f[i] denote the length of the LIS of sequence  $a[1 \dots i]$ . A natural transition funtion is to consider whether the LIS of  $a[1 \dots i]$  should include a[i] or not, and take max of the two.

If a[i] is not included, then simply f[i] = f[i-1]. If a[i] is included, however, we run into a problem: when the last element a[i] is in the sequence, we have the additional constraint that all other elements need to be smaller than a[i]. However, when we reference a previous subproblem f[j] where j < i, we do not know whether the solution for f[j] uses numbers strictly smaller than a[i], hence our proposed transition function does not work.

#### 1.2 Attempt 2

Consider the following subproblem definition: Let f[i] denote the length of the LIS of sequence a[1...i] that ends at a[i]. (i.e. the subsequence must include a[i])

The decision at f[i] is immediate, as we *have* to pick a[i] by definition. To compute f[i], we can enumerate the number that is before a[i] in the sequence. This motivates our transition function:

$$f[i] = \max\{1, \max_{j < i, a[i] < a[i]} f[j] + 1\}$$

If the max evaluates to the first case then the subsequence is simply  $\{a[i]\}$ ; if it evaluates to the second case then the subsequence is  $\{LIS \text{ ending at } a[j], a[i]\}$ .

For example, for the sequence mentioned above, we would fill out a DP table like below

To complete our algorithm, we also need a base case that is f[0] = 0, and an output that is  $\max_{1 \le i \le n} f[i]$ .

#### 1.2.1 Analyze Running Time

The running time of a DP, in general, is

# states × time for evaluating one transition function

In the DP above, there are n states, and we take O(n) to evaluate one transition function. Hence the total running time is  $O(n^2)$ 

#### 1.2.2 Proof of Correctness

We will use induction to prove that our DP computes the correct answer. Our inductive hypothesis, in general, is to assume that "smaller subproblems are computed correctly."

- Base case: f[0] = 0 is true by definition.
- Inductive hypothesis: assume that for every j < i, f[j] is indeed the length of the LIS ending at a[j].
- Induction step: Let  $b[\ ]$  denote the LIS ending at a[i].  $b[\ ]$  is either of length 1 or of length greater than 1.
  - If b[] is of length 1, then it is considered by the first case of the transition function.
  - If b[] is of length greater than 1, let a[j] denote the second-to-last number in b[]. By definition j < i and a[j] < a[i]. By IH, f[j] is computed correctly. Hence f[i] = f[j] + 1 is considered by the second case of the transition function.

Therefore, f[i] is also computed correctly.

• By induction, f[i] is computed correctly for all  $i \ge 0$ .